# Keep in Touch

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# **Project Motivation**

#### • Problem:

- Current touch type learning software has no way to enforce correct finger usage.
- Incorrect finger usage can lead to slower typing times as well as hand and arm pain.

#### • Proposal:

• Develop a Smart-Glove to provide real-time feedback on finger usage

#### • Design Criteria:

- Able to detect > 1060 keystrokes/min (fastest typing speed)
- Force Range = 0.25-0.85N (Gerard 1999)
- Sensitivity (true positive) > 90%
- Specificity (true negative)> 90%

# System Design

Smart glove with force sensors on each finger





Software compares pressure data with keystroke data to determine finger presses. GUI provides feedback for the learn-to-type course.

wiseGEE





# **Timing and Synchronization**

#### Importance of Timing in Timestamps

- Need to distinguish between keystrokes
- Fastest typer generates 1060 keystrokes/min = 17.67 keystrokes/sec
  - Nyquist's Theorem: must sample at twice that = 35.33 keystrokes/sec
  - The mbed code collects data at 40 samples/sec
- Ticker object from mbed.h library
  - Creates a timed interrupt at desired frequency
  - Ticker object's attach() method is used to specify ISR
  - Our ISR sends finger data to the PC 40 times per second

#### • Synchronization:

- PC sends signal to mbed to start Ticker
- Millisecond precision required, so serial port delays are okay.
- 2 mbeds implies 2 data streams need to be processed
  - Need to be efficiently interleaved in chronological order

# Inference Problem

### • Formalized problem:

- X = finger used by user + timestamp recorded on MBED
- Y = key pressed on computer + timestamp record on PC
- Goal: find P(X|Y)
  - Assume a uniform a distribution on X (user is equally likely to have selected any key)
  - Solving for the Maximum a Posteriori estimate of X given Y simplifies to find the X which maximizes P(Y|X).
    - P(Y|X) can be constructed ourselves using some assumptions
      - Given the timestamp of X, the timestamp of Y is likely to very close that of X
      - Given the finger used, it is unlikely that a key very far from that finger was pressed. (This assumption can be used to break ties or filter out nonsensical results.)

## Next Steps

#### • Improved force sensor

- More flexible
- Bigger surface area to detect key presses
- Incorporate a calibration mode to account for keyboard setup
- Add a non-uniform prior to better predict finger usage

