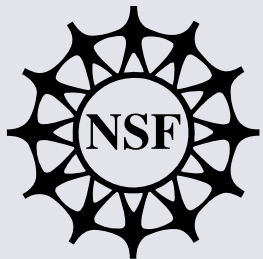
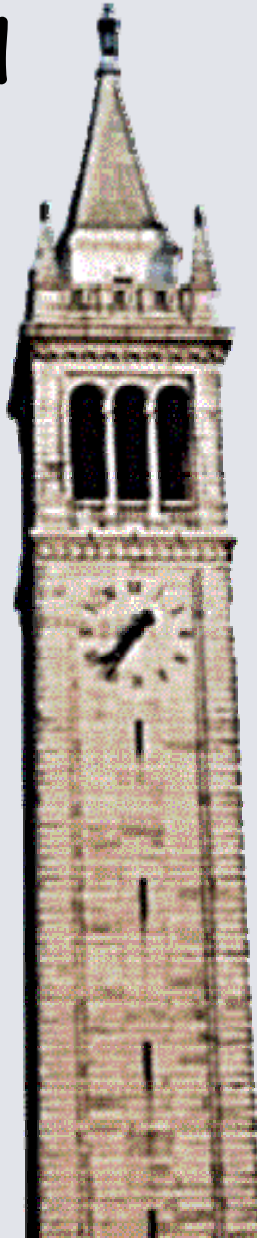


Efficient Simulation Model for Hybrid Bond Graphs

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Chess Review
November 21, 2005
Berkeley, CA





- *Simulation of hybrid systems must combine two models of computation*
- Hybrid Bond Graphs (HBGs) combine
 - Continuous bond graph (BG) models with
 - Switching junctions controlled by FSMto provide a topological framework that supports run-time model reconfiguration
- However, no computational model associated with HBGs

Question: How does one systematically derive simulation models from HBGs?

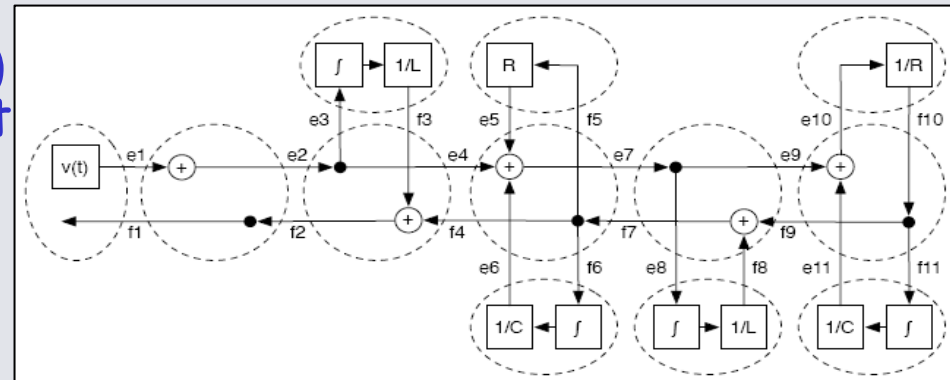
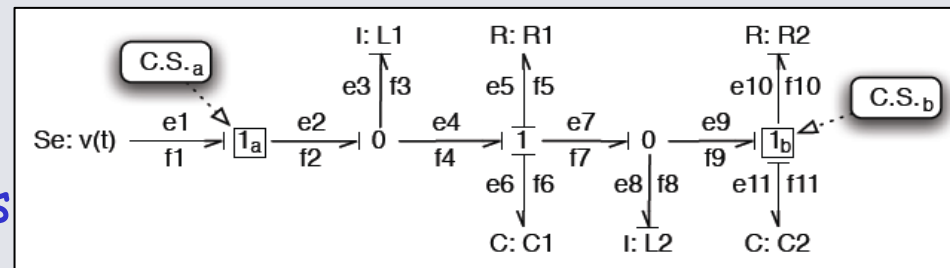
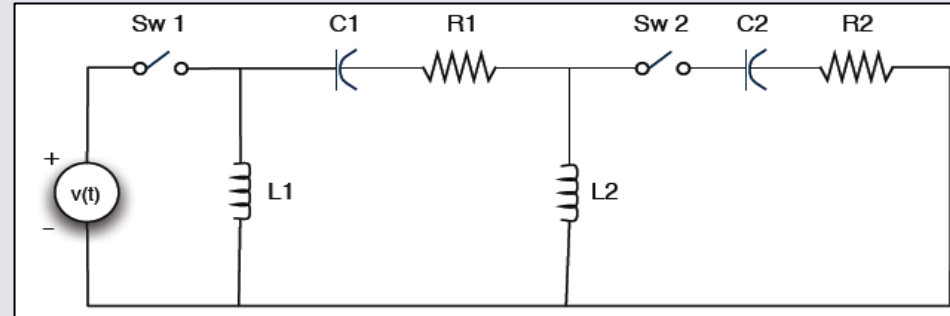
- Approach: Use causal structure implied by BG to derive block diagram models for simulation (SCAP algorithm)



HBG Overview



- BG to Block Diagram Computational Model
 - Constituent element blocks + algebraic relations at junctions
- Determining Bond (DB)
 - One per junction, derived from causality at junction
 - Determines algebraic relations
- HBG Complexities
 - Junction switches (on and off) may cause causality changes at runtime, thus block diagram may change
 - Only changes in DBs will change algebraic relations at junction
 - These changes can propagate

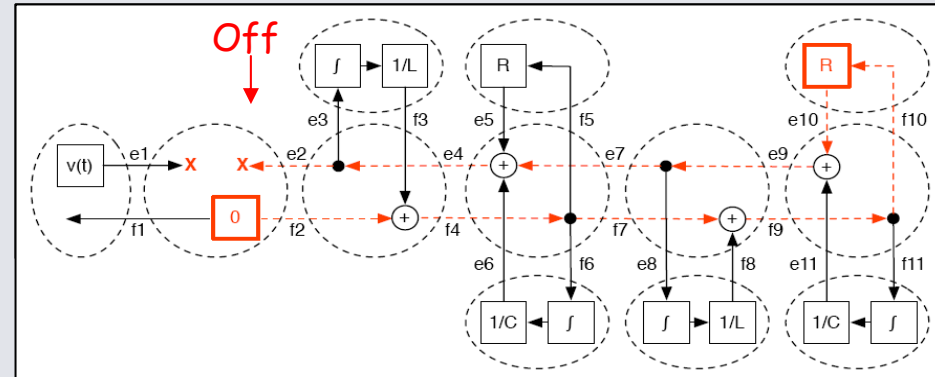


Approaches

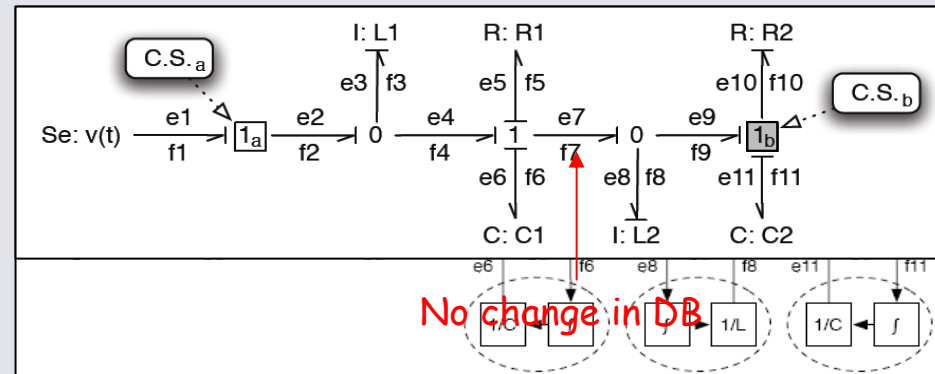


- Pre-generate block diagrams for all modes
 - 2^n possible configurations
- Generate block diagrams from scratch after every mode change
 - Can be computationally expensive at switches
- Smarter approach: derive new block diagram incrementally from old
 - Start with block diagram in initial mode
 - Look for changes in DBs
 - Update block diagram at changes

Junction 1a off, junction 1b on:



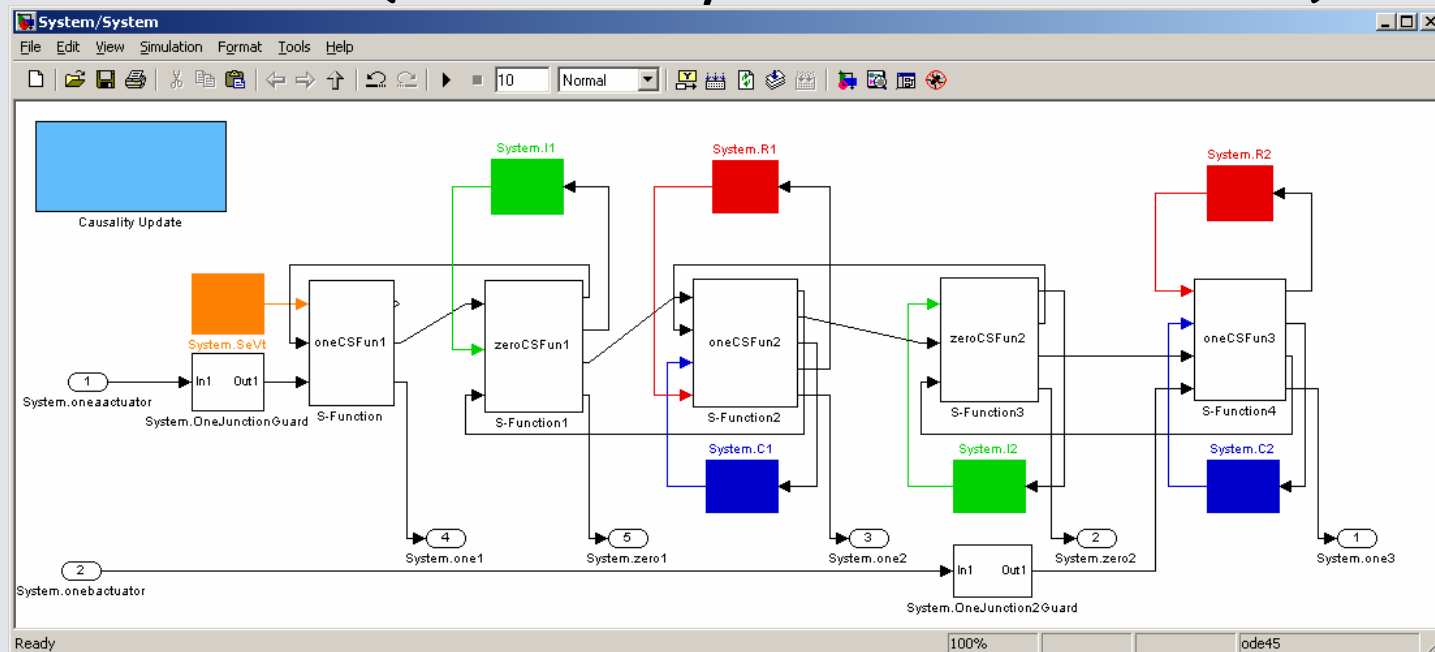
Junction 1a on, junction 1b off:



Efficient Simulation Model



- Causality update triggered by change in discrete state
 - Start at junctions which switch
 - If they cause changes in adjacent junction DBs then
 - update DB's algebraic constraints
 - Continue till no DB change or all junctions visited
- For efficiency, junctions implemented as S-functions; use global variables (cf. Ptolemy's director function)



Questions?

