

# Applications of Petri Nets

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2010.10.28

# Outline

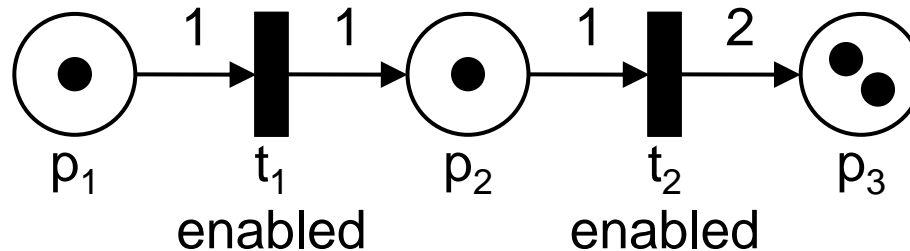
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- Revisiting Petri Nets
- Application 1: Software Syntheses
  - Theory and Algorithm
- Application 2: Biological Networks
  - Comprehensive Introduction
- Application 3: Supply Chains
  - Example and Experiment
- Summary

# Definition of a Petri Net

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- A 3-tuple  $(P, T, F)$ 
  - $P$ : set of **places**
  - $T$ : set of **transitions**
  - $F: (P \times T) \cup (T \times P) \rightarrow \mathbb{N}$ , weighted flow relation



- How does it work?
  - Each place holds some ( $\geq 0$ ) **tokens**
  - A transition is **enabled** if its input places contain at least the required # of tokens
  - The **firing** of an enabled transition results in
    - Consumption of the tokens of its input places
    - Production of the tokens of its output places

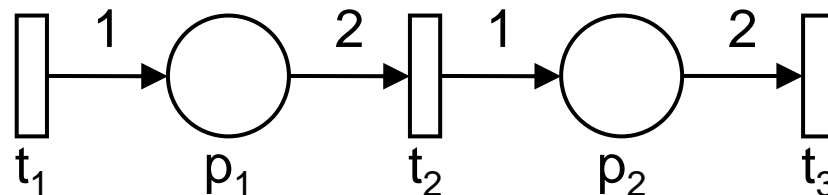
# More about Petri Nets

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- **Marking**
  - A vector representing the number of tokens in all places
- Properties of Petri Nets
  - Reachability (of a marking from another marking)
  - Boundedness
    - The numbers of tokens in all places are bounded
  - Conservation
    - The total number of tokens is constant
  - Deadlock-freedom
    - Always at least one transition can fire
  - Liveness
    - From any marking, any transition can fire sometime
  - Schedulability
    - The first paper will discuss this

# T-Invariant and Finite Complete Cycle

- **T-invariant** is a vector s.t.
  - The  $i$ -th component is the number of firing times of transition  $t_i$
  - The marking is unchanged if firing them so many times
  - However, it does not guarantee that a transition can be fired
    - Deadlock
- **Finite complete cycle** is a sequence of transitions s.t.
  - The marking is unchanged if firing the sequence



One T-invariant: (4,2,1)

Some finite complete schedules:

$\langle t_1, t_1, t_1, t_1, t_2, t_2, t_3 \rangle$

$\langle t_1, t_1, t_2, t_1, t_1, t_2, t_3 \rangle$

# Outline

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- Revisiting Petri Nets
- Application 1: Software Syntheses
  - Synthesis of Embedded Software Using Free Choice Petri Nets
- Application 2: Biological Networks
- Application 3: Supply Chains
- Summary

# Static, Quasi-Static, and Dynamic Scheduling

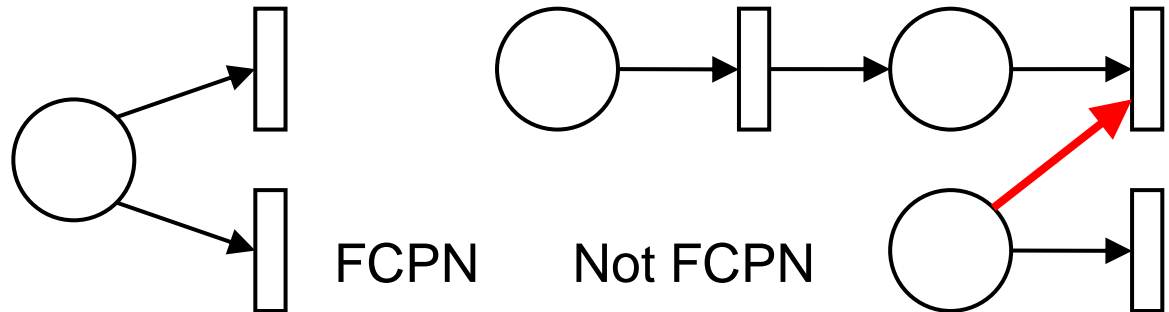
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- Scheduling problem
  - Mapping a functional implementation to real resources
  - Satisfying real-time constraints
  - Using resources as efficiently as possible
- Static scheduling
  - Specifications contain only data computations
  - The schedule can be completely computed at compile time
- Quasi-static scheduling
  - Specifications contain data-dependent controls, like if-then-else or while-do loops
  - The schedule leaves data-dependent decisions at run-time
- Dynamic scheduling
  - Specifications contain real-time controls

# Free Choice Petri Net

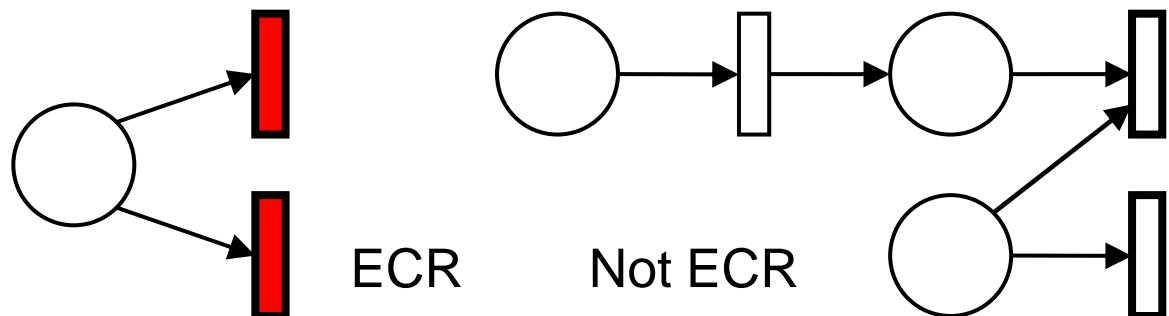
- Free Choice Petri Net (FCPN) is a Petri net such that every arc from a place is
  - A unique outgoing arc, or
  - A unique incoming arc to a transition

exactly an if-then-else structure!



- Two transitions are in **equal conflict relation** (ECR) if their presets are non-empty and equal

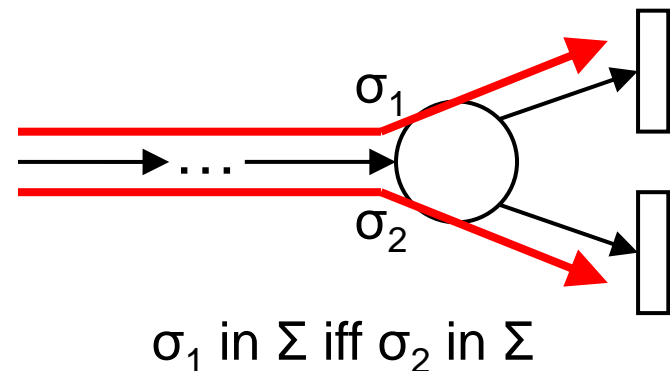
branches of if-then-else structure





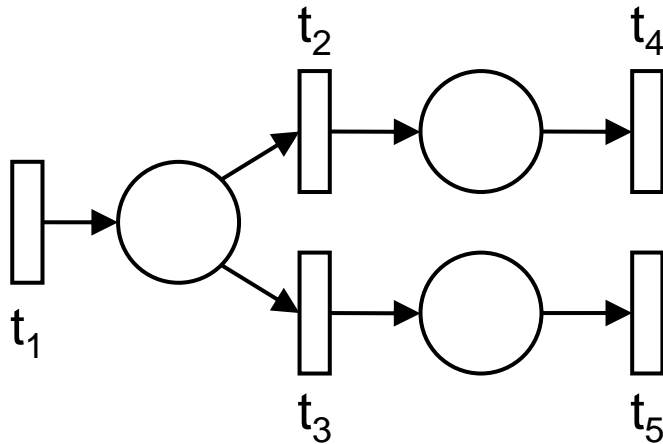
# Valid Schedule (Set)

- Let
  - $\Sigma = \{\sigma_1, \sigma_2, \dots\}$  be a finite set
    - $\sigma_i = \langle \sigma_i^1, \sigma_i^2, \dots \rangle$  is a finite complete cycle containing all source transitions
- $\Sigma$  is a **valid schedule (set)** if
  - For all  $(\sigma_i^j, t_k)$  s.t.
    - $\sigma_i^j \neq \sigma_i^h$  for all  $h < j$
    - $\sigma_i^j \neq t_k$  and they are in equal conflict relation
  - Exist  $\sigma_i$  s.t.
    - $\sigma_i^m = \sigma_i^m$  for all  $m \leq j$
    - $\sigma_i^m = t_k$  if  $m = j$
- In words, a valid schedule is
  - A set of finite complete cycles for every possible outcome of a choice



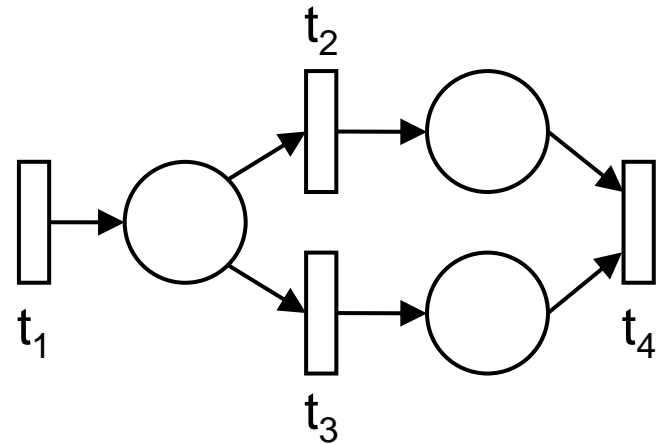
# Quasi-Statically Schedulable

- Given
  - A FCPN  $N$
  - An initial marking  $\mu_0$
- $(N, \mu_0)$  is **quasi-statically schedulable** if
  - There exists a valid schedule



$$\Sigma = \{ \langle t_1, t_2, t_4 \rangle, \langle t_1, t_3, t_5 \rangle \}$$

Schedulable



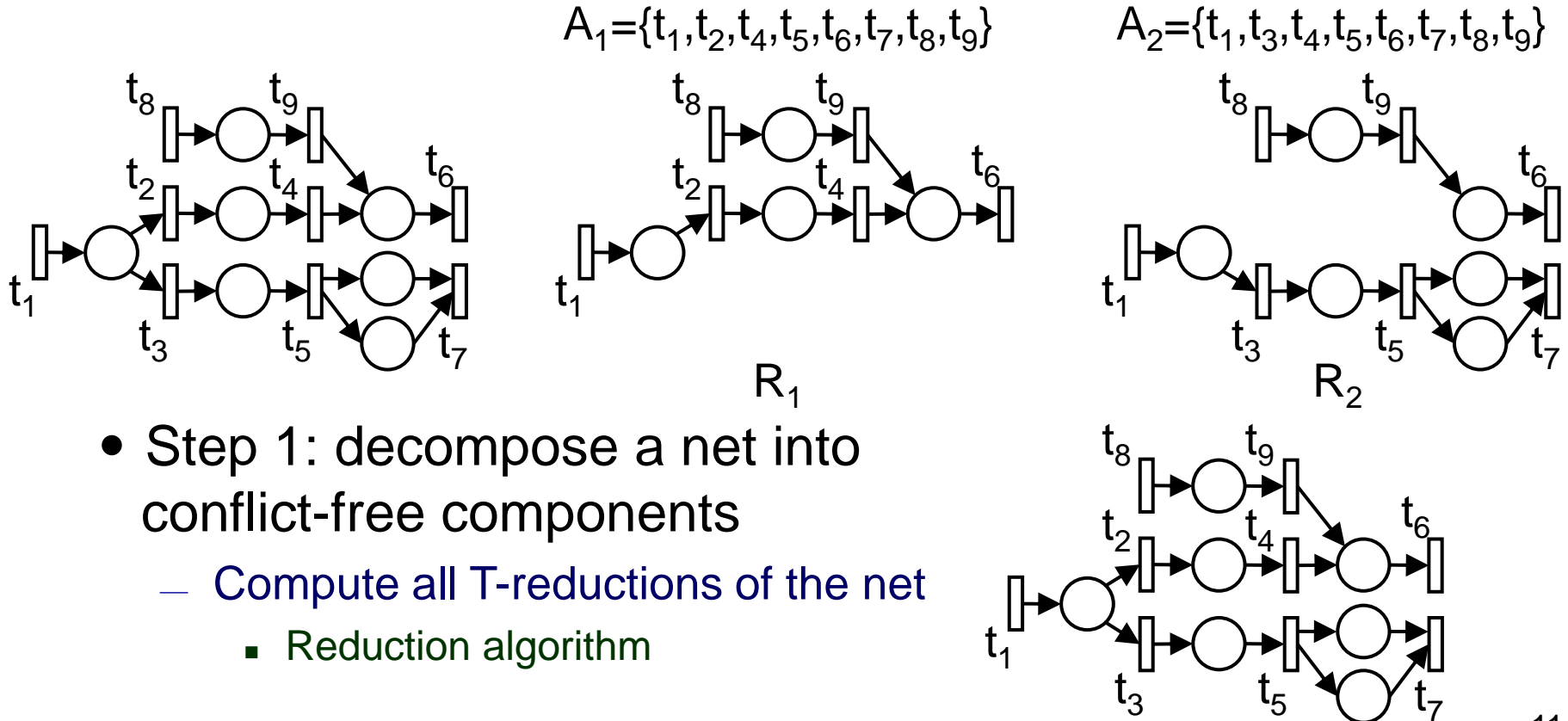
$$\Sigma = \{ \langle t_1, t_1, t_2, t_3, t_4 \rangle \} ?$$

$$\Sigma = \{ \langle t_1, t_1, t_2, t_3, t_4 \rangle, \langle t_1, t_1, t_3, t_2, t_4 \rangle \} ?$$

Non-schedulable

# How to Find a Valid Schedule? Step 1

- **T-allocation** is a function that chooses exactly one transition for every place
- **T-reduction** associated with a T-allocation is a set of subnets generated from the image of the T-allocation



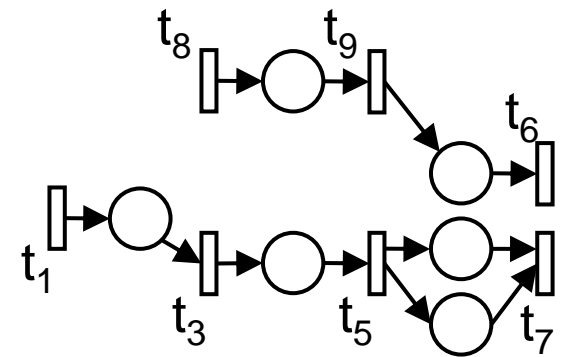
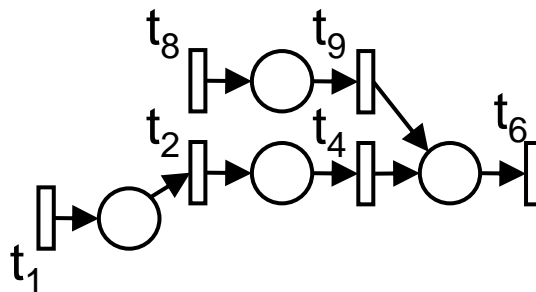
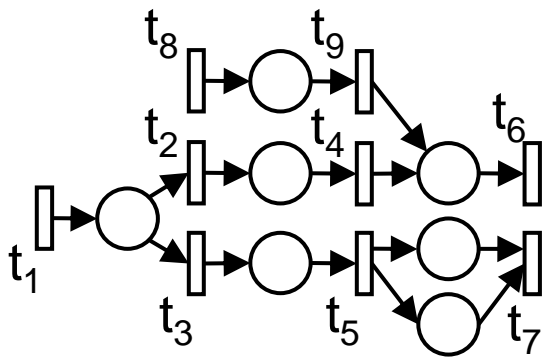
# How to Find a Valid Schedule? Step 2

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- A T-reduction is **schedulable** if
  - It has a finite complete cycle that
    - Contains at least one occurrence of every source transition of the net
  - (Definition 3.5)
- Step 2: check if every conflict-free component is statically schedulable
  - Apply the standard techniques for synchronous dataflow networks
    - Solve T-invariant equation
    - Check deadlock by simulation

# How to Find a Valid Schedule? Step 3

- Given a FCPN, there exists a valid schedule if and only if every T-reduction is schedulable
  - Note that: a valid schedule  $\rightarrow$  quasi-schedulable
- Step 3: derive a valid schedule, if there exists one
  - Compute the union of the finite complete cycles of all T-reduction



T-invariants  
(why needs two?)

$(1, 1, 0, 1, 0, 1, 0, 0, 0)$   
 $(0, 0, 0, 0, 0, 1, 0, 1, 1)$

$(1, 0, 1, 0, 1, 0, 1, 0, 0)$   
 $(0, 0, 0, 0, 0, 1, 0, 1, 1)$

finite complete cycle

$\langle t_1, t_2, t_4, t_6, t_8, t_9, t_6 \rangle$

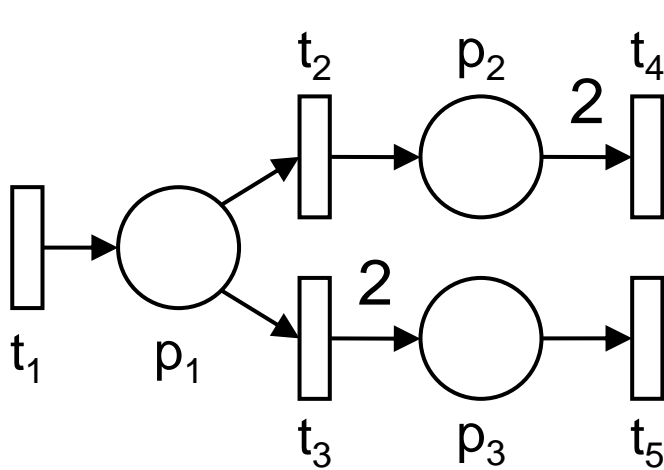
$\langle t_1, t_3, t_5, t_7, t_8, t_9, t_6 \rangle$

valid schedule

$\{ \langle t_1, t_2, t_4, t_6, t_8, t_9, t_6 \rangle, \langle t_1, t_3, t_5, t_7, t_8, t_9, t_6 \rangle \}$

# Code Generation

- Derive an implementation directly from a valid schedule



valid schedule

$\{ \langle t_1, t_2, t_1, t_2, t_4 \rangle, \langle t_1, t_3, t_5, t_5 \rangle \}$

```

while ( true ) {
    t1;
    if ( p1 ) {
        t2;
        count ( p2 ) ++;
        if ( count ( p2 ) == 2 ) {
            t4;
            count ( p2 ) -- 2;
        }
    }
    else {
        t3;
        count ( p3 ) += 2;
        while ( count ( p3 ) >= 1 ) {
            t5;
            count ( p3 ) --;
        }
    }
}

```

Annotations in the code:

- 1 → p<sub>2</sub> → 2**: Points to the inner if statement in the first branch.
- 2 → p<sub>3</sub> → 1**: Points to the while loop in the second branch.
- conflict transition**: Points to the transition t<sub>1</sub> in the while loop header.

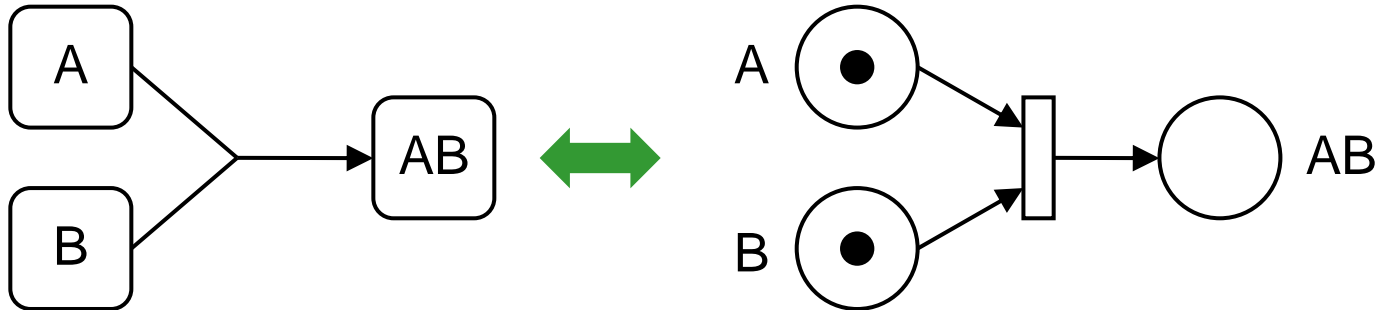
# Outline

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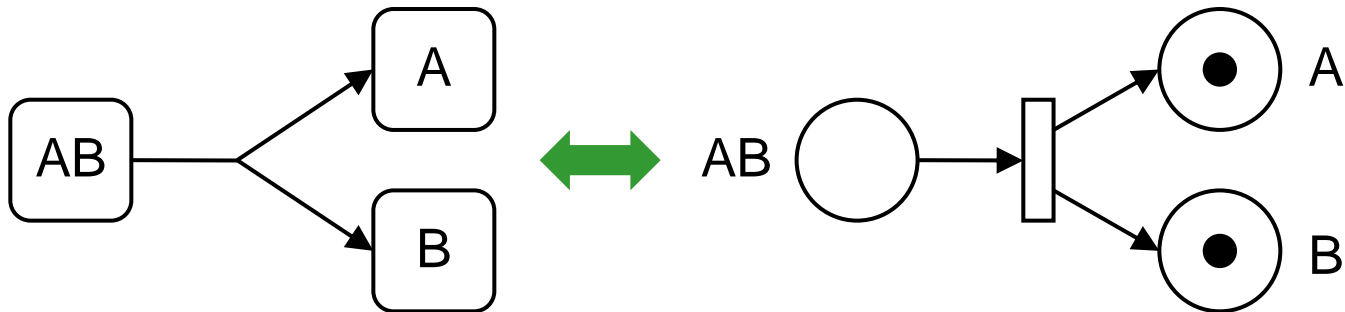
- Revisiting Petri Nets
- Application 1: Software Syntheses
- Application 2: Biological Networks
  - Petri Net Modeling of Biological Networks
- Application 3: Supply Chains
- Summary

# Basic Modeling of Biological Reactions (1/2)

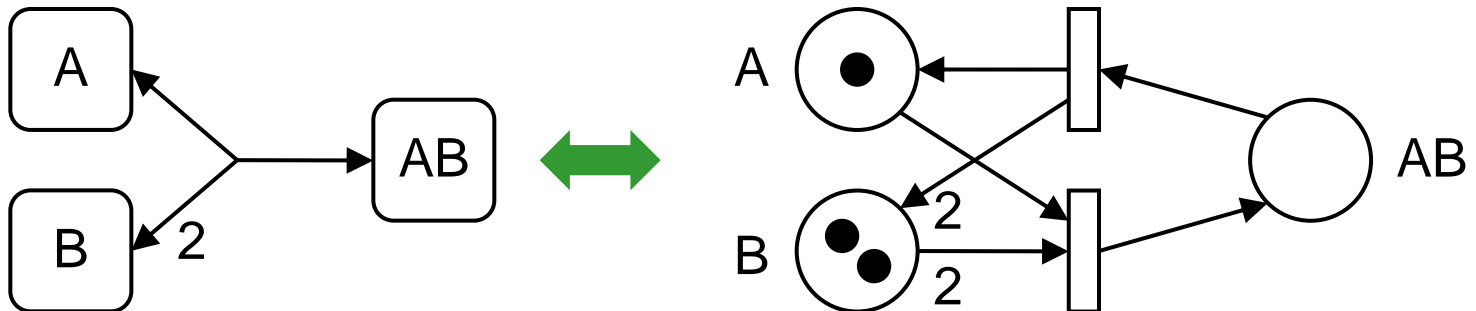
- Synthesis



- Decomposition



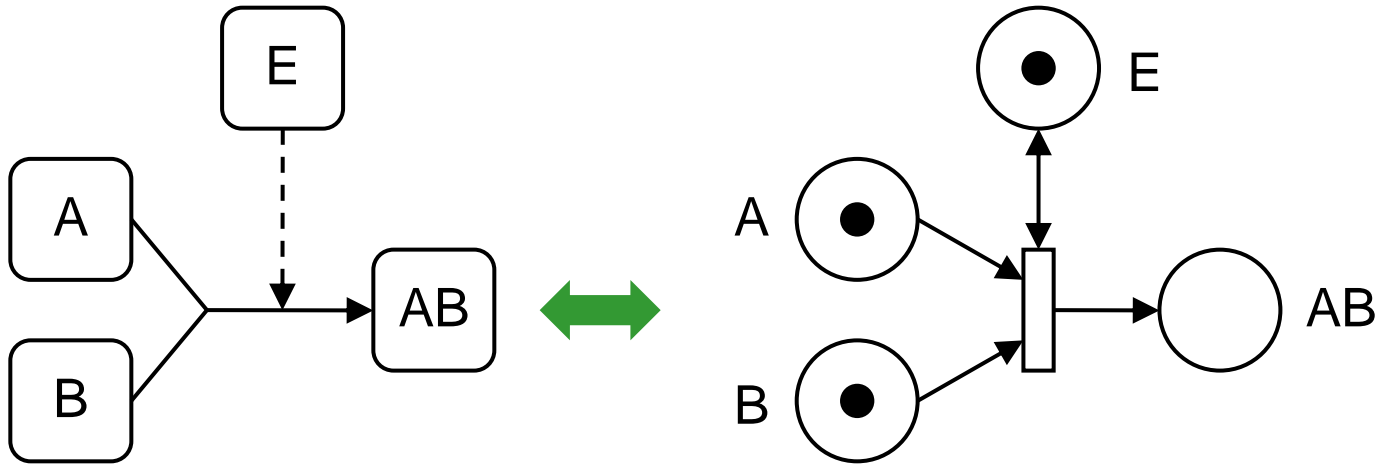
- Reversible reaction with stoichiometry



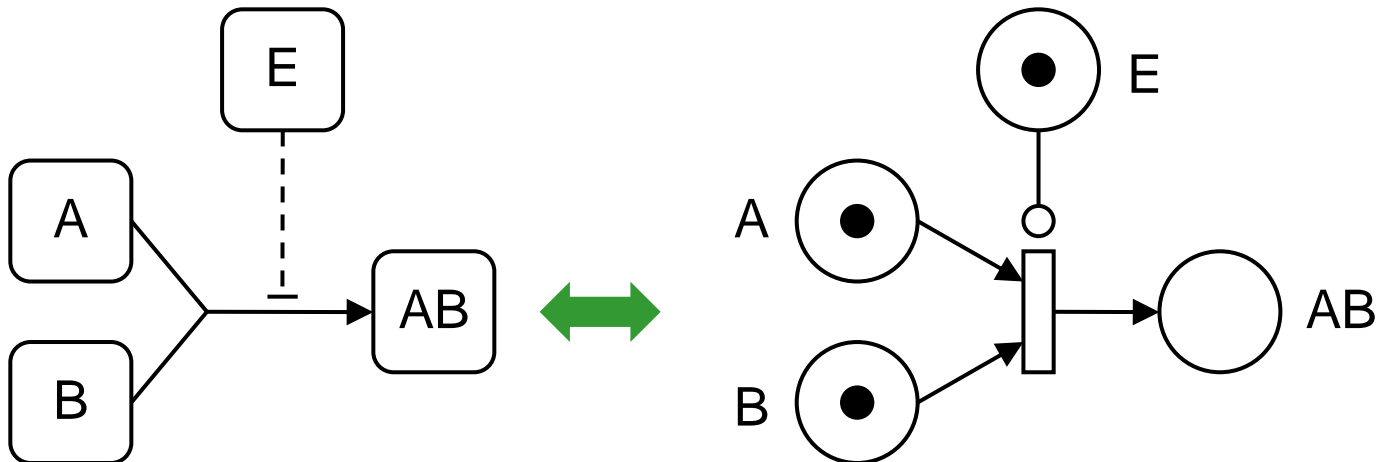


# Basic Modeling of Biological Reactions (2/2)

- Catalyzed reaction



- Inhibited reaction



# Extensions of Petri Nets

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- Coloured Petri Net (CPN)
  - Assign data values to the token
  - Define constraints on the token values
- Stochastic Petri Net (SPN)
  - Transitions have exponentially distributed time delays
- Hybrid Petri Net (HPN)
  - Discrete and continuous places
    - Marked tokens and concentration levels
  - Discrete and continuous transitions
    - Determined and distributed delays
- Functional Petri Net (FPN)
  - Flow relations depend on the marking
- Hybrid Functional Petri Net (HFPN)

# More Complicated Modeling

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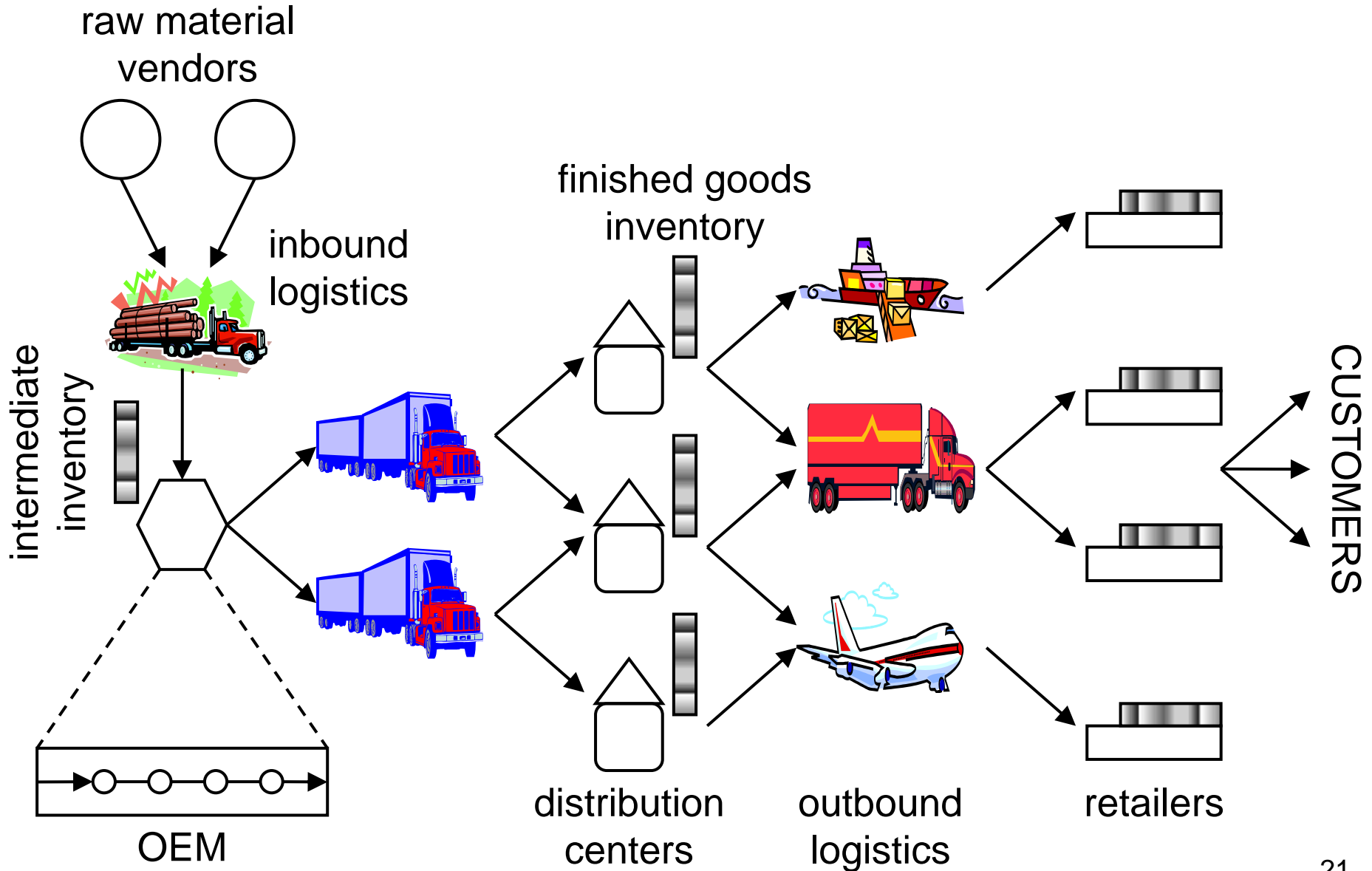
- Biochemical networks
  - Enzymatic reaction chain: CPN
  - Intrinsic noise due to low concentrations: SPN
  - More general pathway: FPN, HFPN
- Genetic networks
  - Response to genes rather than consumption and production
  - Switch Control: logical approach, CPN
  - Concentration dynamics: HPN, HFPN
- Signaling networks
  - Response to signal rather than consumption and production
  - Transition delay: timed PN, timed CPN, SPN
- Discussion
  - Tradeoff between expressiveness and analyzability
  - Spatial properties, hierarchical modeling, other modeling formalisms

# Outline

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- Revisiting Petri Nets
- Application 1: Software Syntheses
- Application 2: Biological Networks
- Application 3: Supply Chains
  - Performance Analysis and Design of Supply Chains: A Petri Net Approach
- Summary

# Supply Chain Networks (SCN)

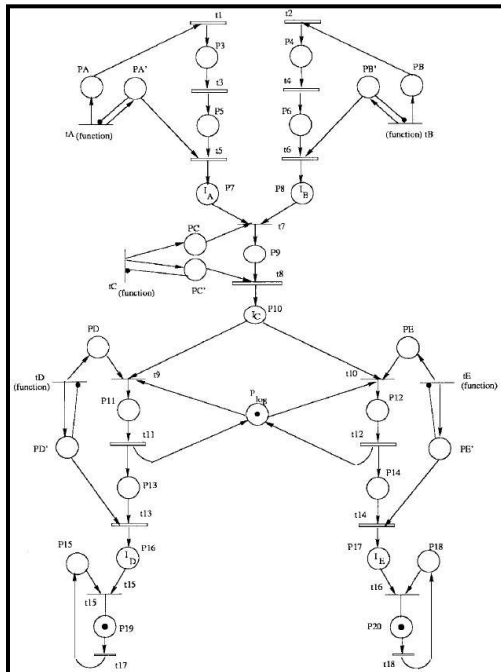
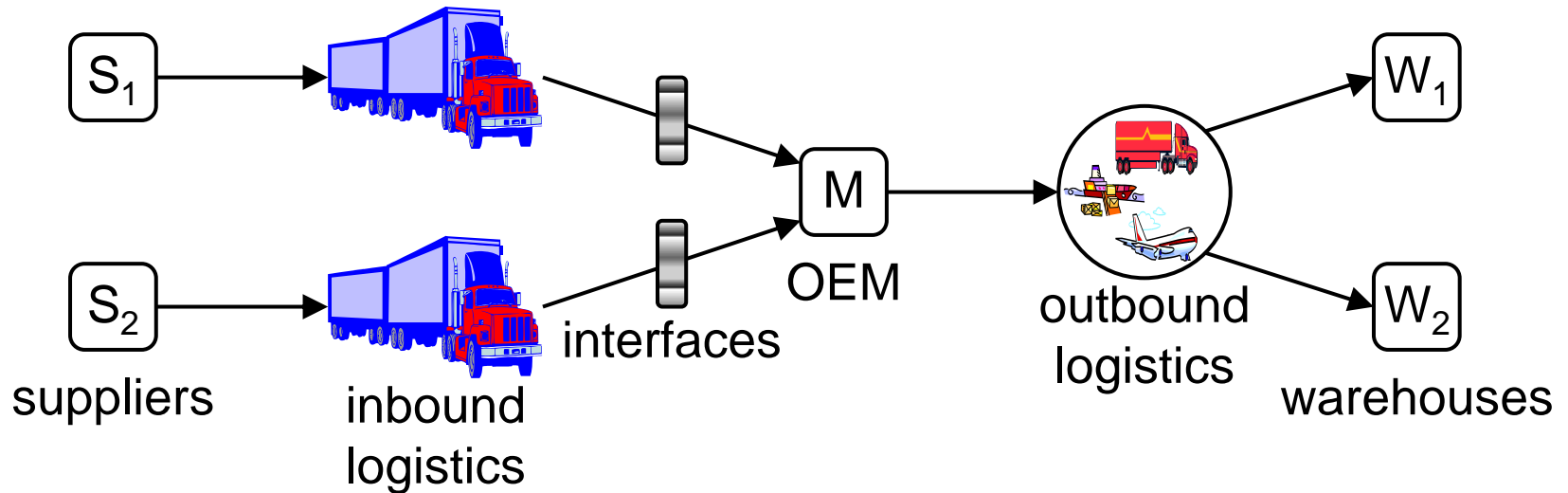


# Configurations & Operational Models of SCN

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- Configurations
  - Serial structure
  - Divergent structure: petroleum industry
  - Convergent structure: automobiles and air crafts
  - Network structure: computer industry
- Operational models
  - Make-to-stock (MTS)
    - Orders are satisfied from stocks of inventory of **finished goods which are kept at retail points**
  - Make-to-order (MTO)
    - **A confirmed order triggers the flow** of the supply chain
  - Assemble-to-order (ATO)
    - Before **decoupling point**, intermediate goods are made-to-stock
    - After decoupling point, goods are made-to-order
  - Tradeoff between holding cost and delayed delivery's cost

# Performance Analysis – Modeling



- Generalized Stochastic Petri Net (GSPN)
  - Random order request
  - Random logistics/interface time
- MTS, MTO, and ATO may have different structures & initial markings

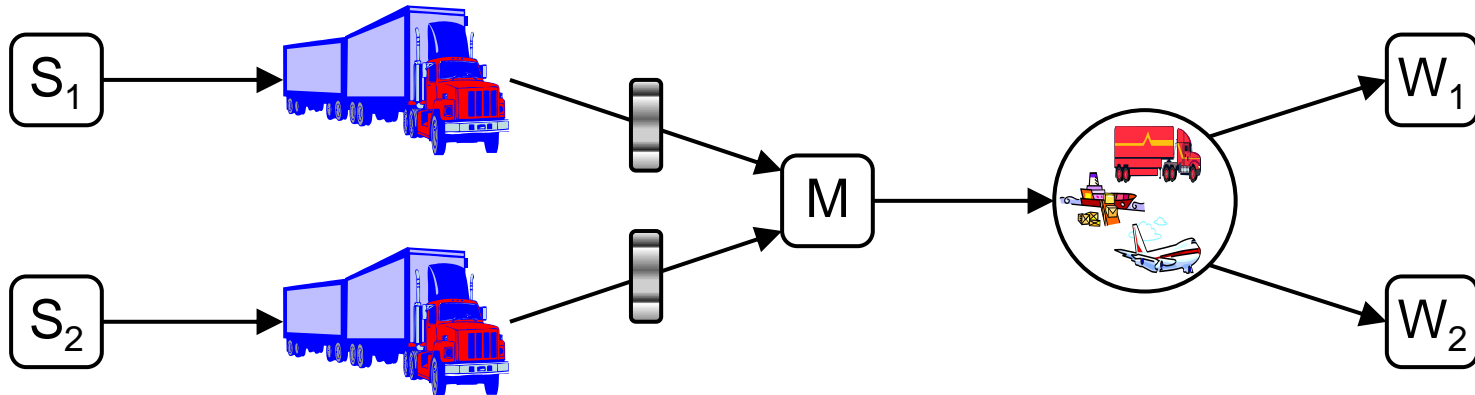
# Performance Analysis – Setting

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- Cost function
  - Holding cost for inventories:  $H_I$
  - Cost of delayed delivery:  $H_D$
  - Vary the ratio of  $H_D$  and  $H_I$  from 1.5 to 40.0
- Apply Stochastic Petri Net Package (SPNP)
- Compare between make-to-stock (MTS) and assemble-to-order (ATO)



# Performance Analysis – Experiment 1

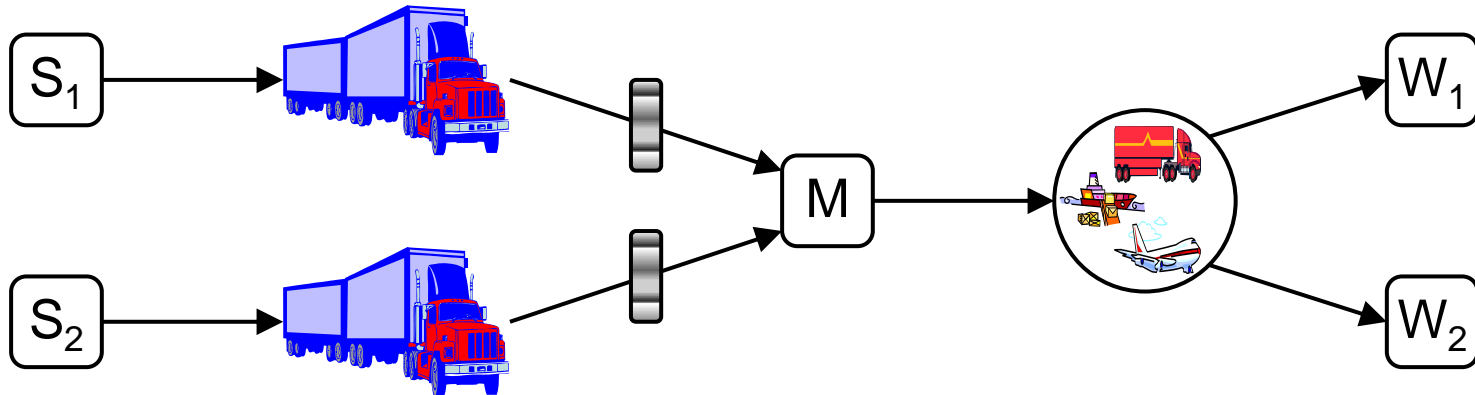


- Change arrival rate of end products on ( $W_2$ )

Arrival Rate ( $W_2$ )	Total Cost			
	$H_D / H_I = 1.5$ (Expensive Holding)		$H_D / H_I = 40$ (Expensive Delay)	
	MTS	ATO	MTS	ATO
0.8	22.421	19.815	} 26.001	257.437
1.0	21.237	18.610		237.559
1.2	20.012	17.714		224.228
1.4	18.774	17.016		214.675

**MTS > ATO**  
reasonable
**U-shape**  
why?
**MTS < ATO**  
reasonable

# Performance Analysis – Experiment 2



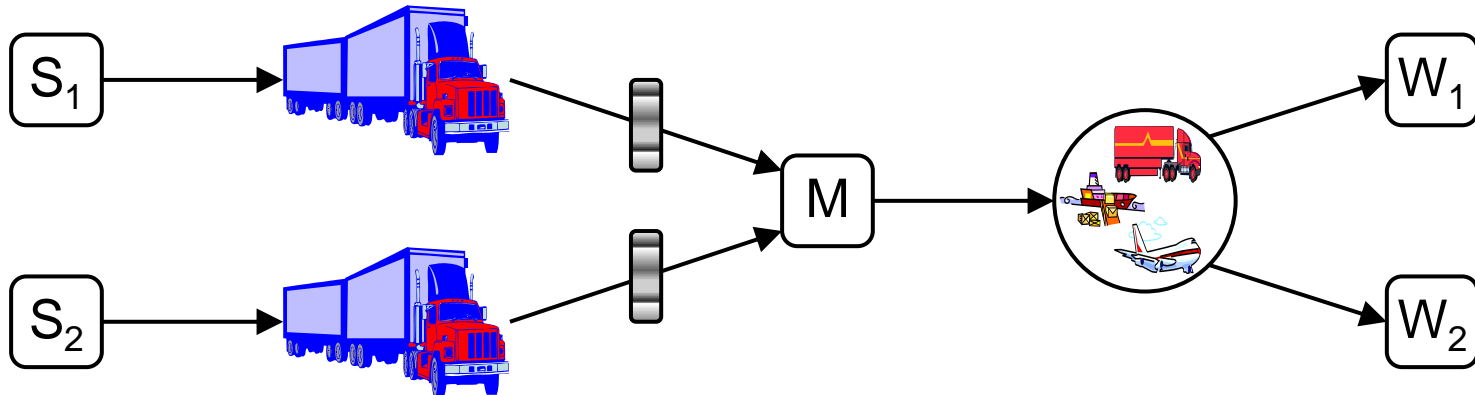
- Change targeted finished goods inventory (on M)

FGI (M)		Total Cost			
		MTS		ATO	
MTS	ATO	$H_D / H_I = 1.5$	$H_D / H_I = 40$	$H_D / H_I = 1.5$	$H_D / H_I = 40$
6	5	18.54	28.01	15.64	197.40
9	6	27.53	29.34	18.37	201.52
12	7	35.553	42.175	21.07	204.87
15	8	43.403	49.929	23.73	207.92

holding costs play more important roles

immune but useless

# Performance Analysis – Experiment 3

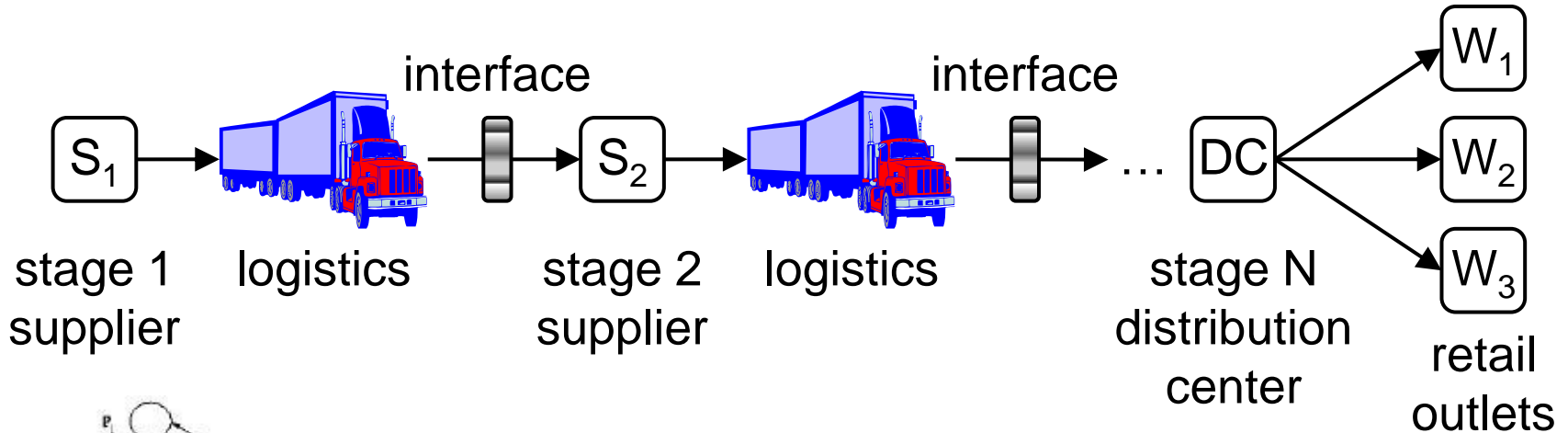


- Change interface times (from  $S_2$  to  $M$ )

Interface Rate ( $S_2 \rightarrow M$ )	Total Cost			
	$H_D / H_I = 1.5$ (Expensive Holding)		$H_D / H_I = 40$ (Expensive Delay)	
	MTS	ATO	MTS	ATO
4.0	22.566	15.542	24.934	197.185
5.0				
6.0				
8.0				
	22.651	15.640	24.981	197.360
	22.709	15.705	25.038	197.502
	22.780	15.785	25.109	197.659

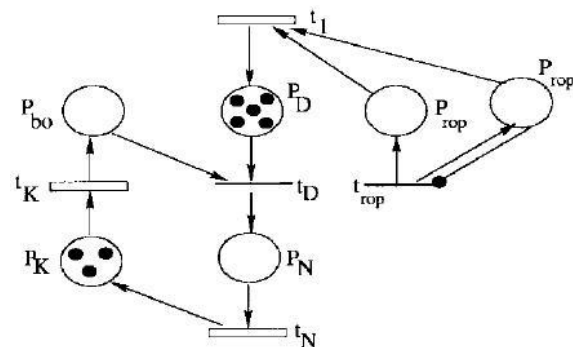
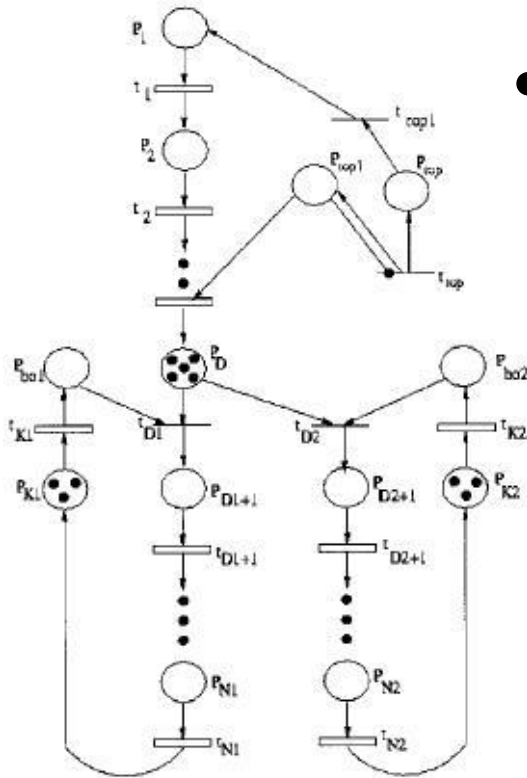
holding costs increase because interface  $S_1 \rightarrow M$  is not fast enough to work with interface  $S_2 \rightarrow M$

# Decoupling Point Location Problem – Modeling



- Integrated GSPN-queuing model

- Amendable for integrated queuing network GSPN analysis and deriving aggregated facility by solving the original product from queuing network (PFQN)



# Decoupling Point Location Problem – Setting

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- Cost function
  - Holding cost (proportional to  $H_1$ )
    - $H_1$ : holding cost for the first stage supplier
    - Increase as moving from the first stage supplier to the distribution center ( $H_1, 1.2H_1, 1.2^2H_1, 1.2^3H_1, \dots$ )
  - Lead time cost (proportional to  $H_2$ )
    - $H_2$ : average lead time cost per unit good per hour
- Consider 5 stage supply chain with the last stage being the retail outlet
- Set the decoupling point at stages 1, 2, 3, and 4
- Solve the PFQNs

# Decoupling Point Location Problem – Experiment

Decoupling Point	Total Cost (Base Stock Policy)			
	Expensive Holding $\leftrightarrow$ Expensive Delay			
	$H_2 / H_1 = 10$	$H_2 / H_1 = 30$	$H_2 / H_1 = 40$	$H_2 / H_1 = 50$
1	<b>3.596</b>	<b>5.940</b>	<b>8.285</b>	10.630
2	5.215	6.963	8.712	<b>10.461</b>
3	8.967	10.237	11.508	12.779
4	12.071	12.429	12.788	13.147

Decoupling Point	Total Cost (Reorder Point Policy)			
	Expensive Holding $\leftrightarrow$ Expensive Delay			
	$H_2 / H_1 = 10$	$H_2 / H_1 = 30$	$H_2 / H_1 = 40$	$H_2 / H_1 = 50$
1	<b>3.427</b>	<b>5.853</b>	8.280	10.706
2	4.234	6.060	<b>7.886</b>	9.711
3	5.686	6.974	8.262	9.550
4	8.055	8.414	8.772	<b>9.131</b>

As delay cost increases, the decoupling point is moving to right

# Outline

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- Revisiting Petri Nets
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# Summary

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- Perti Net and its extension provide a wide range of applications
  - Software synthesis
  - Biological network
  - Supply chain