



TerraSwarm

Connecting the Cloud to Things

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Invited Talk

Berkeley Cloud Workshop

February 27, 2015



Sponsored by the TerraSwarm Research Center, one of six centers administered by the STARnet phase of the Focus Center Research Program (FCRP) a Semiconductor Research Corporation program sponsored by MARCO and DARPA.



Berkeley Ubiquitous SwarmLab



The SwarmLab is an industry-university partnership pursuing “swarm technology.”

VISA IHI
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ERICSSON



TerraSwarm Research Center



The TerraSwarm Research Center 2013-2018

What it is:

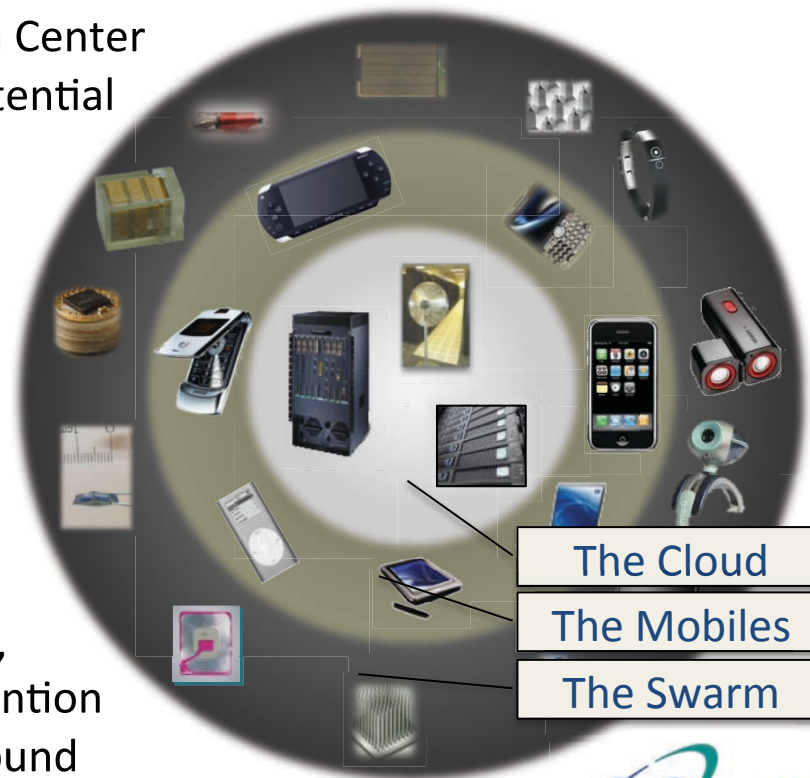
The TerraSwarm Research Center is addressing the huge potential (and associated risks) of pervasive integration of smart, networked sensors and actuators into our connected world.

The Goal

To lead the world in development of the platforms, methodologies, and tools that enable invention of creative, secure, and sound applications using networked sensors and actuators.

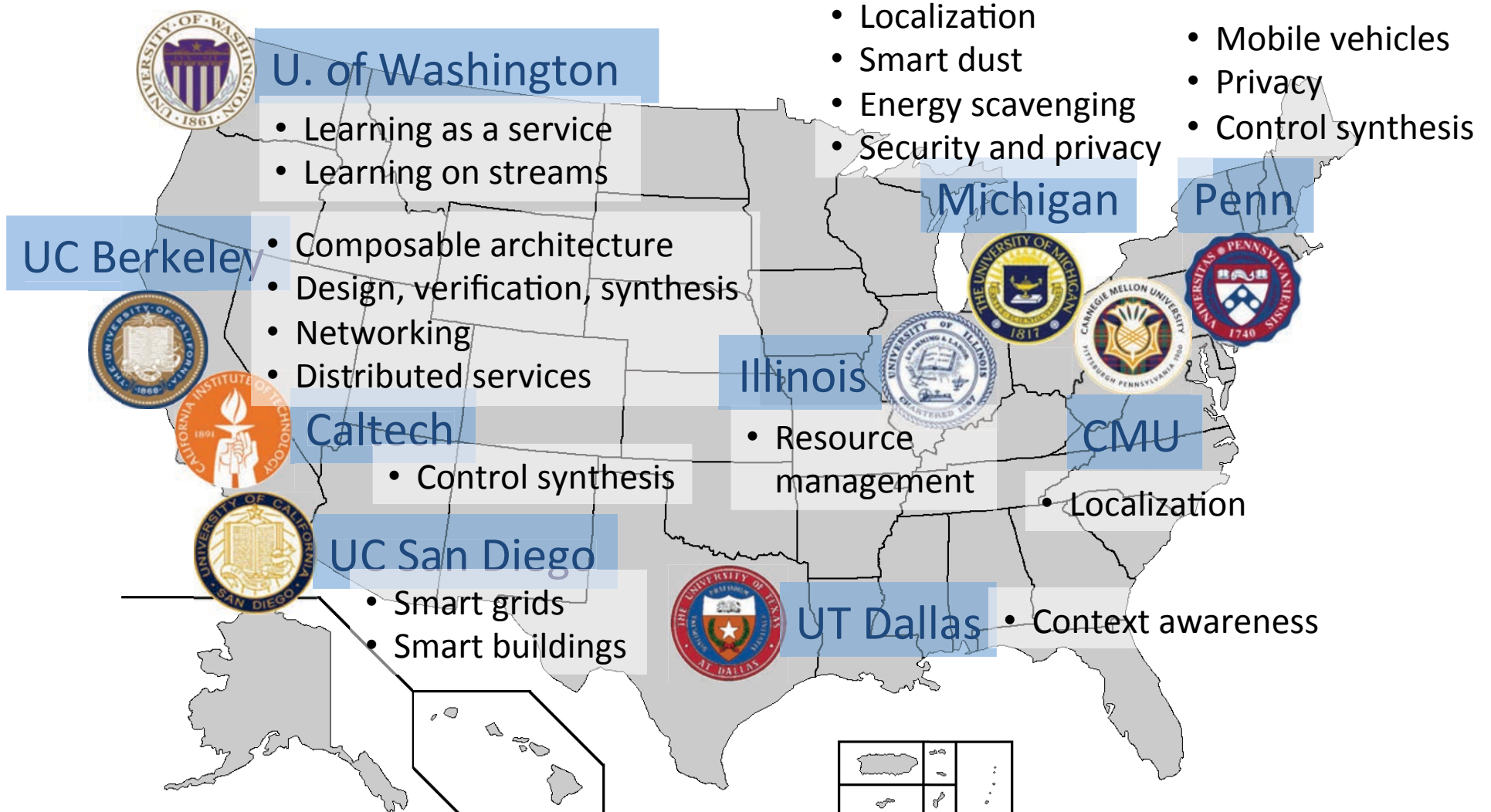
TerraSwarm Research Center

The Sponsors:





TerraSwarm Sites





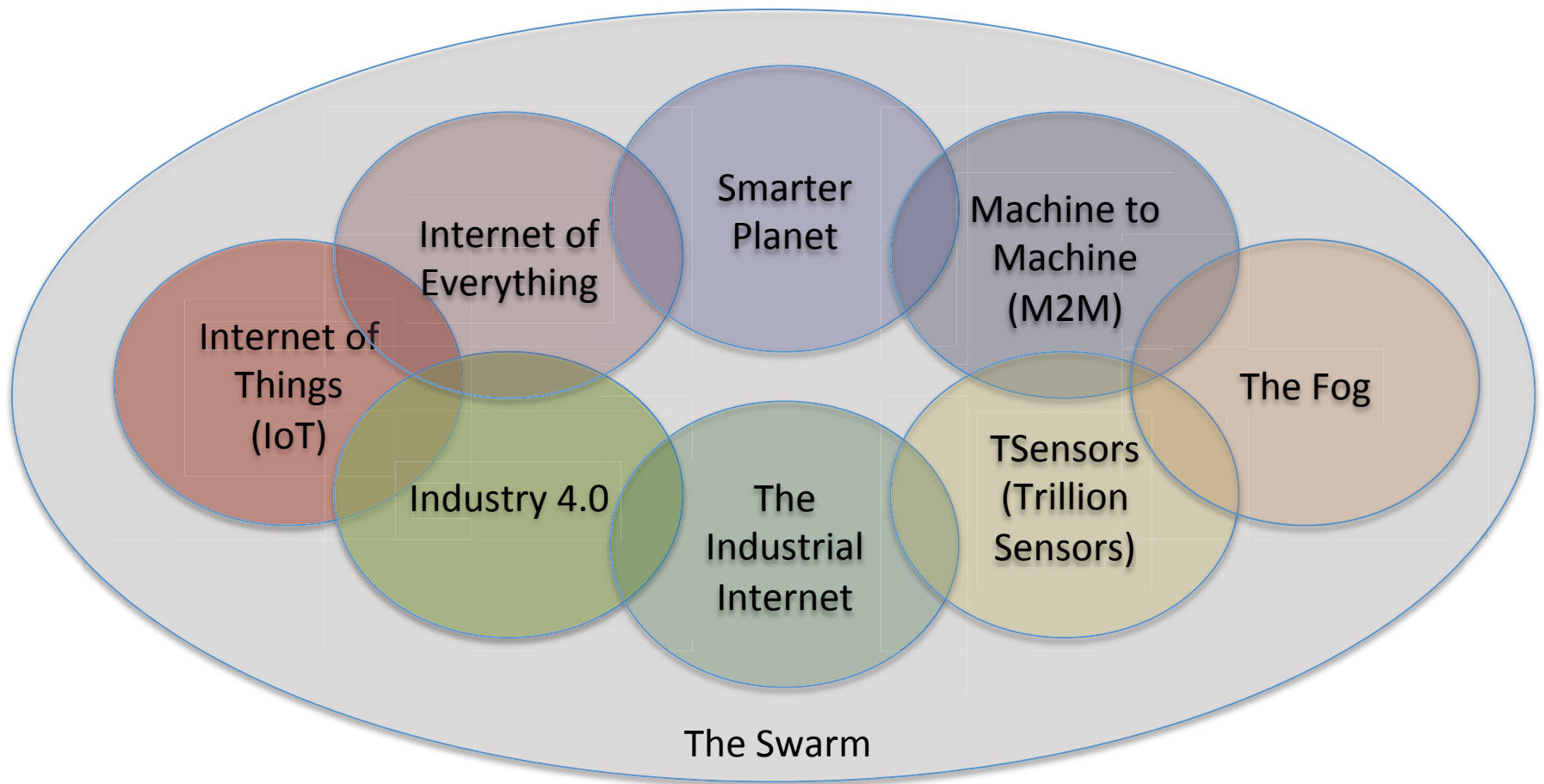
In the last year...



IoT has hit the fan!

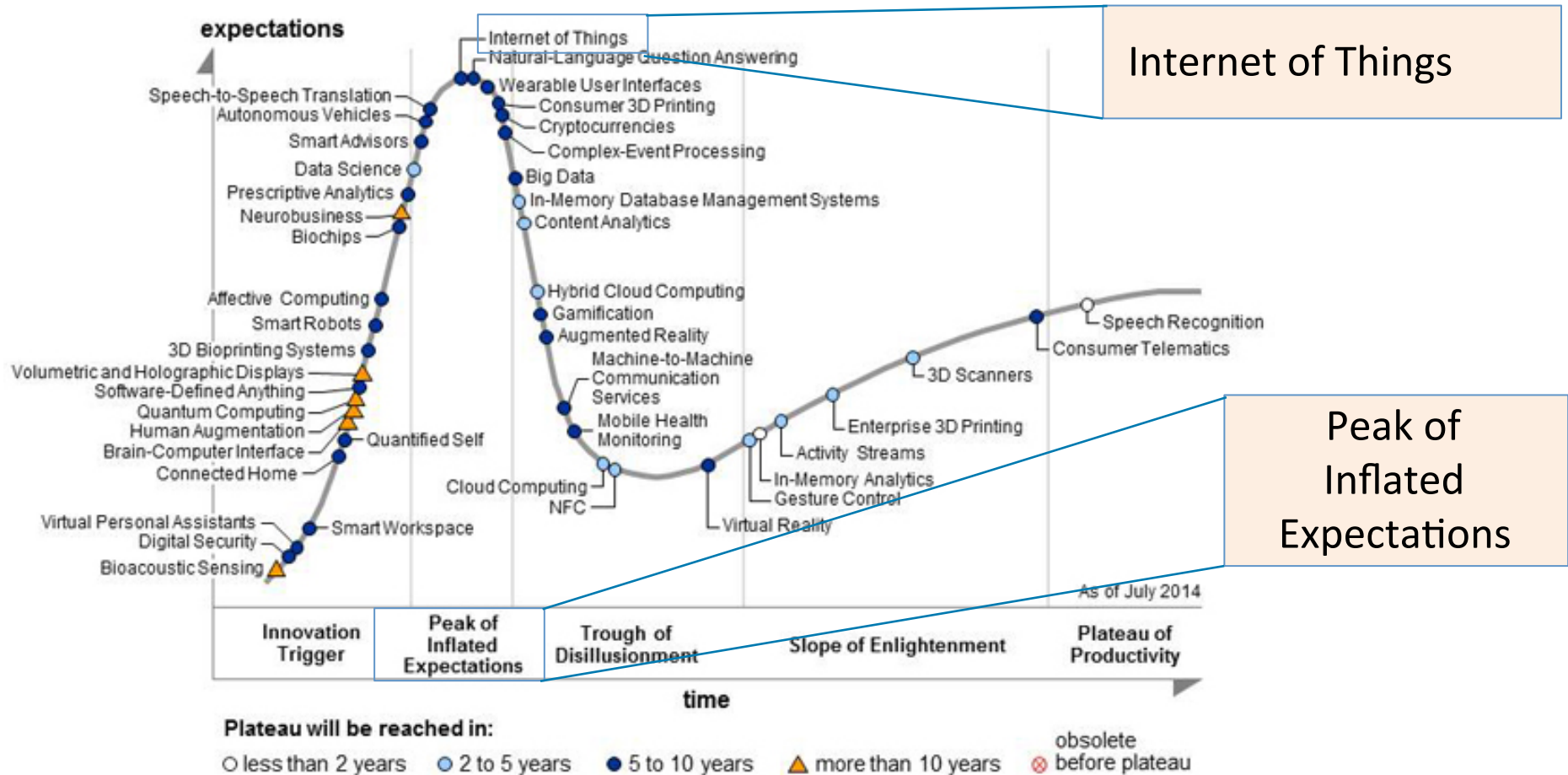


The Buzz around the Swarm





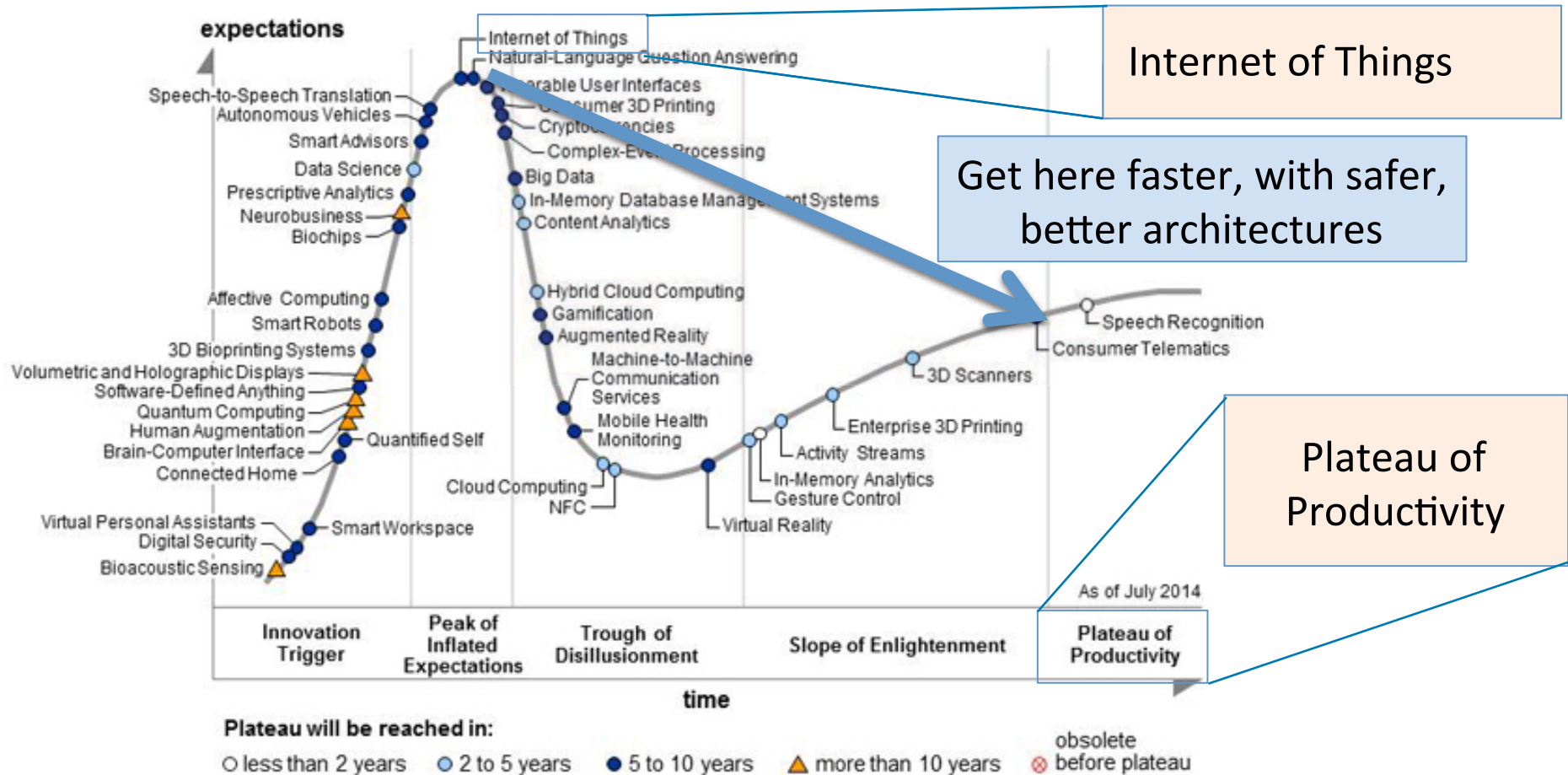
Gartner Hype Cycle 2014



<http://www.gartner.com/technology/research/hype-cycles/>



The Goal of TerraSwarm



<http://www.gartner.com/technology/research/hype-cycles/>



In the last year... Startups!!!

designlines INTERNET OF THINGS

News & Analysis

IoT Blooms in San Francisco

Rick Merritt

4/14/2014 09:00 AM EDT

7 comments



82



Tweet

84



Share

98



g+1

24

SAN FRANCISCO — Less than an hour's drive north from Silicon Valley and a short walk from San Francisco's financial district, a new high-tech community is being born. Call it IoT Town.

 Whistle



SKYCATCH



AUTOMATIC

 fitbit

EE|Times

 Highway 1



LEMNOS Labs

WEARABLE WORLD

TerraSwarm Research Center





In the last year...

Disasters!!!

Cyber attacks:

- Target
- Home Depot
- JP Morgan Chase
- Anthem
- ...

Vulnerabilities:

- Shellshock
- Heartbleed
- ...





Our Focus: The Internet of Important Things



Bosch-Rexroth

Example:

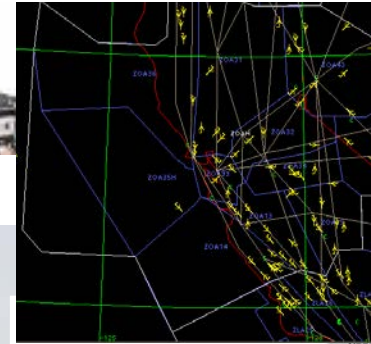
Print-on-demand printing press by Bosch Rexroth.

- 100s of microcontrollers
- Ethernet
- Clock synchronization
- TCP/IP
- Deterministic latency
- No packet losses
- Vast data source
- Safety-critical
- **Today: Isolated**
- **Tomorrow: Connected**

Cyber-Physical Systems (CPS): *Orchestrating networked computational resources with physical systems*



Avionics

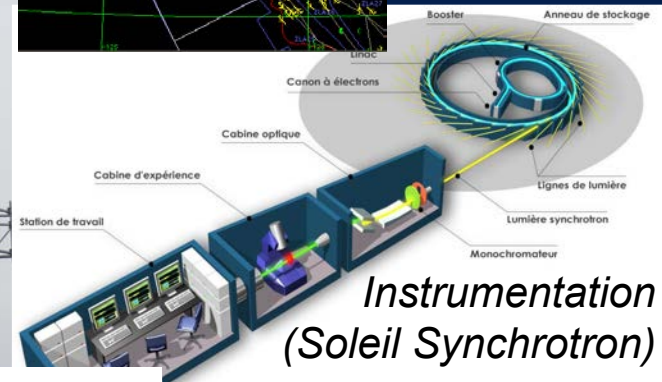
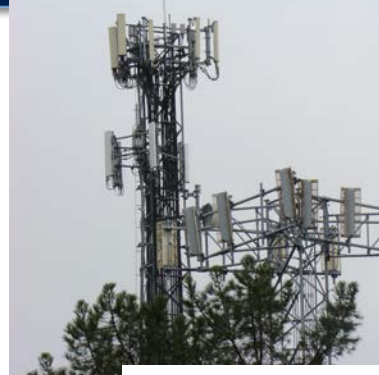


Transportation
(Air traffic
control at
SFO)

Building Systems

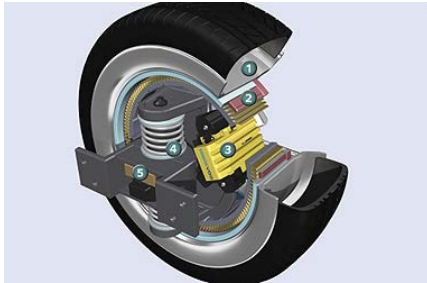


Telecommunications

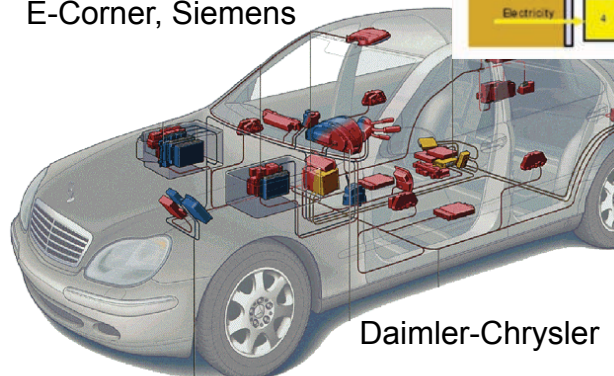


Instrumentation
(Soleil Synchrotron)

Automotive



E-Corner, Siemens



Daimler-Chrysler

Military systems:



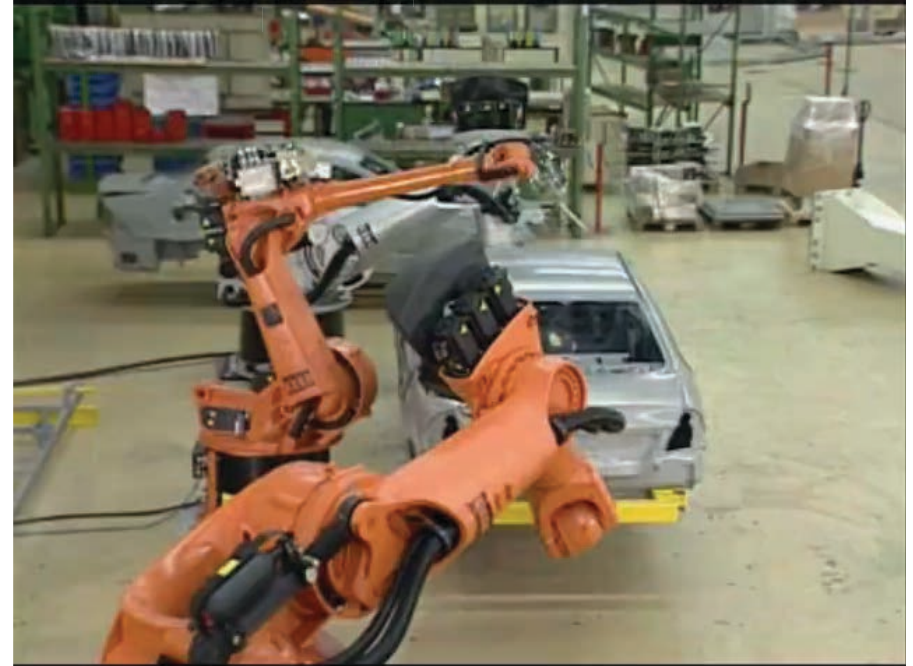
Courtesy of Doug Schmidt

Power
generation and
distribution



Courtesy of
General Electric

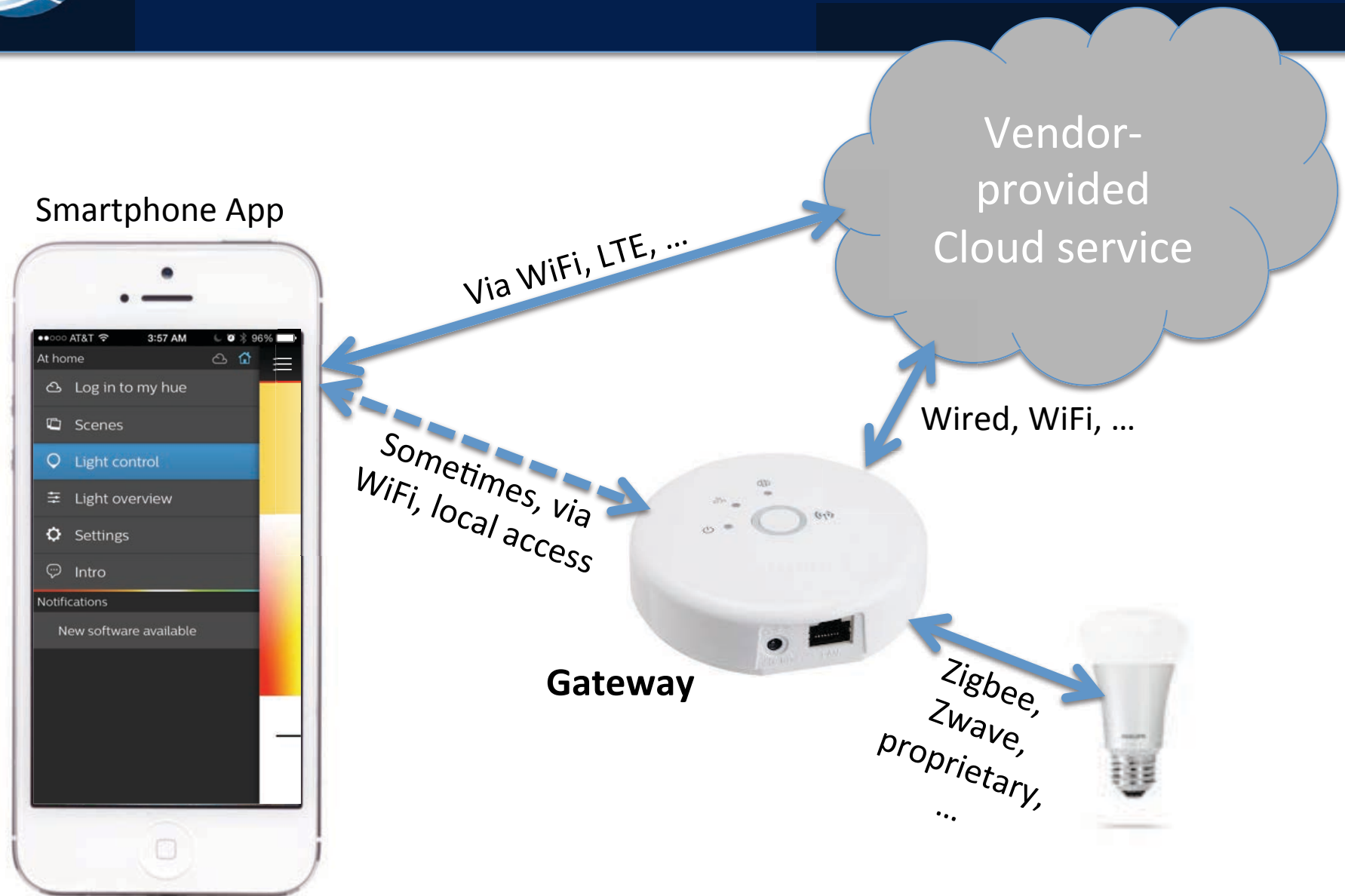
Factory automation



Courtesy of Kuka Robotics Corp.



Typical IoT Architectures Today



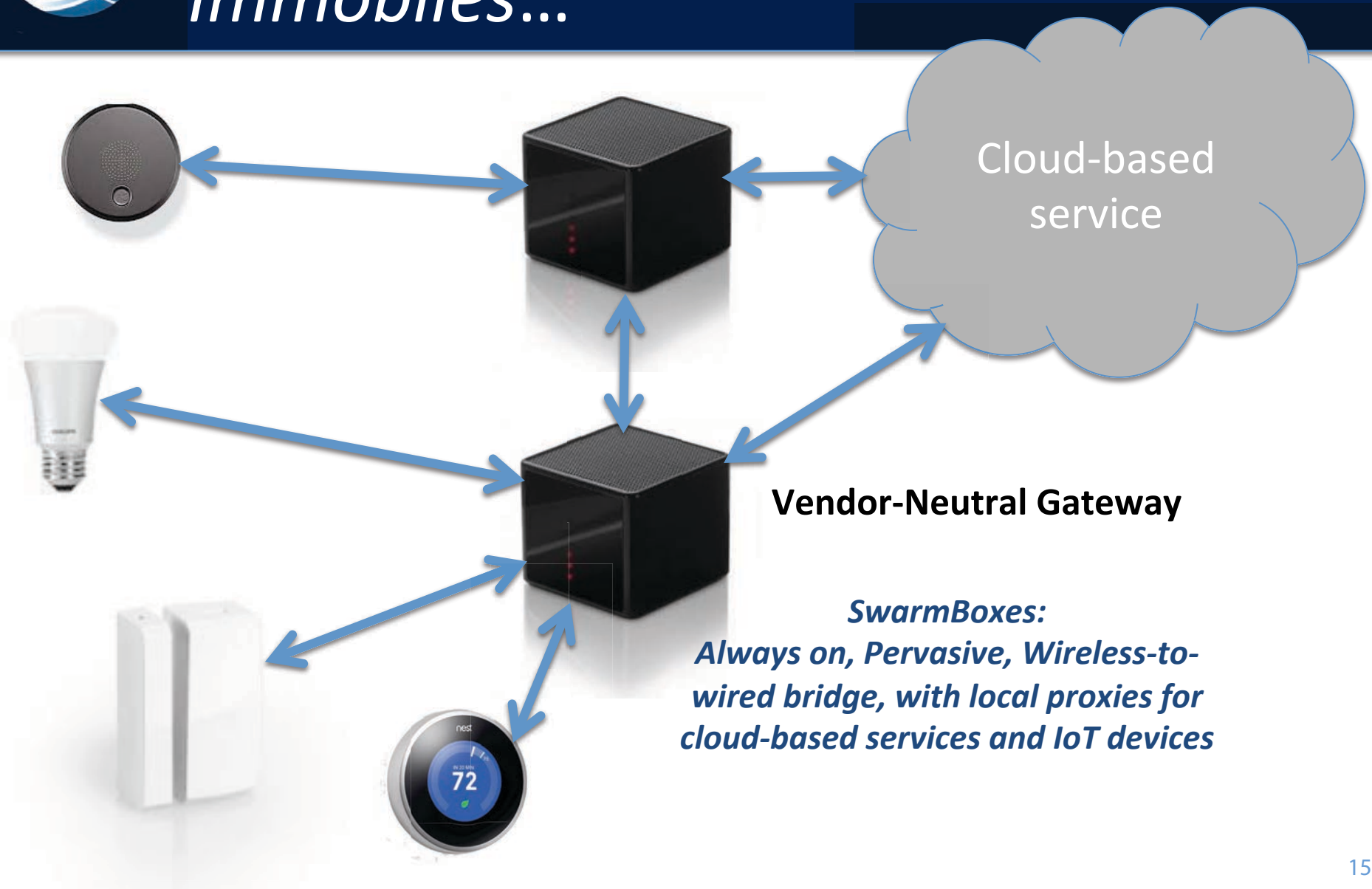


Challenges

- Smartphone apps proliferate, increasing user complexity.
- Vendor-specific gateways don't scale well to many vendors.
- Latency of cloud-based services is substantial and uncontrollable.
- Security and privacy of the cloud: trust?
- Composition of services can only be done in the cloud (e.g. using IFTTT), increasing latency.
- Many moving parts makes systems less reliable, and tracking the source of problems can be hard.
- Hard to imagine using this technology in the *internet of important things* (IoIT)



A New Infrastructure *Immobiles...*





The Immobiles

Fingers of the Cloud Touching the Physical World

Exploiting locality:

- Keep data local by default (privacy)
- Provide service even with network outages (resilience)
- Differentiate clients who have physical access from those that don't (security)
- Provide basic services:
 - Location estimation
 - Access to local devices
 - Certificate authority
 - Publish-and subscribe
 - Discovery

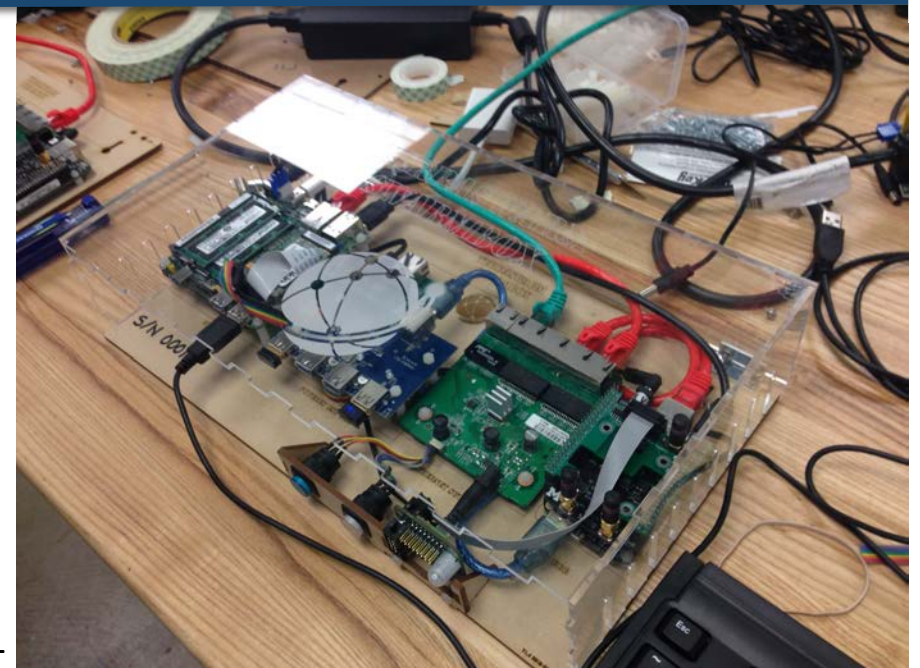




Our First Immobile: SwarmBox 0001



January 15-16, 2015, the TerraSwarm team met in the Berkeley InventionLab to create the first prototype of the next generation infrastructure, the *immobiles*.





SwarmBox-Like Products Already Appearing...

Example:

Specs listed “preliminary” on 2/25/15:



Advantech WISE-3310 “200-Node Wireless IoT Network Controller”

- Dual Cortex-A9 1.0 GHz
- Linux 3.0.35 BSP embedded
- 6LoWPAN and IEEE 802.15.4e
- AES-128 bit encryption

Advantech
industrial
computer



... and “Industrial Computers”



Total Control
Solutions
industrial PC

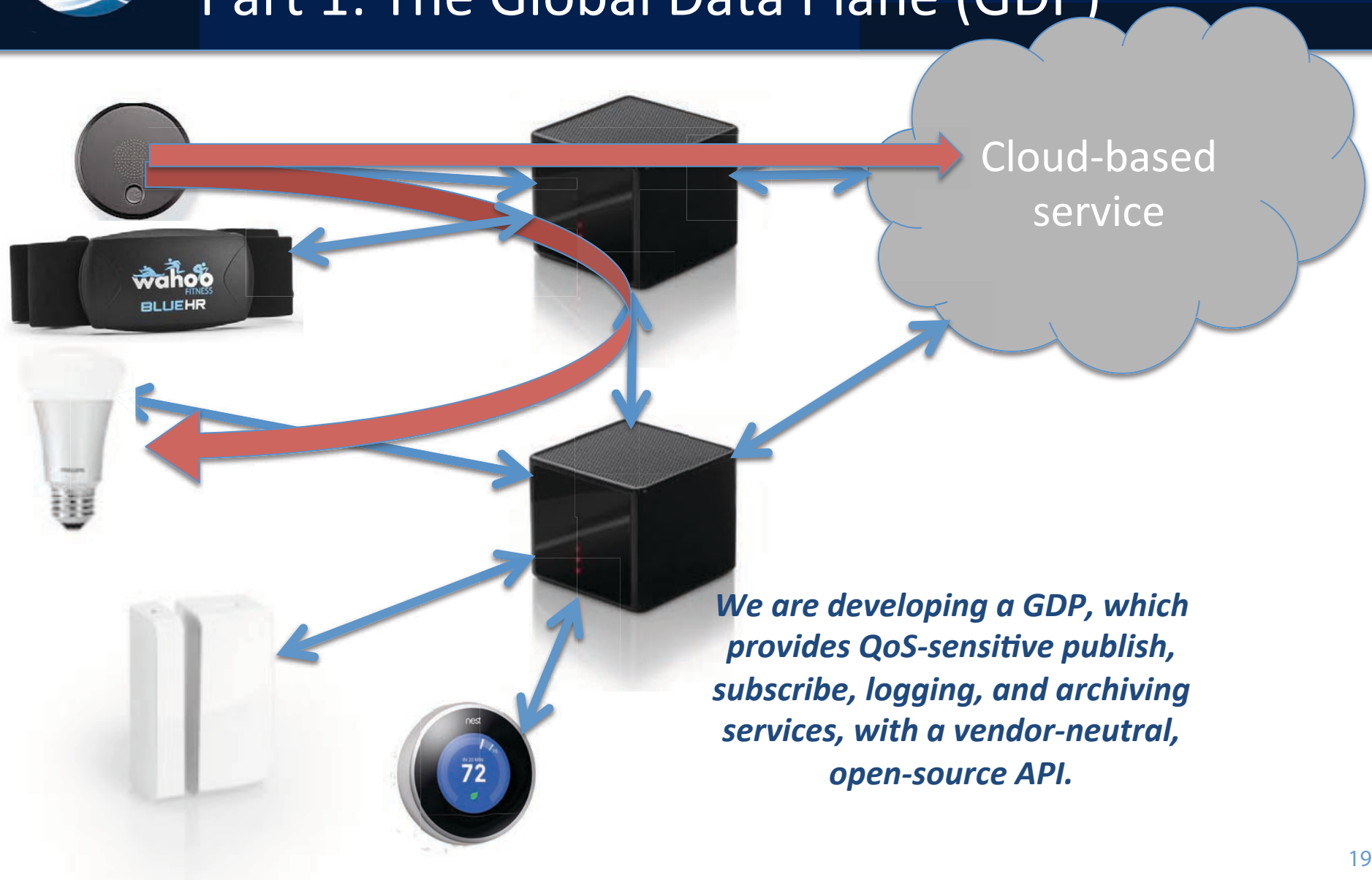


Logic Supply industrial computer



Using the Immobiles

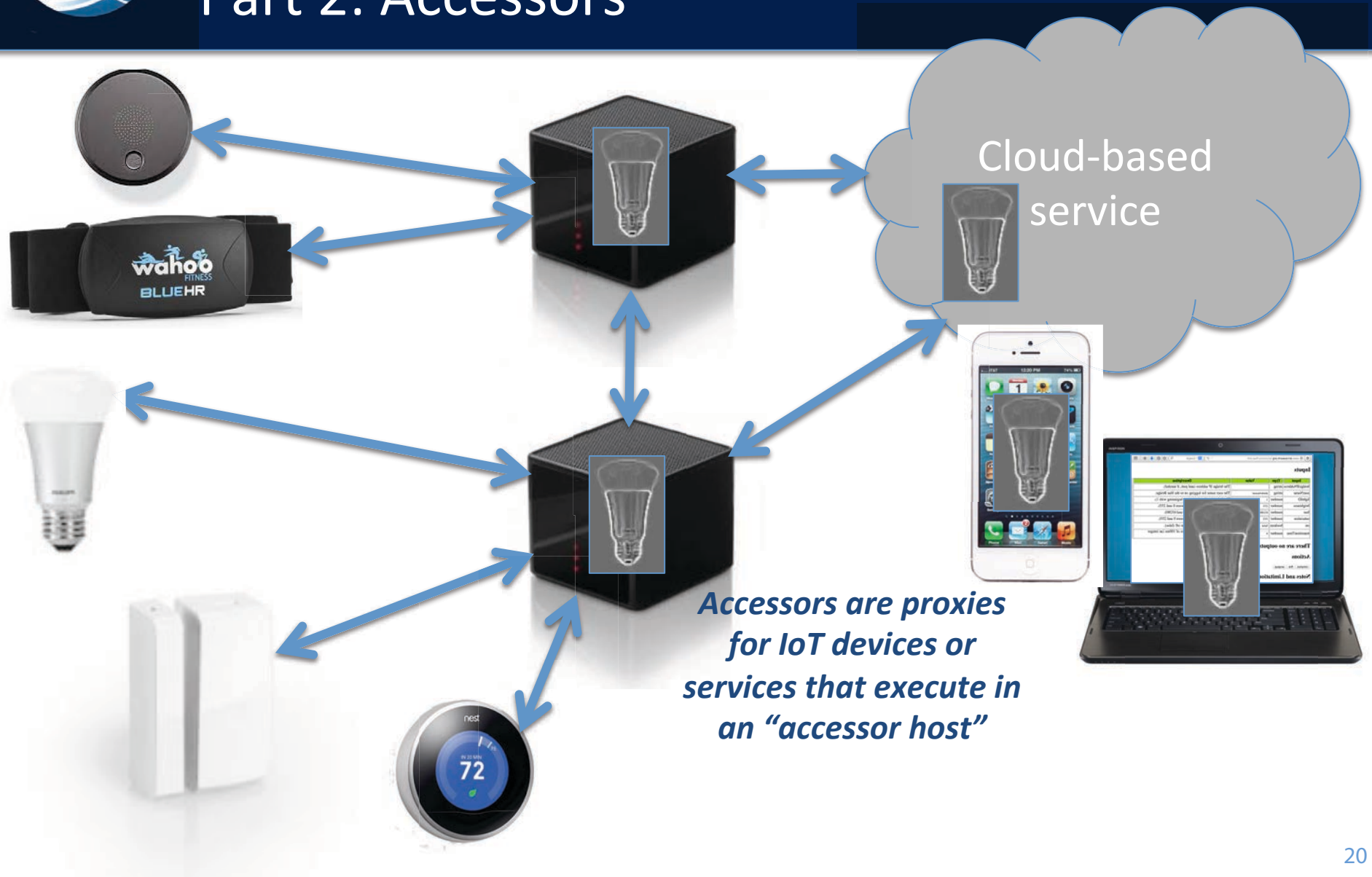
Part 1: The Global Data Plane (GDP)





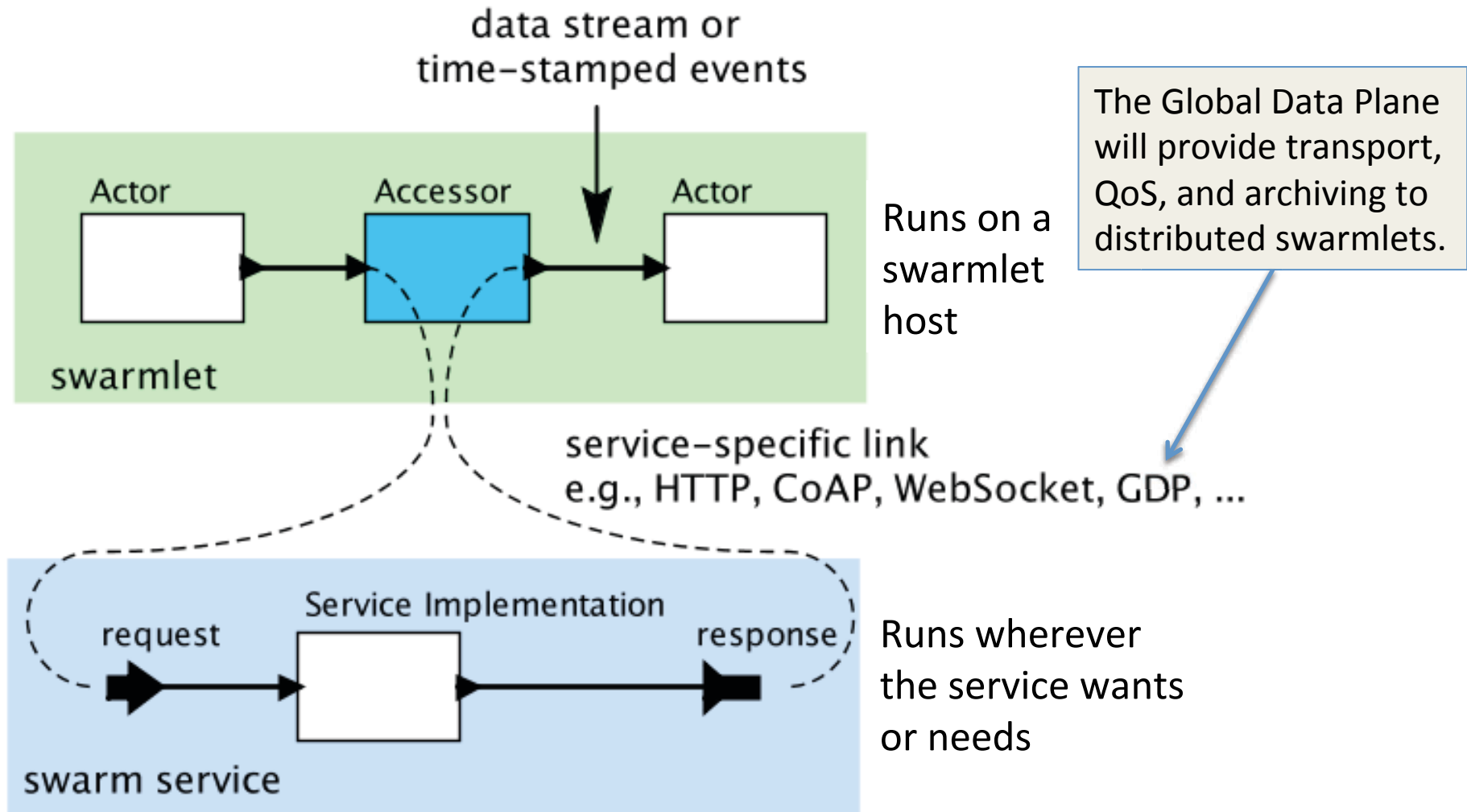
Using the Immobiles

Part 2: Accessors



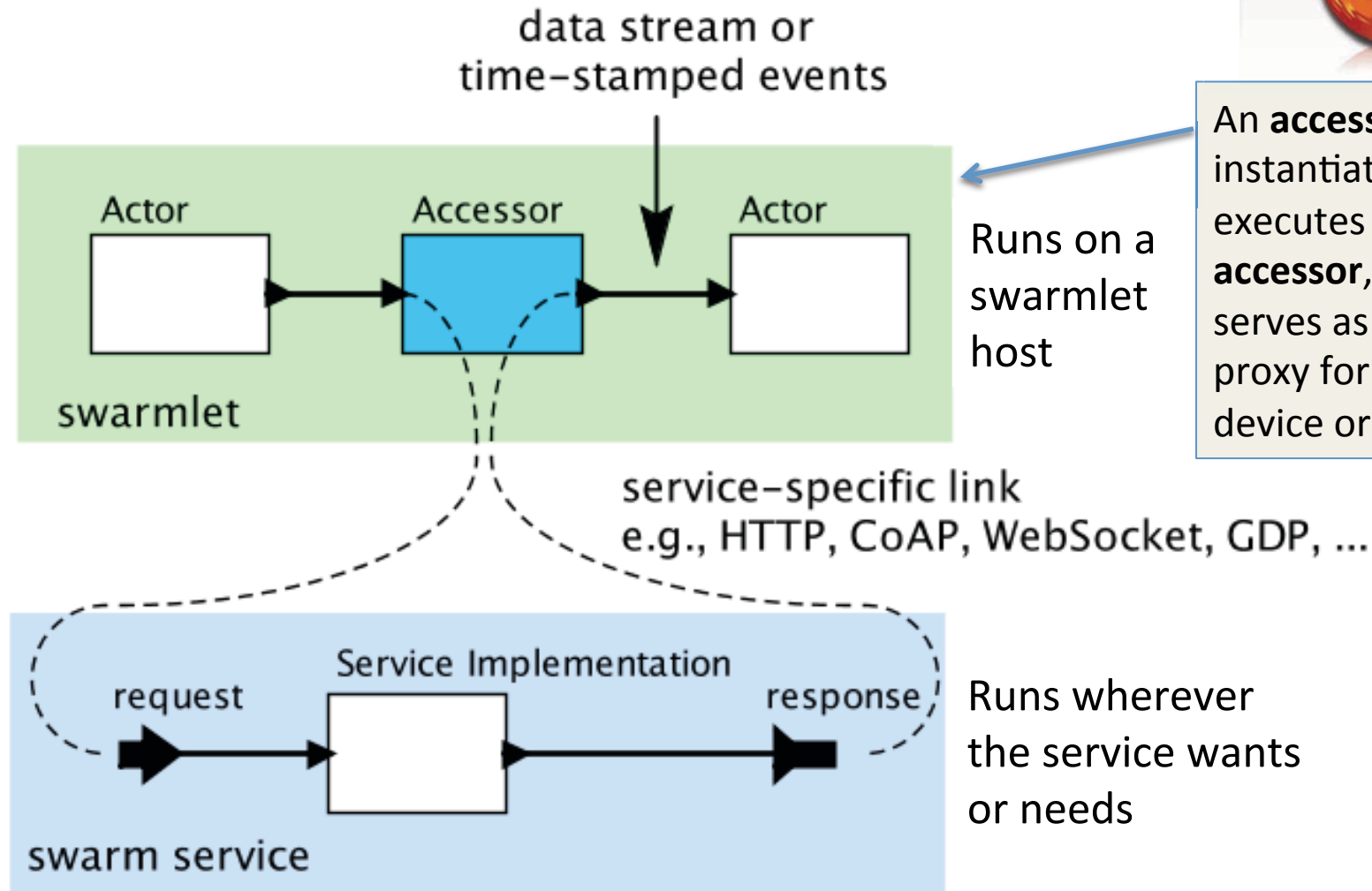


Swarmlets and Accessors





A *Swarmlet Host* is to IoT what a browser is to I



Runs on a
swarmlet
host

An **accessor host**
instantiates and
executes an
accessor, which
serves as a local
proxy for a remote
device or service

Runs wherever
the service wants
or needs



Swarmling Host Prototypes

Browsers, Node.js, Nashorn/Vert.x

← www.terraswarm.org/accessors/Hue.xml ↻ Google 🔍 ☆ 📁 ⬇️ 🏠 ☰



Inputs See <http://terraswarm.org/accessors>

Input	Type	Value	Description
bridgeIPAddress	string		The bridge IP address (and port, if needed).
userName	string	ptolemyuser	The user name for logging on to the Hue Bridge.
lightID	number	1	The light identifier (an integer beginning with 1).
brightness	number	255	The brightness (an integer between 0 and 255).
hue	number	65280	The hue (an integer between 0 and 65280).
saturation	number	255	The saturation (an integer between 0 and 255).
on	boolean	false	Whether the light is on (true) or off (false).
transitionTime	number	4	The transition time, in multiples of 100ms (an integer between 0 and 65535).

There are no outputs.

Actions

Notes and Limitations

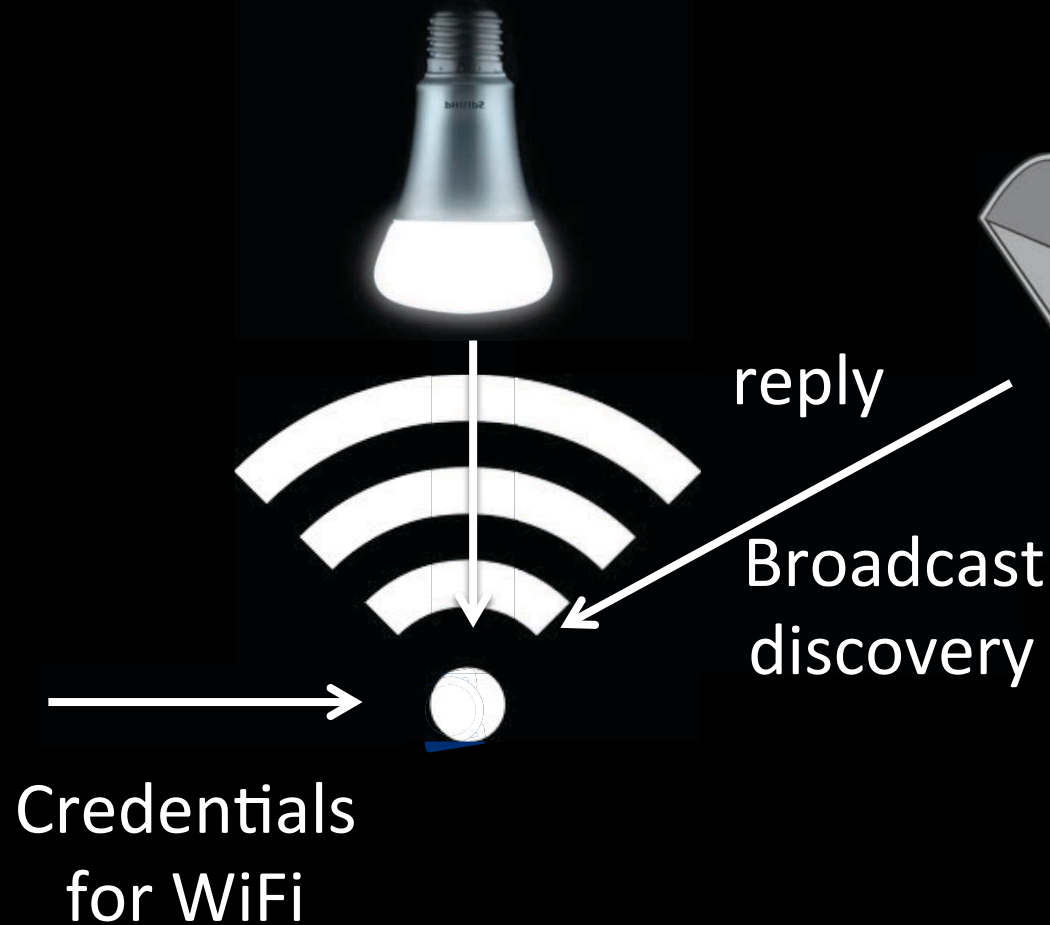


A **swarmlet host** instantiates an **accessor**, providing a client with “access” to its service or device.





Robotic Swarms - Discovery



Robot wakes up in an unknown place

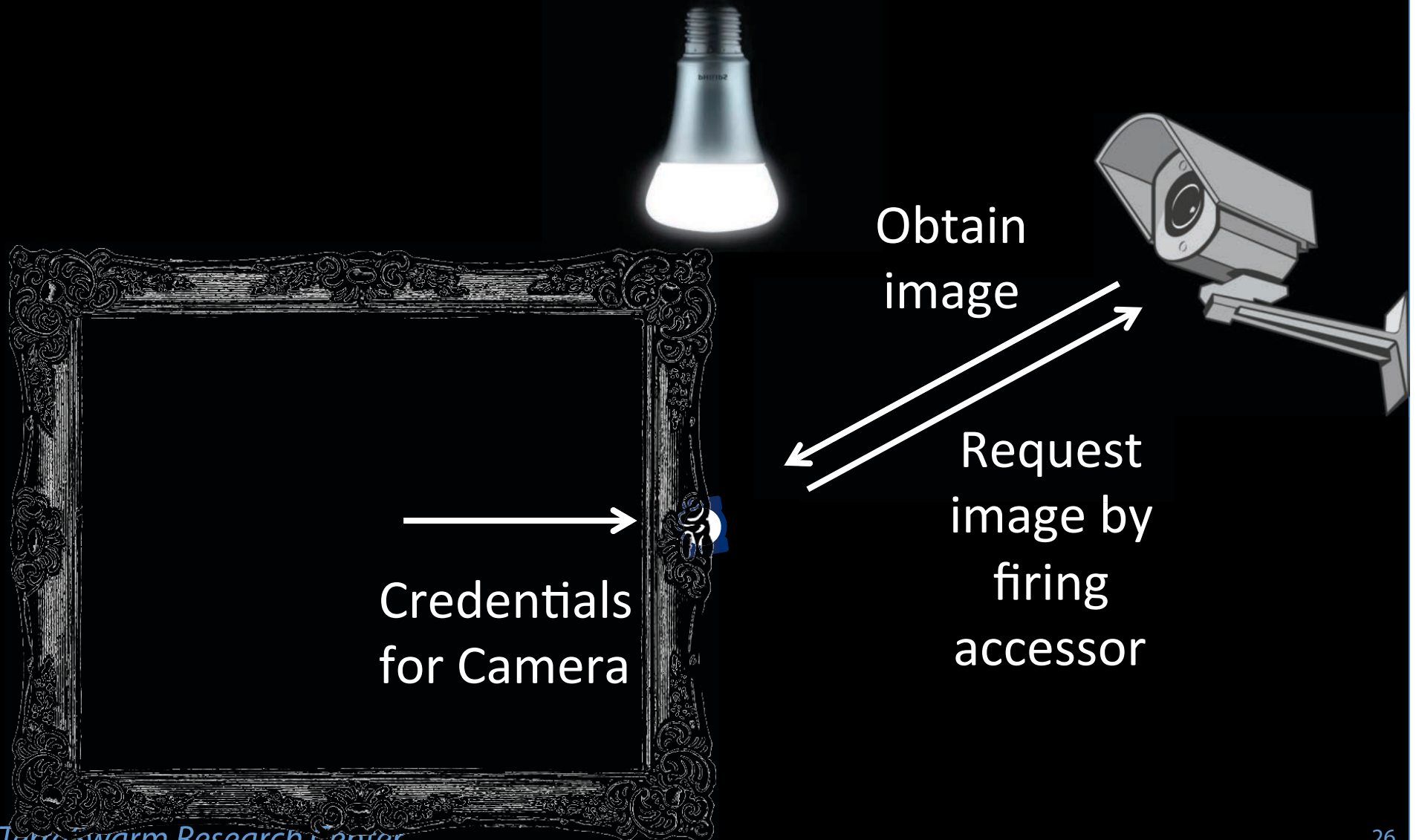


Robotic Swarms - Accessors





Robotic Swarms - Accessors

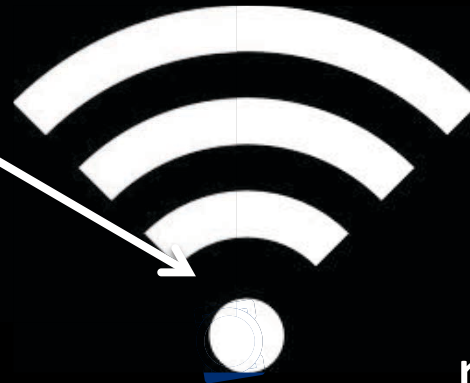




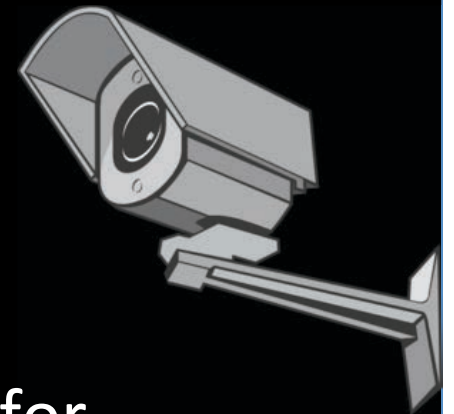
Robotic Swarms – Accessors



Reply with
accessor

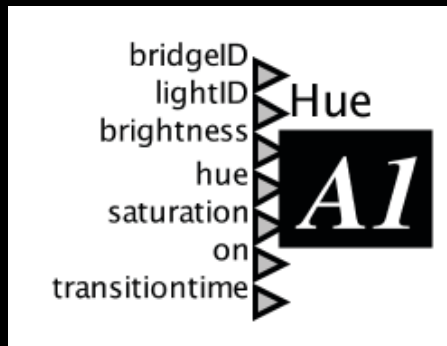


Search for
accessors
matching light
interface





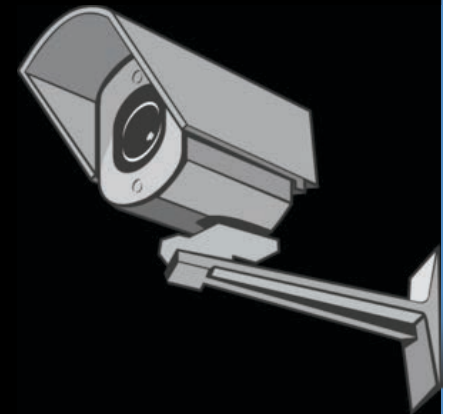
Robotic Swarms - Accessors



Turn on
the light
by firing
accessor

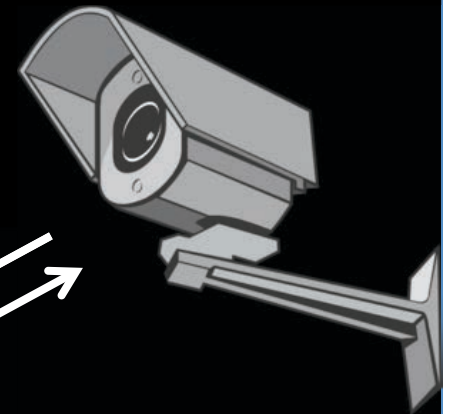


Light
goes
on



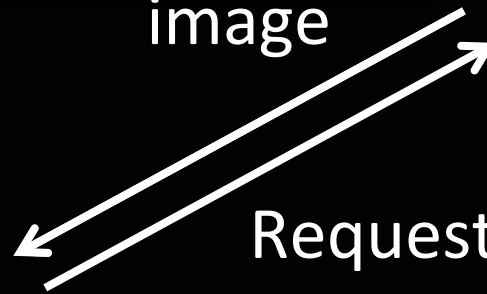


Robotic Swarms - Accessors



Obtain
image

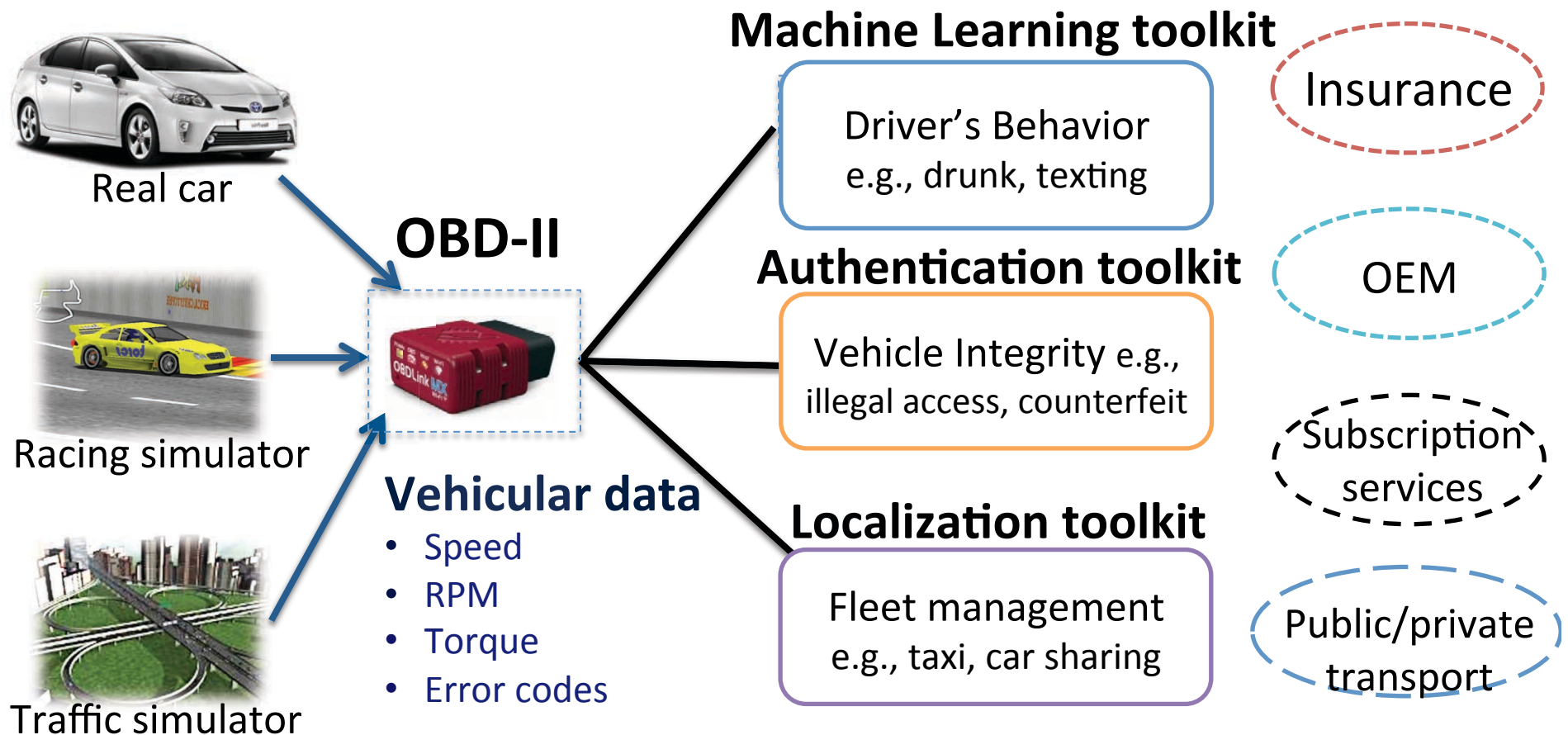
Request
image by
firing
accessor





Automotive Swarmlets

Applying the accessor architecture

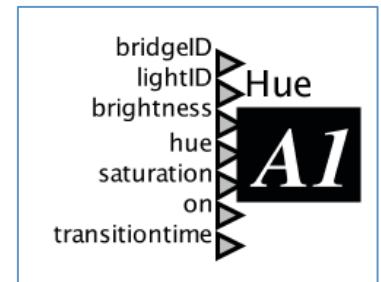


We are testing the accessor architecture on automotive application that use data from the On Board Diagnostics bus (OBD-II)

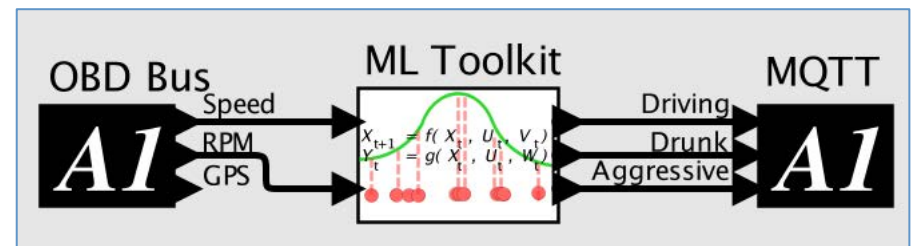


Some of the Questions Being Addressed in TerraSwarm Research

- Interface
 - Subtyping?
 - Ontologies?
 - Contracts?
 - Discovery?
- Component
 - Languages?
 - Libraries?
 - Sandboxing?
 - Authentication?
 - Error handling?
- Composition
 - What MoCs?
 - Callbacks vs. actors?
 - Time stamping?
 - Always live swarmlets?
 - Graphical editing?



```
function fire() {  
  var command = '{"on":false,';  
  if (get(on) === "true") {  
    command = '{"on":true,';  
  } ...  
}
```





Questions?

