

MoTif:

The Modular Timed Graph Transformation Language

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OVERVIEW

□ Introduction

- Context
- Existing Programmed Graph Rewriting Systems
- Graph transformation in AToM³'s by example

□ The Modular Timed Graph Transformation (MoTif) system

- Overview of the DEVS formalism
- Meta-model, Code generation, Rule compilation & Usage
- Mimic AToM³ & beyond

□ Conclusion and Future Work

CONTEXT

- **Meta-Model + Model Transformation + ...**
- **Model Transformation \Rightarrow Graph Transformation**
- **Types of rule-based Graph Transformations [1]**
 - **Unordered Graph Rewriting: non-deterministic, run till no more rules apply**
 - **Ordered Graph Rewriting: explicit (partial) ordering of rules**
 - **Event-driven Graph Rewriting: external ordering of rules**
- **Ordered Graph Rewriting can be generalized to Programmed Graph Rewriting**

[1] Blostein D., Fahmy H., Grbavec A., Practical Use of Graph Rewriting, Technical Report No. 95-373, 1995.

IN THE CONTEXT

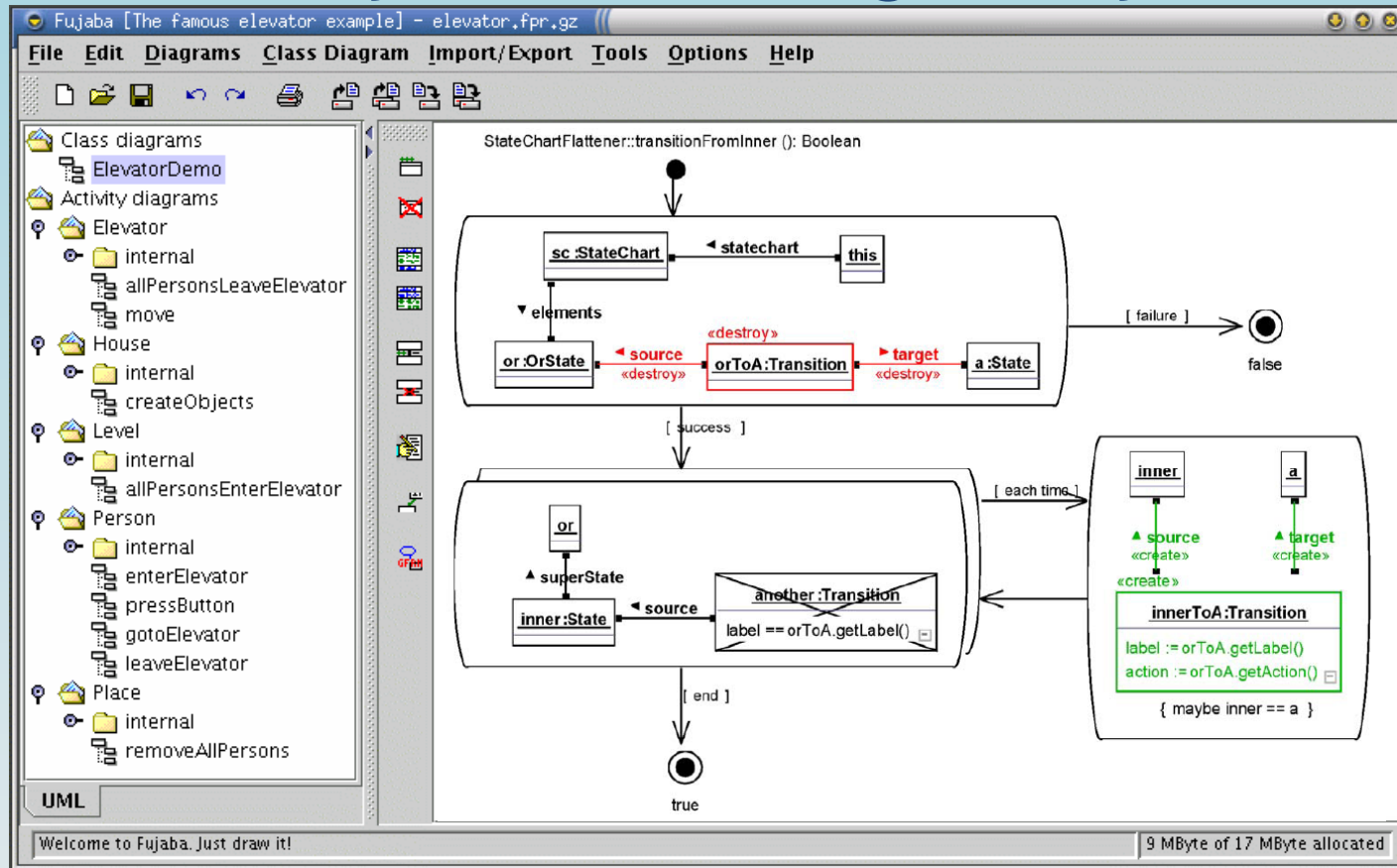
Programmed Graph Rewriting wish list

- **Cleanly separate**
 1. **Transformation entities**
 2. **Control flow, structure, hierarchy**
- **Graph transformation control flow primitives [1]**
 - **Flow: Sequencing, Branching, Looping**
 - **Structure: Parallelism, Hierarchy**
 - **Essence: Time, Backtracking**

1. Eugene Syriani and Hans Vangheluwe: Programmed Graph Rewriting with DEVS. In: Manfred Nagl and Andy Schürr (eds.), *International Conference on Applications of Graph Transformations with Industrial Relevance (AGTIVE 2007)*. Lecture Notes in Computer Science. Springer-Verlag, Kassel (2007).

EXISTING PROGRAMMED GRAPH REWRITING SYSTEMS

From UML to JAVA And Back Again (FUJABA) [4,5]

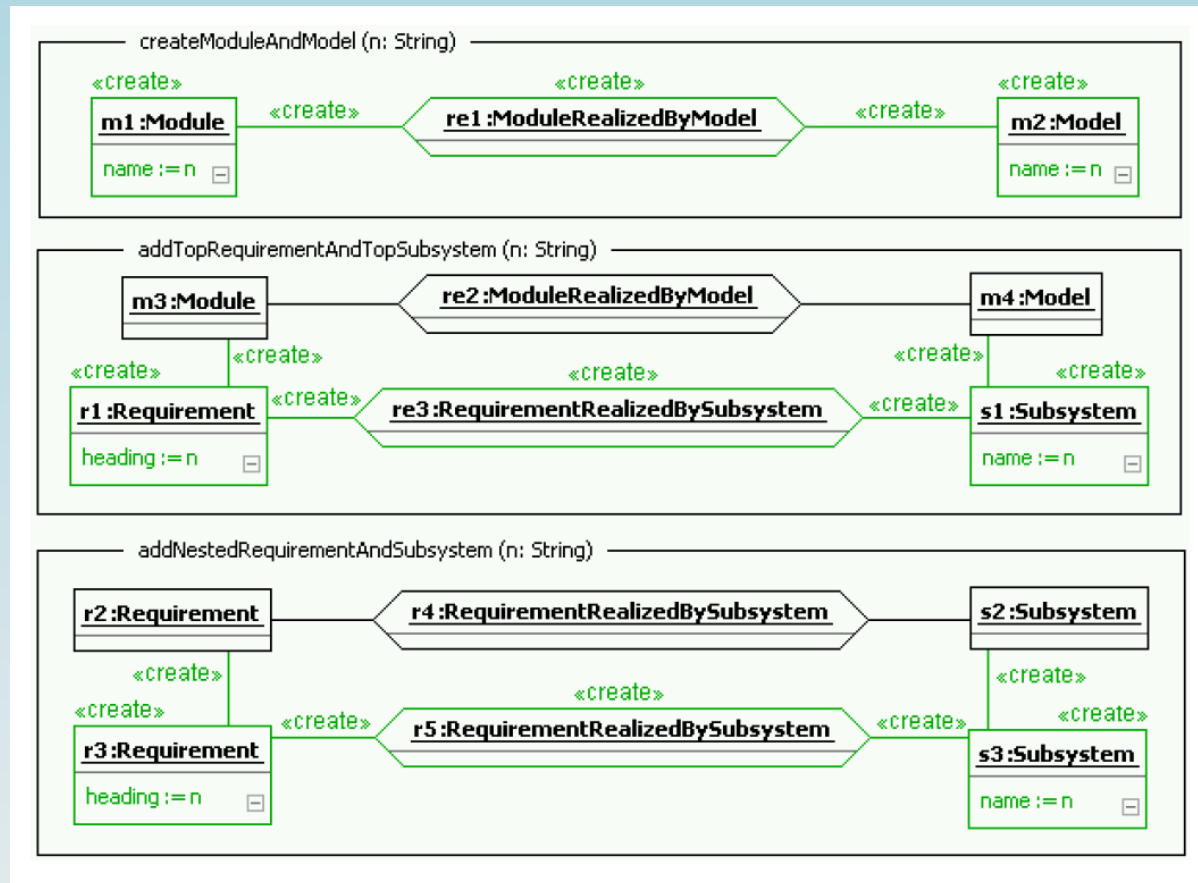


[4] Nickel U., Niere J., Zündorf A. Tool demonstration: The FUJABA environment, *Proceedings of ICSE*, ACM Press, pp. 742-745, 2000.

[5] Fischer T. et al. Story Diagrams: an new graph grammar language based on UML and JAVA, *Proceedings of ESEC*, LNCS 1764, pp. 1-21, 2000.

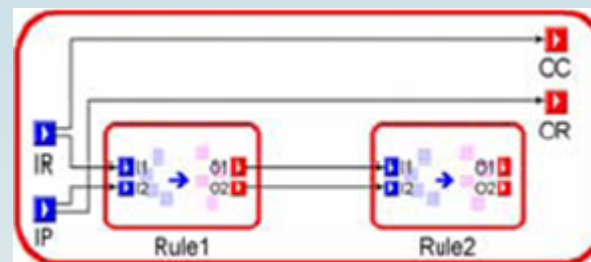
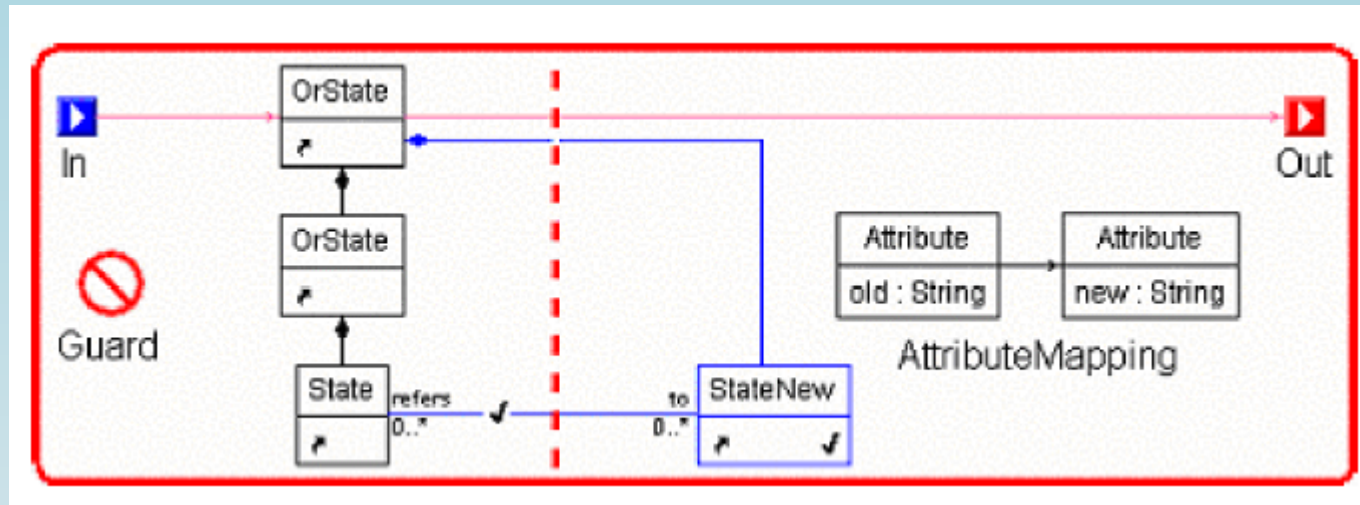
EXISTING PROGRAMMED GRAPH REWRITING SYSTEMS

MOFLON [6]



EXISTING PROGRAMMED GRAPH REWRITING SYSTEMS

Graph Rewriting and Transformation (GReAT) [7,8,9]



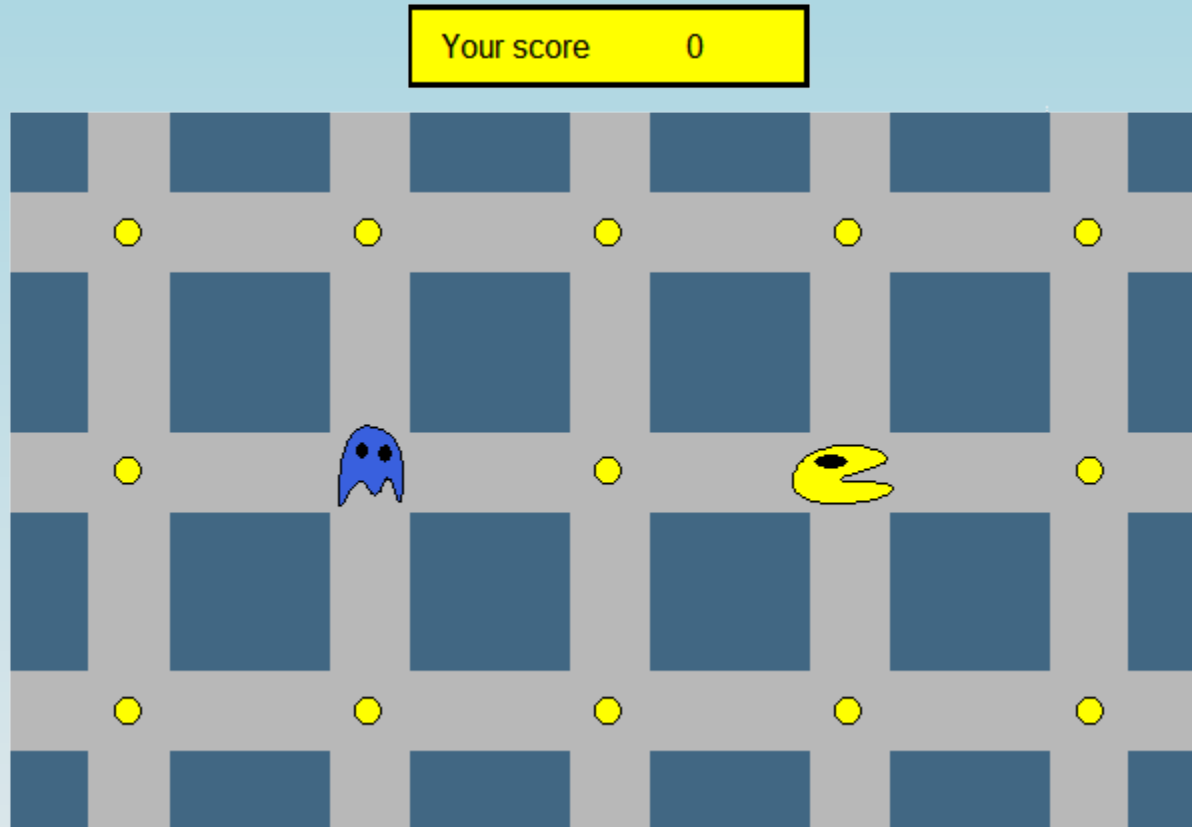
[7] Vizhanyo A. et al., Towards generation of high-performance transformations, *Proceedings of GPCE*, LNCS 3286 pp. 298-396, 2004.

[8] Agrawal A., Metamodel based model transformation language, *Proceedings of OOPSLA*, ACM Press pp. 386-397, 2003.

[9] Agrawal A., The design of a language for model transformations, *SoSym 5*, pp. 261-288, 2005.

RUNNING EXAMPLE WITH AToM³ [12]

Simplified PacMan formalism [13]

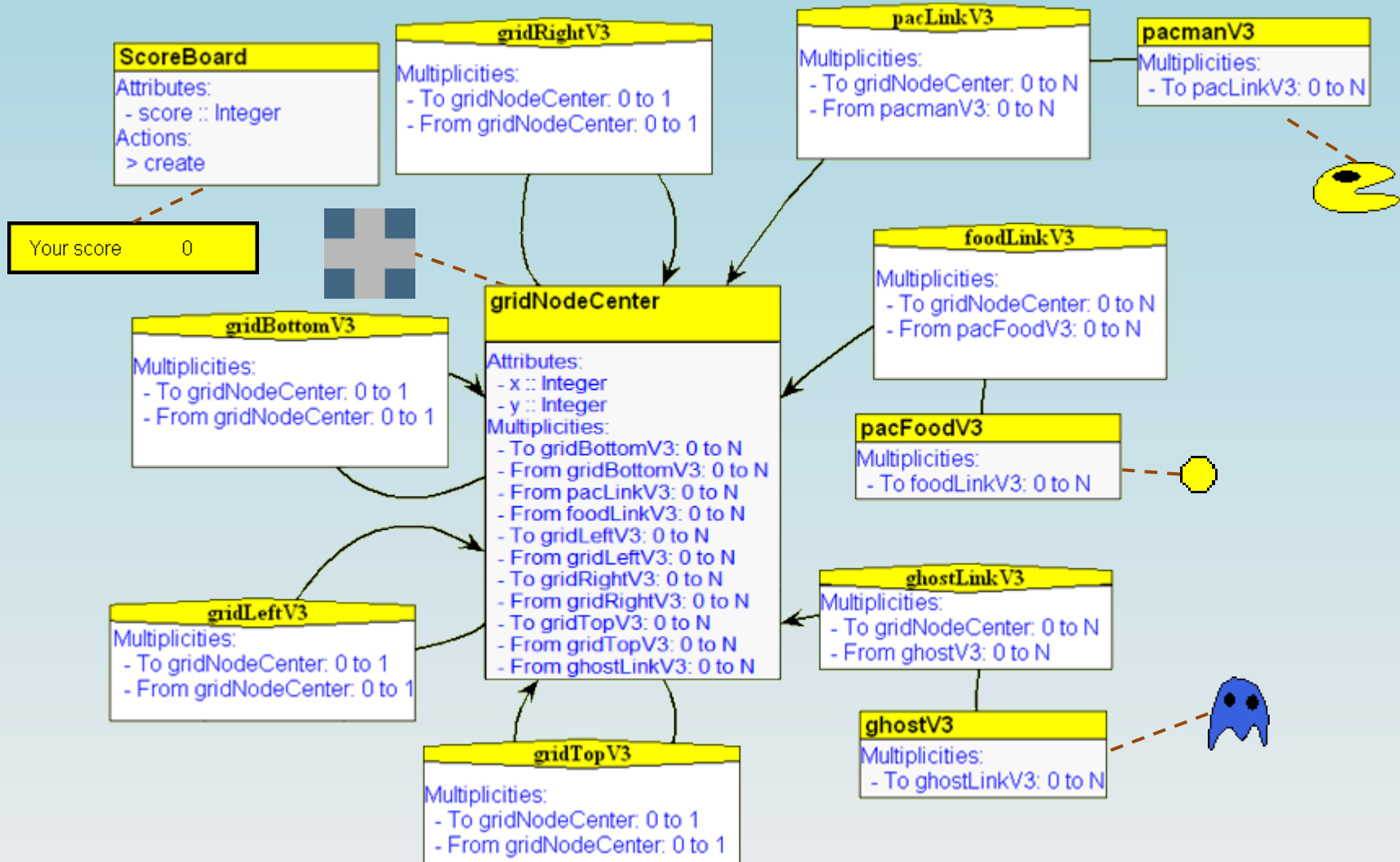


[12] de Lara J., Vangheluwe H., AToM³: A tool for multi-formalism and meta-modelling, *LNCS* (2002), 174-188

[13] Heckel R., Graph Transformation in a nutshell, *ENTCS* (2006), 187-198

RUNNING EXAMPLE WITH ATOM³

Build the Meta-Model of the PacMan formalism






RUNNING EXAMPLE WITH ATOM³

Model the Graph Transformation

AToM3 v0.3 using: pacManV3 + TransformationToolbar

pacManV3 TransformationToolbar

New Edit New Help   Your score  EDIT LOAD SAVE GEN EXEC DOG ? CGEN

7% Editing GraphGrammarEdit

WARNING: Name must use Python variable syntax

Name: pacGrammarMoTif

InitialAction: Enabled?

Rules:

- New: ghostMoveRight 3
- Edit: **pacMoveUp 3**
- Delete: pacMoveDown 3
- pacMoveLeft 3
- pacMoveRight 3

FinalAction: Enabled?

Load GG

Save GG

Generate latex document from GG

Generate GG code

Execute GG code

OK Cancel

7% Editing GGRuleEdit

Name (Python variable syntax required): pacMoveUp

Order: 1

TimeDelay: 2

Subtypes Matching (if rule matches A then it also matches B if B has all attributes in A):

Test Rule:

Condition:

Action:

Enabled? Enabled?

pacManV3 pacManV3 pacManV3

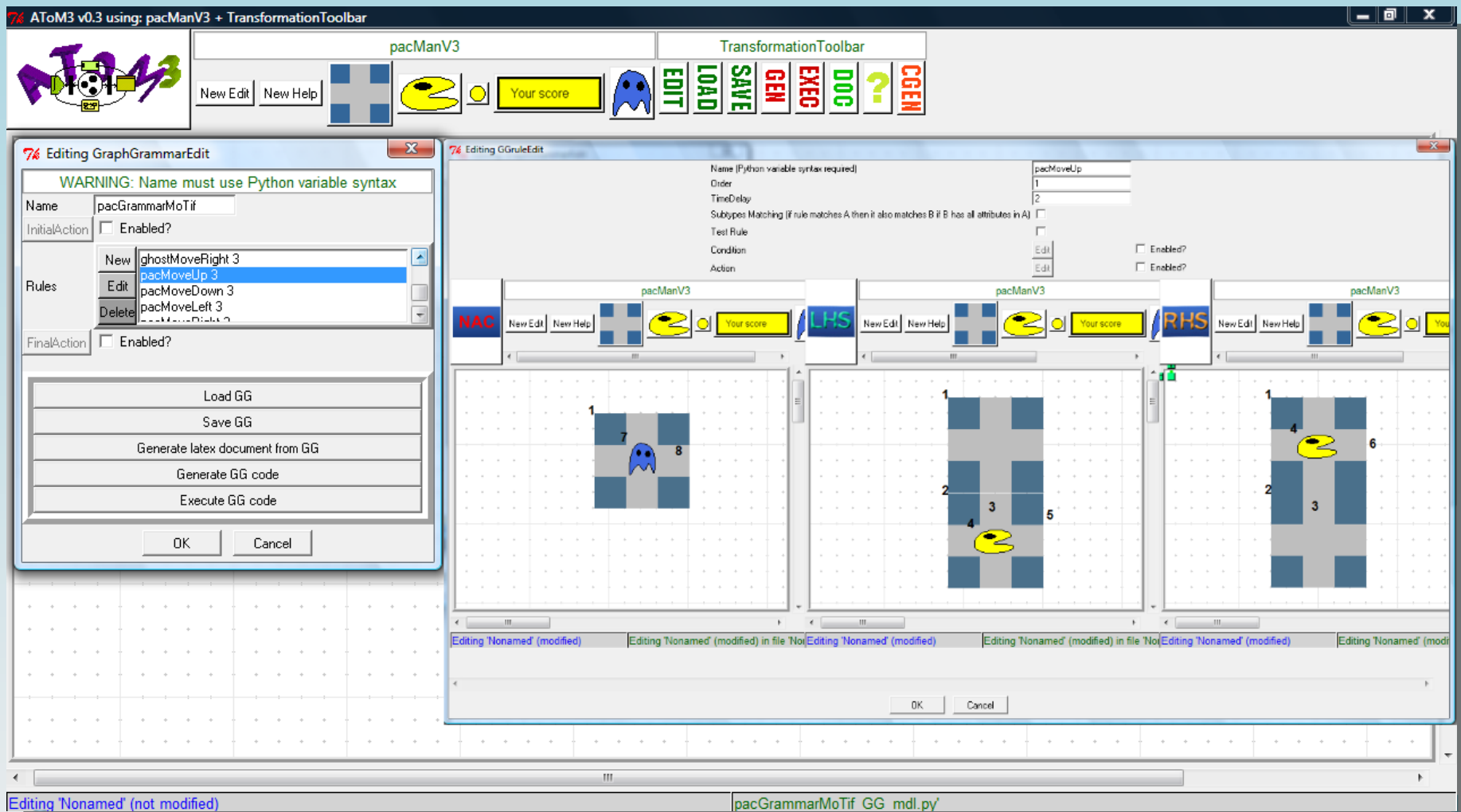
LHS

RHS

Editing 'Nonamed' (modified) Editing 'Nonamed' (modified) in file 'No' Editing 'Nonamed' (modified) in file 'No' Editing 'Nonamed' (modified) in file 'No' Editing 'Nonamed' (modified) in file 'No'

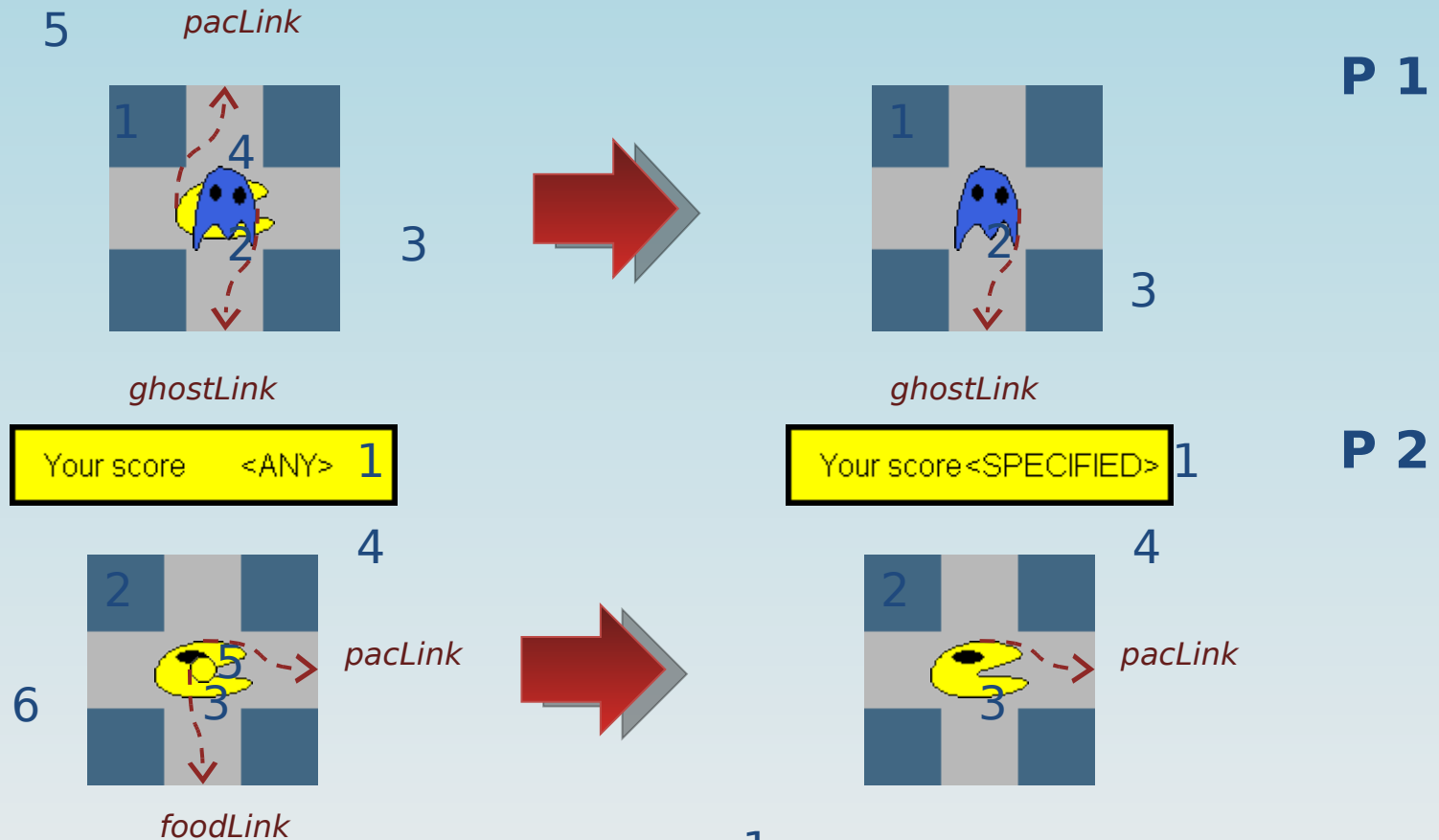
OK Cancel

Editing 'Nonamed' (not modified) pacGrammarMoTif GG mdl.py



RUNNING EXAMPLE WITH ATOM³

Graph Transformation Rules

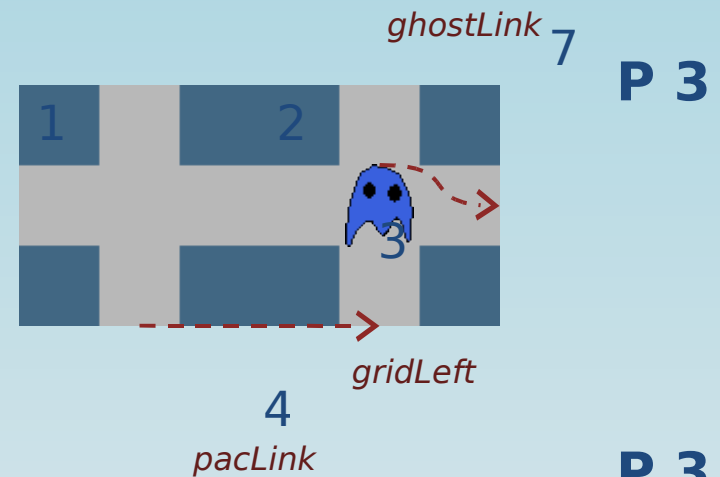
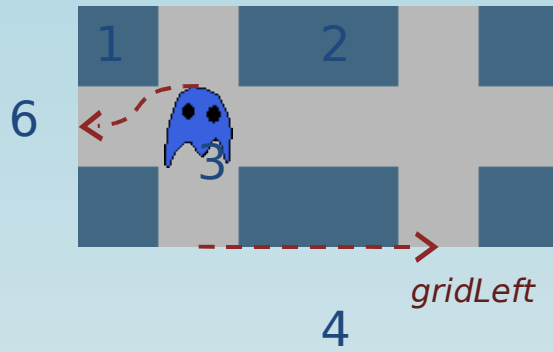


1: `return self.LHS.nodeWithLabel(1).score + 1`

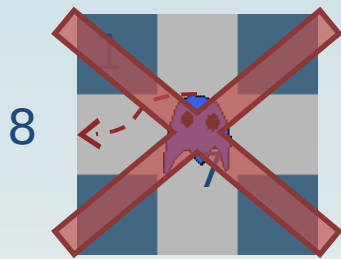
RUNNING EXAMPLE WITH ATOM³

Graph Transformation Rules

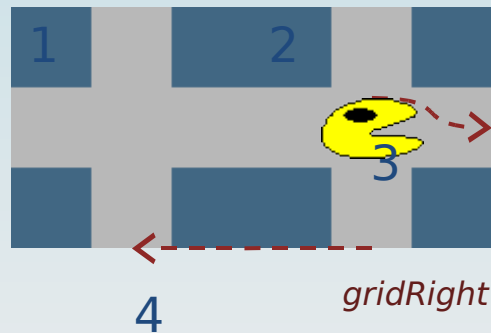
ghostLink



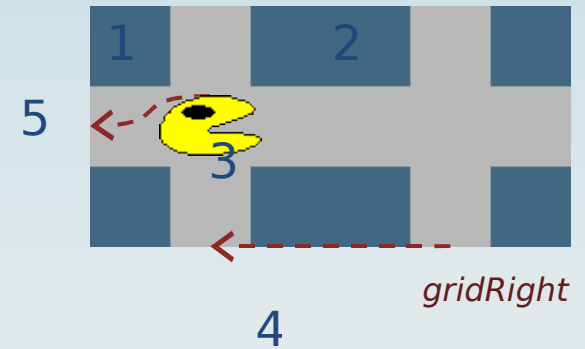
ghostLink



pacLink 6

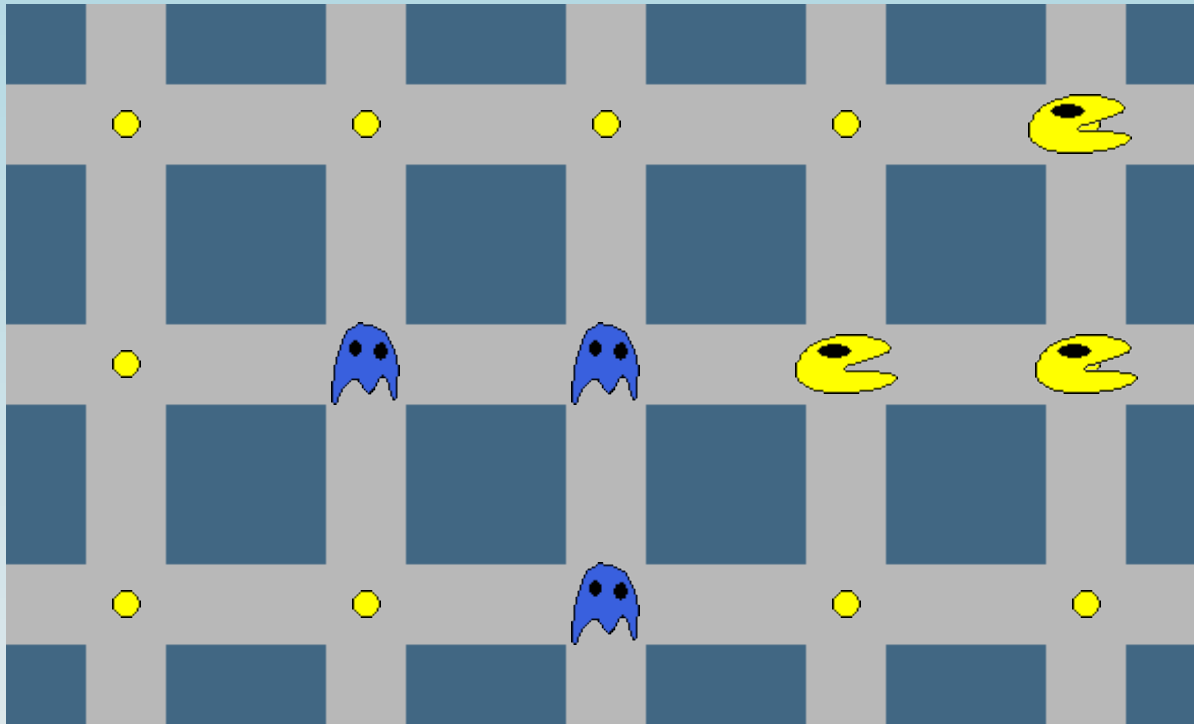


pacLink **P 3**



RUNNING EXAMPLE WITH ATOM³

Your score 2



RUNNING EXAMPLE WITH ATOM³

- **Capture execution trace:**
 - **Keep log of used rules**

```
Rules Used
>1: PacManUp
>2: Eat
>3: PacManLeft
>4: Eat
>5: PacManDown
>6: Eat
>7: PacManDown
>8: Eat
>9: GhostRight
>10: GhostDown
>11: Kill
>12: GhostUp
>13: GhostLeft
>14: GhostUp
>15: GhostLeft
>16: GhostRight
```

OVERVIEW OF THE DEVS FORMALISM

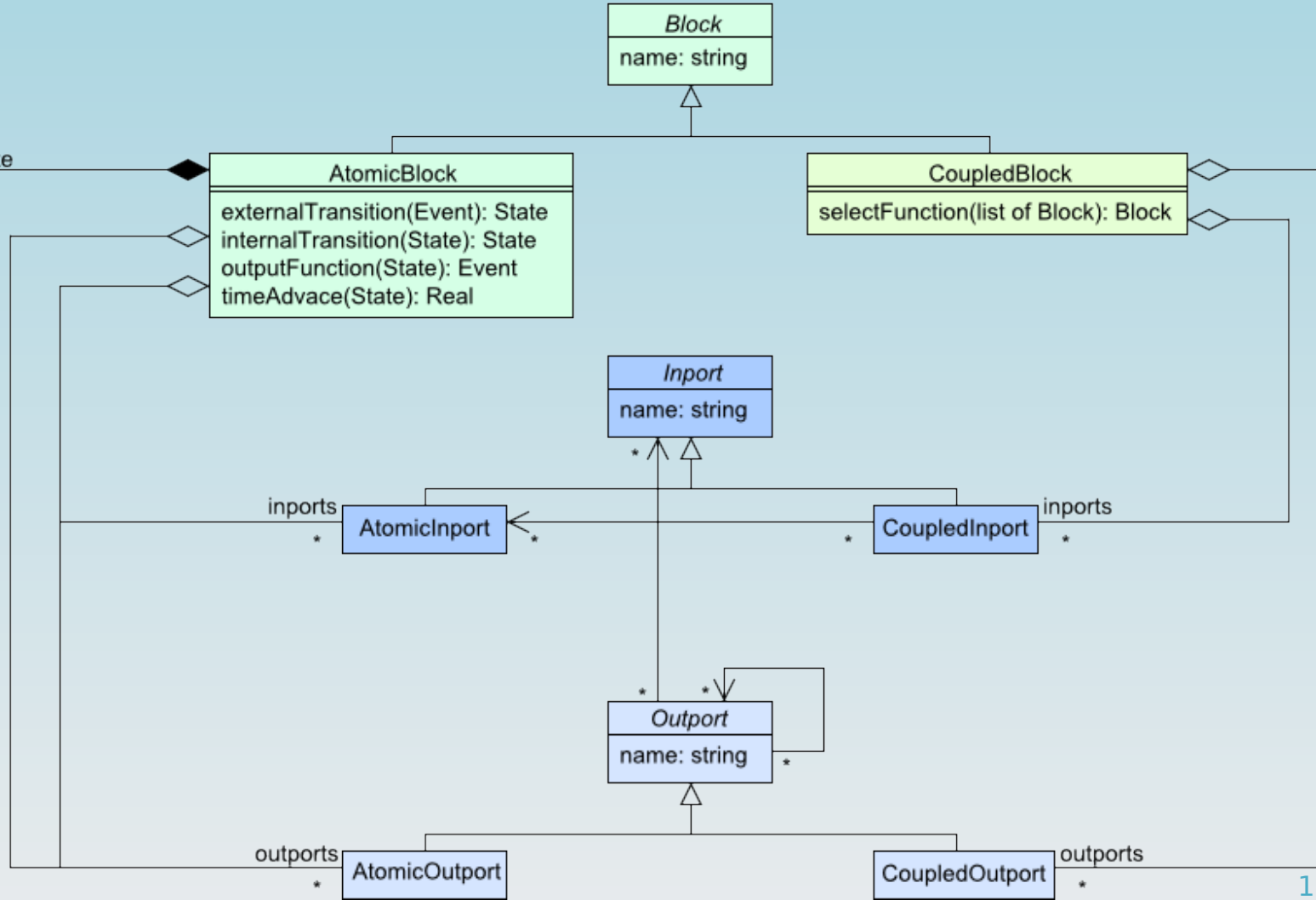
- **Bernard Zeigler, late '70s**
- **The Discrete Event System Specification [1] (DEVS) formalism**
- **DEVS is compositional**
- **Foundation for compositional modelling and simulation of discrete event systems**
- **DEVS:**
 - **Blocks**
 - **Ports**
 - **Events**
- **Semantics: Parallel composition of blocks/models**

OVERVIEW OF THE DEVS FORMALISM

Time
time: Real

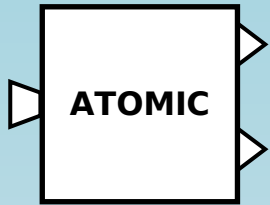
Event

State
declarations: string
functions: string



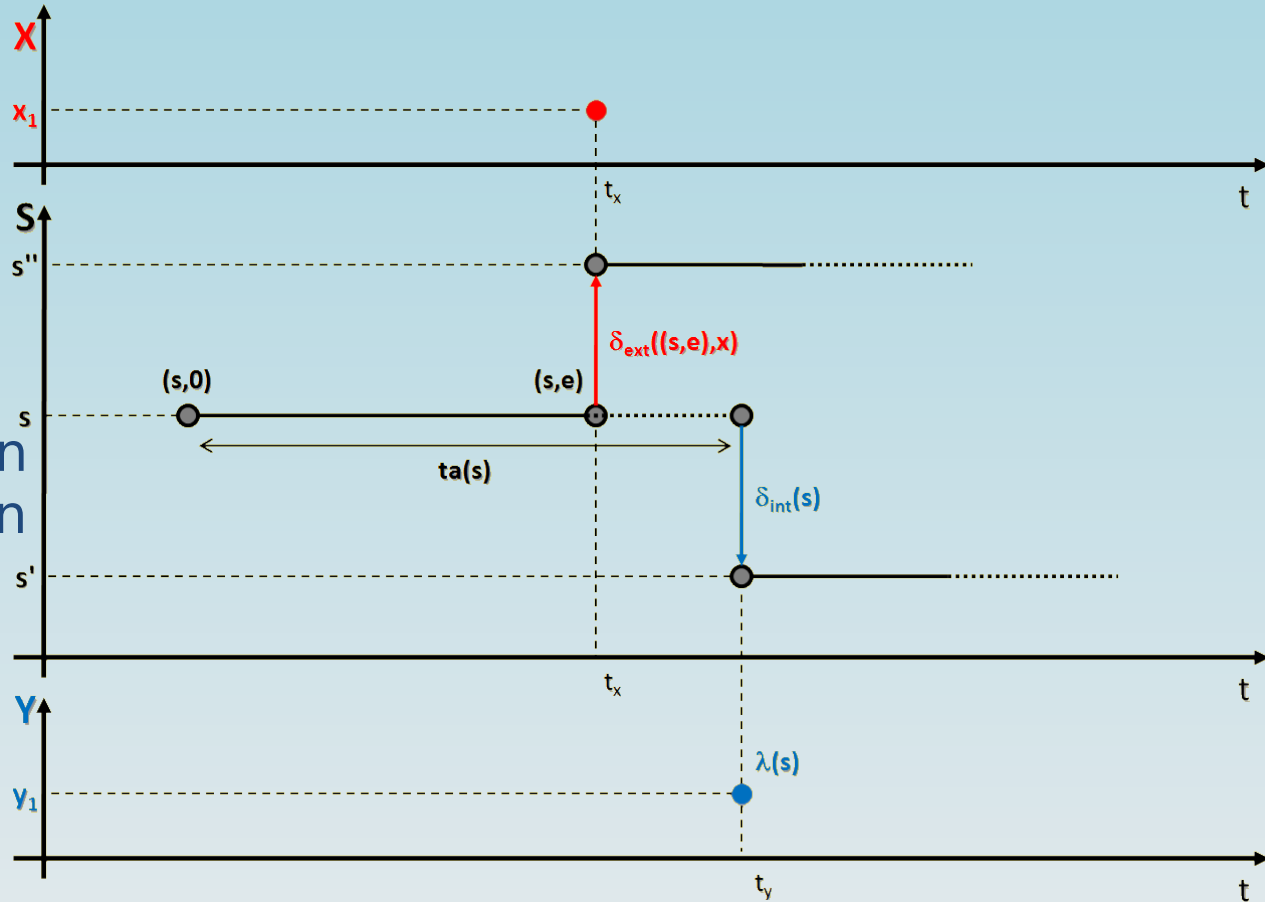
- **Block:**
 - Atomic
 - Coupled
- **Port:**
 - Inport
 - Output
- **Event**
- **Global time**

OVERVIEW OF THE DEVS FORMALISM



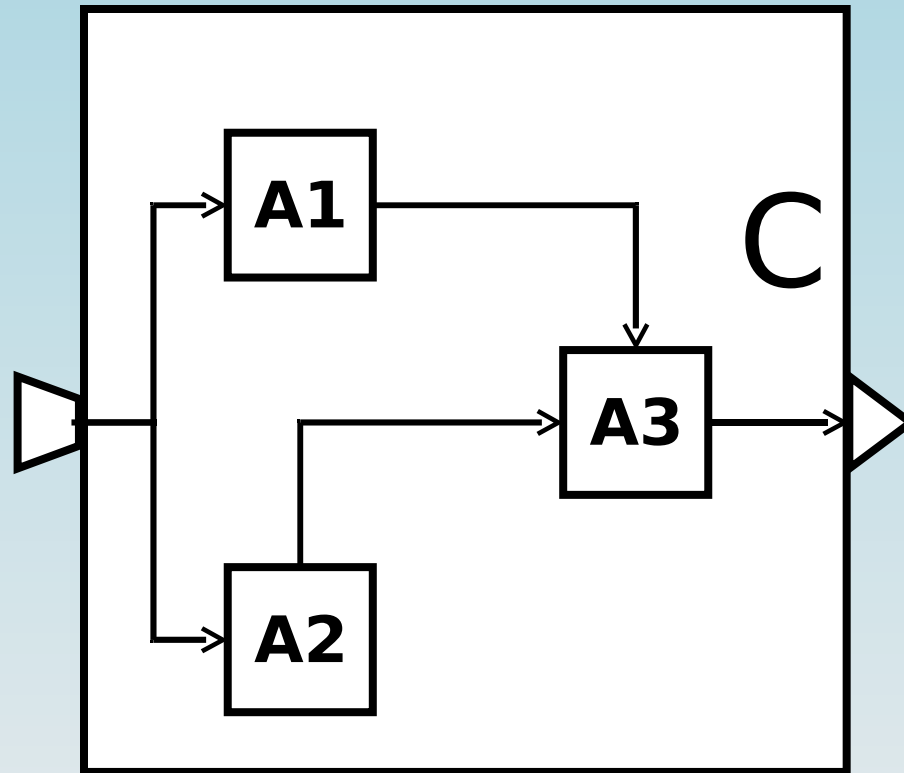
Atomic DEVS:

- Time Advance
- Output Function
- Internal Transition
- External Transition



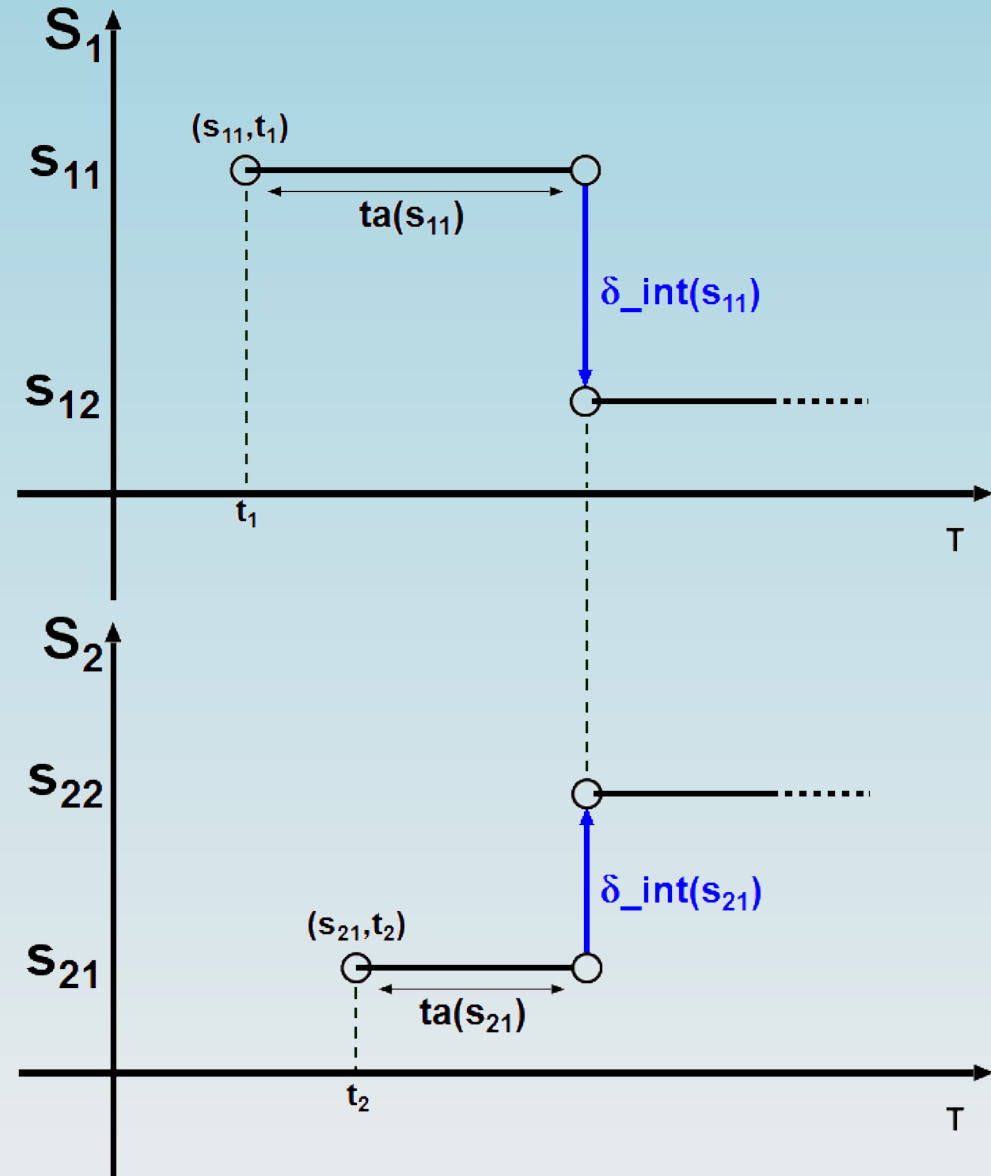
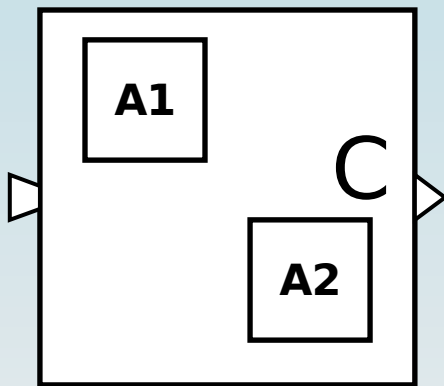
OVERVIEW OF THE DEVS FORMALISM

Coupled DEVS



OVERVIEW OF THE DEVS FORMALISM

Coupled DEVS: – Select Function



OVERVIEW OF THE DEVS FORMALISM

Our implementation: pythonDEVS

```
class AExample(AtomicDEVS):  
    def __init__(self):  
        self.state = ExampleState()  
  
        self.in = self.addInPort()  
        self.out = self.addOutPort()
```

```
    def extTransition(self):  
        X = self.peak(self.in)  
        ...  
        return self.state
```

```
    def intTransition(self):  
        ...  
        return self.state
```

```
    def outputFnc(self):  
        ...  
        self.poke(self.out, Y)
```

```
    def timeAdvance(self):  
        return 1
```

```
class CExample(CoupledDEVS):  
    def __init__(self):  
        self.M1 = self.addSubModel(Example())  
        self.M2 = self.addSubModel(Example())  
        self.connectPorts(self.M1.out, self.M2.in)
```

```
    def select(self, immList):  
        return immList[0]
```

MoTif

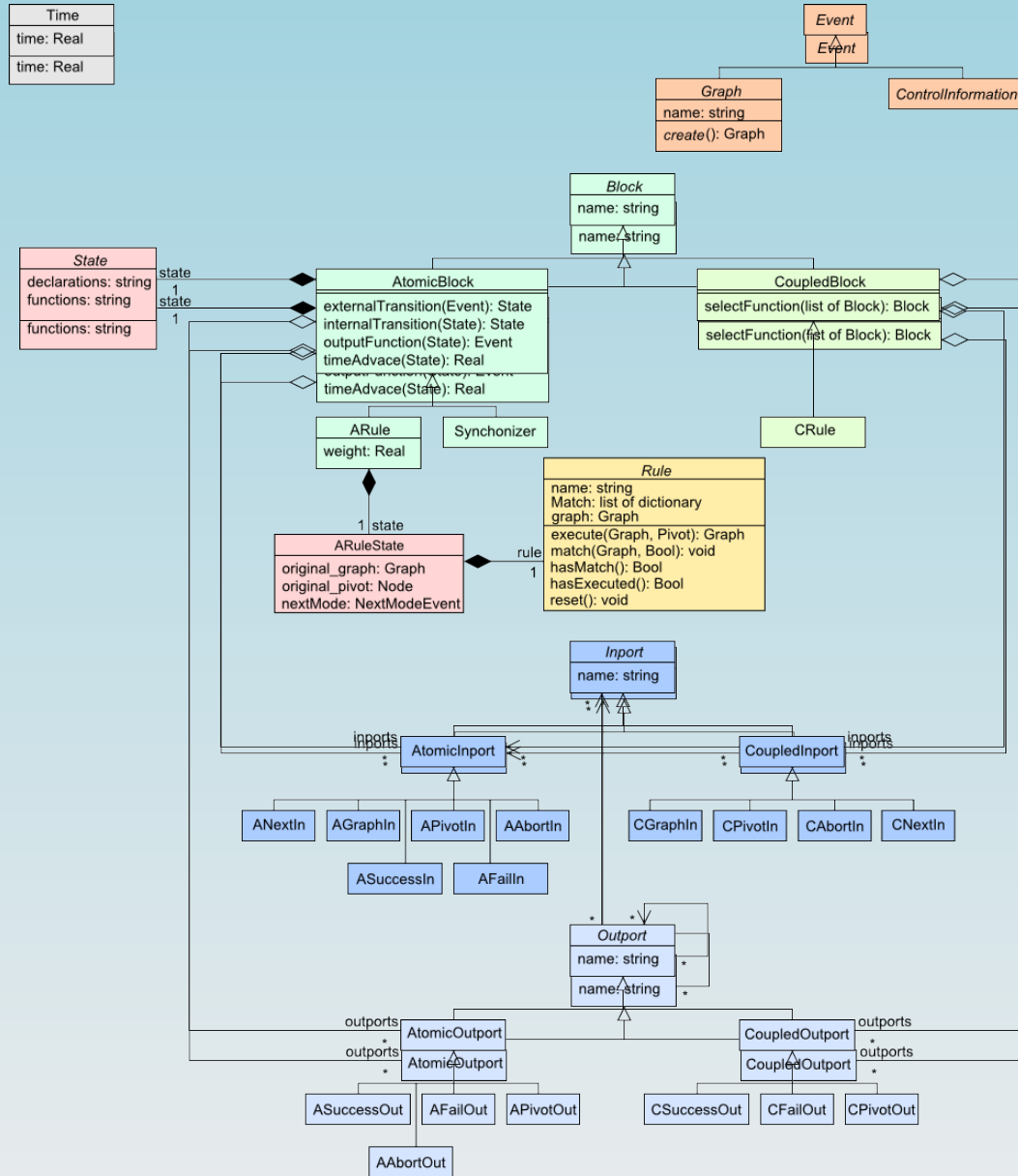
- **DEVS blocks**

- **Atomic block: encapsulate the graph rewriting rule**
- **Coupled block: encapsulate a structured collection of rules (graph transformation)**

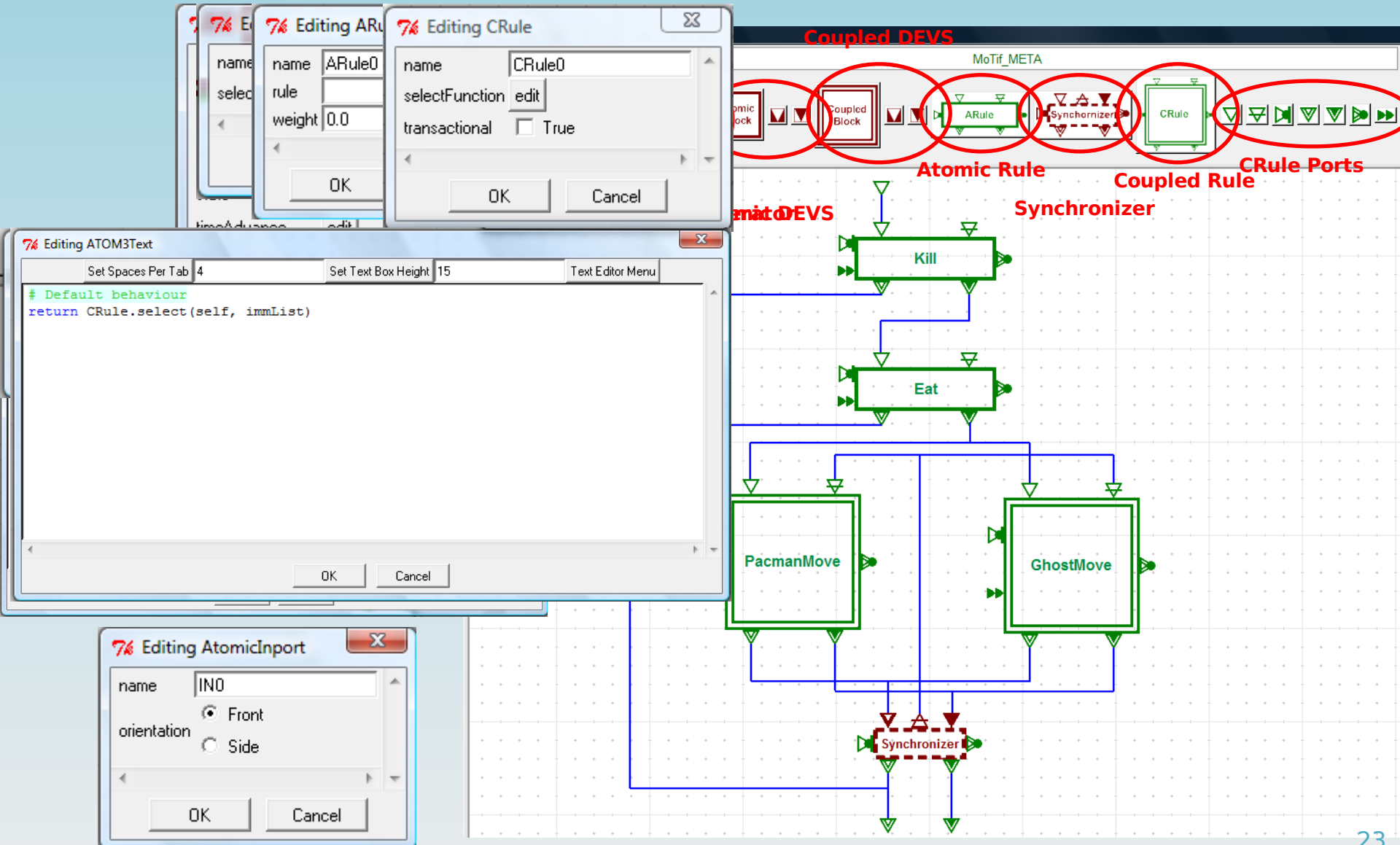
- **Events**

- **Inport: receive the host graph**
- **Outport(s): send the transformed graph**

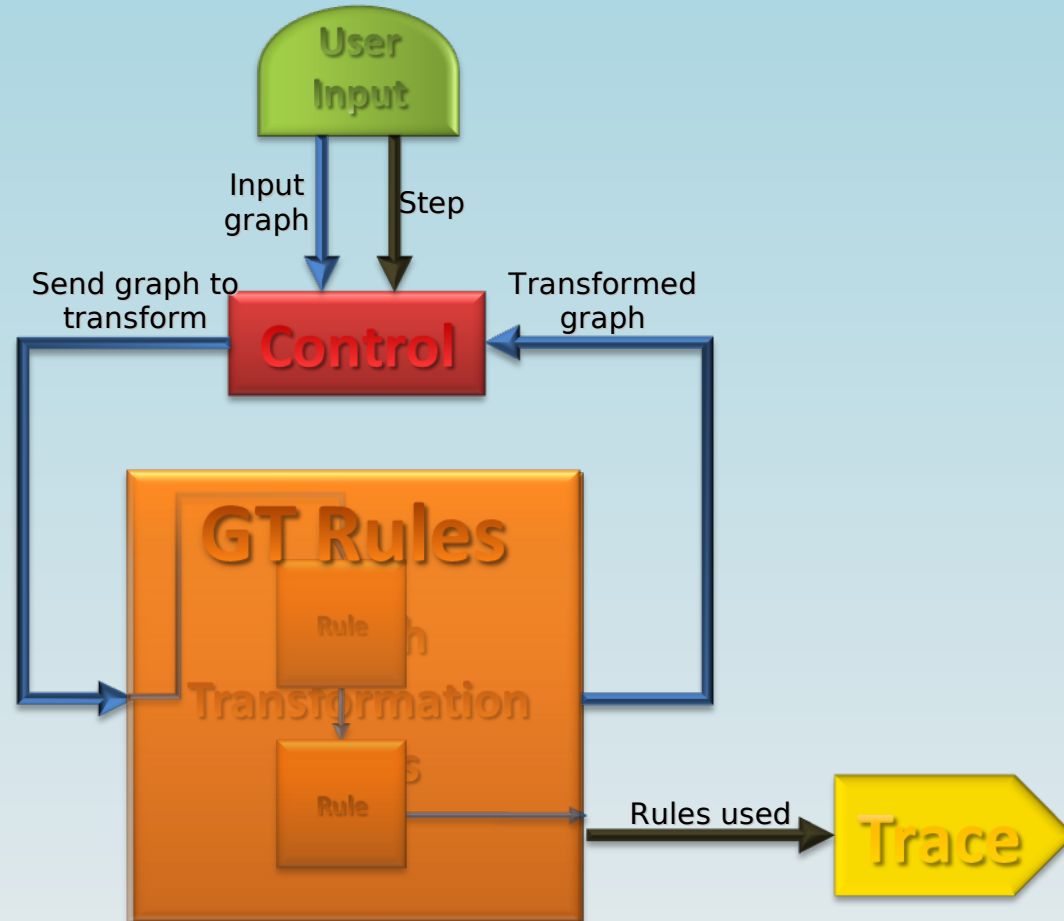
MOTIF META-MODEL



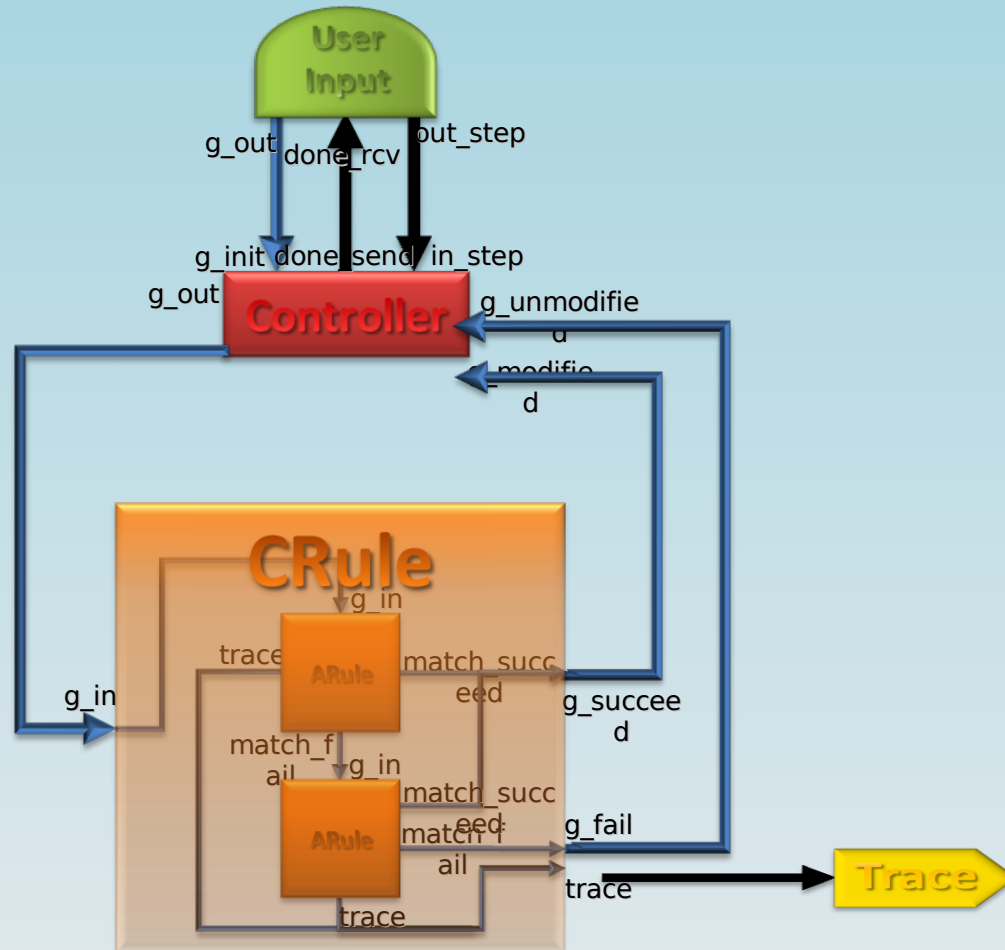
MOTIF MODELLING ENVIRONMENT



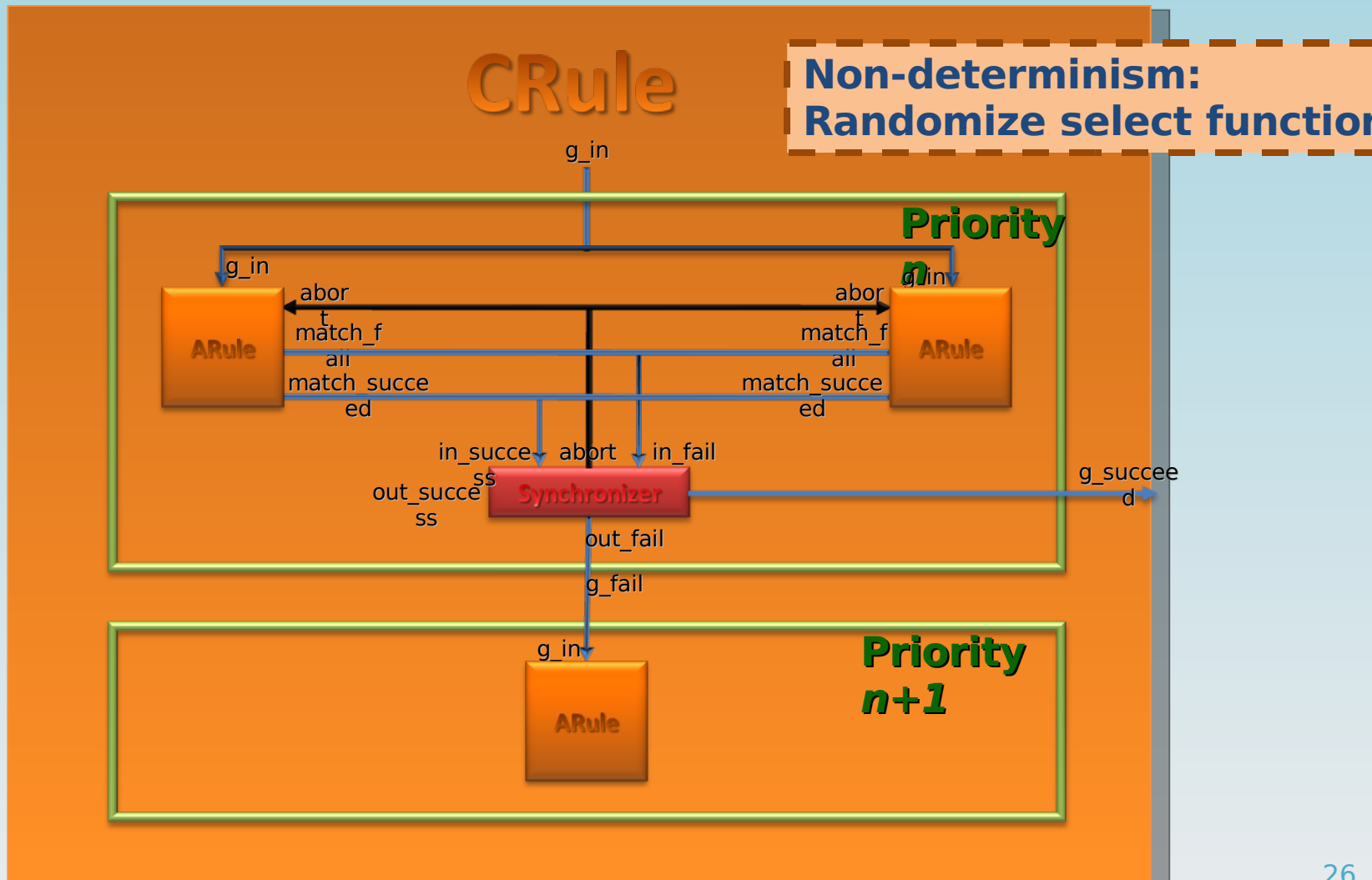
MODEL AToM³'S GRAPH TRANSFORMATION ENGINE



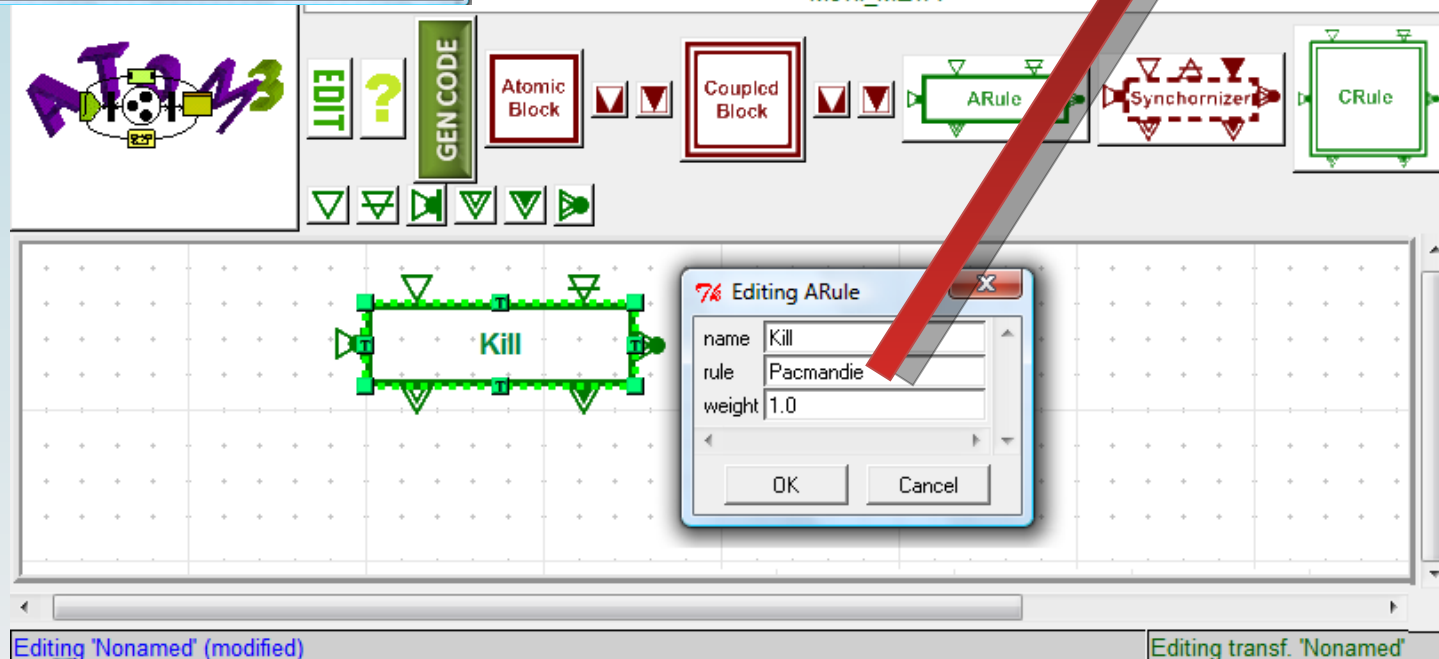
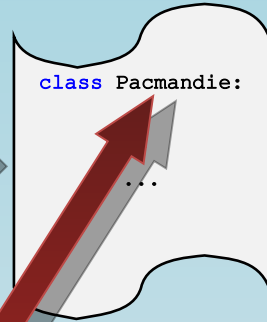
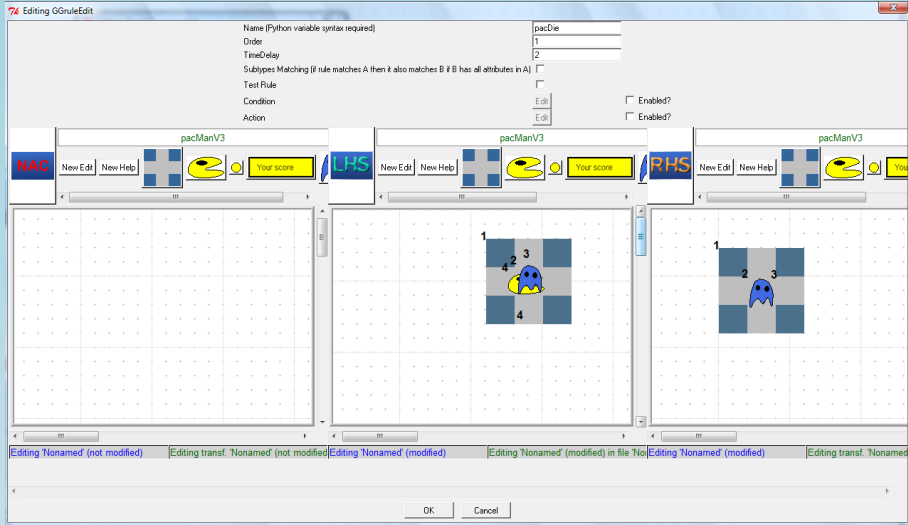
GRAPH TRANSFORMATION ENGINE



MANAGING PRIORITIES



MoTif & AToM³



MoTif EXECUTION

COMPILE



```
class Pacmanmove:
def
class Pacmandie:
def match():
...
```

IMPORT



GENERATE



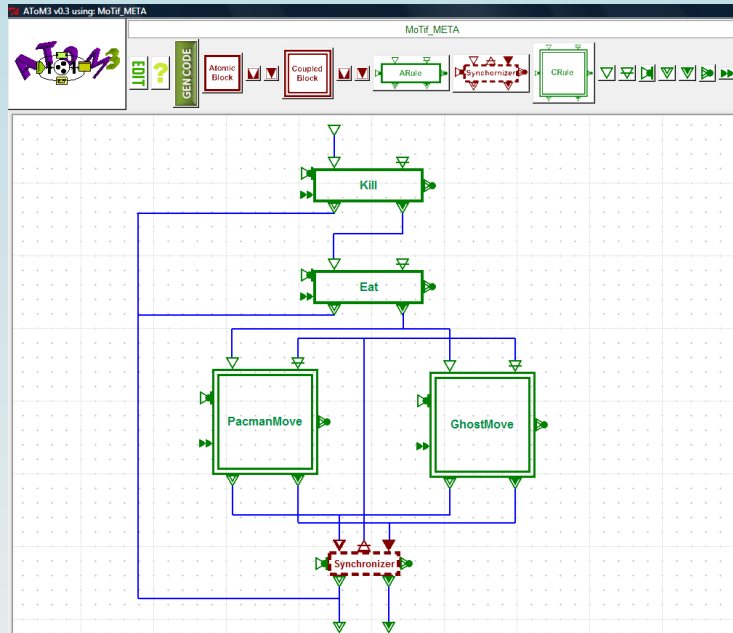
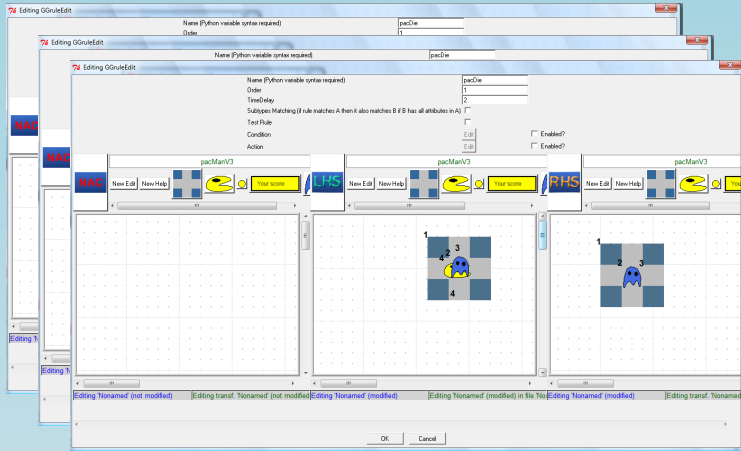
```
class Kill(ARule):
def __init__(self):
ARule.__init__(self,
name='Kill')
self.state =
ARuleState(Pacdie())

def weightFunction(self):
return 1.0
```

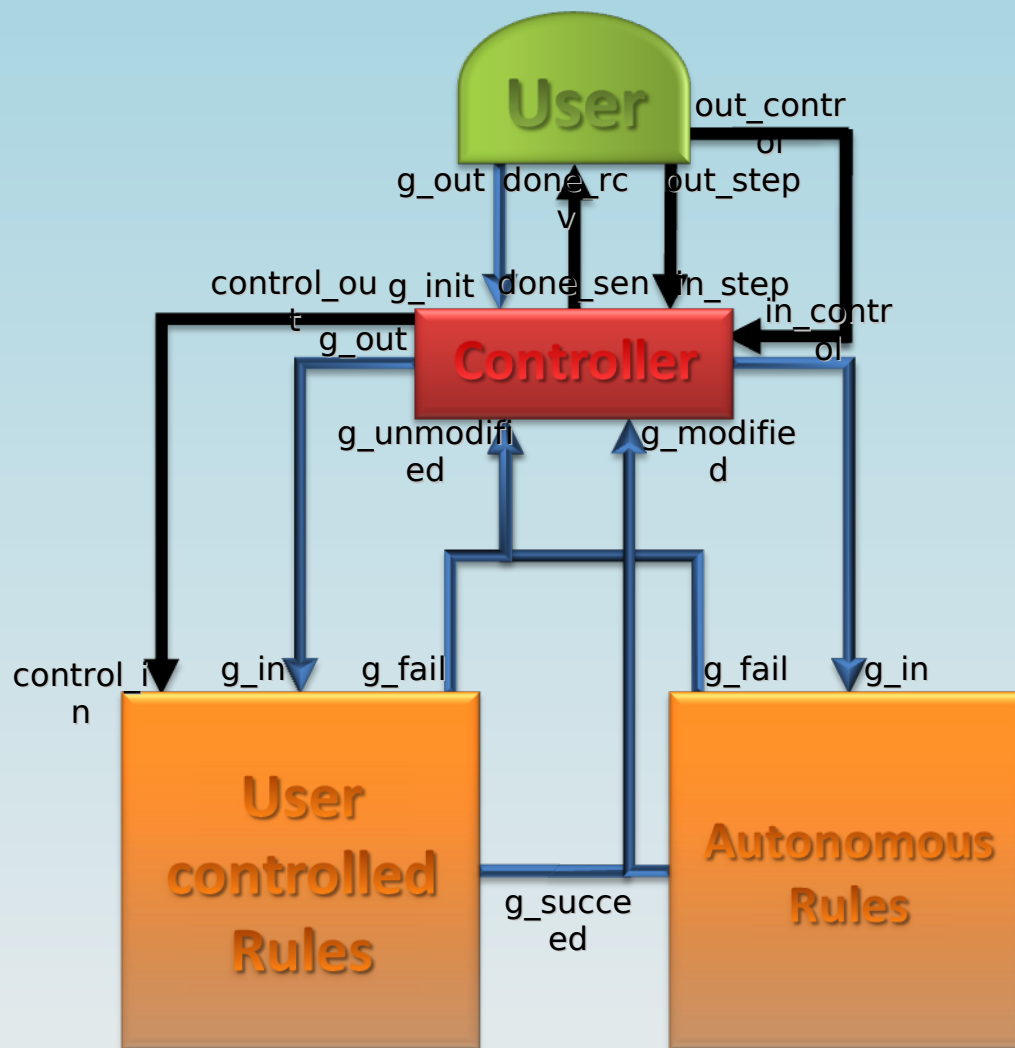
SIMULATE



```
Rules Used
>1: PacManUp
>2: Eat
>3: PacManLeft
>4: Eat
>5: PacManDown
>6: Eat
>7: PacManDown
>8: Eat
>9: GhostRight
>10: GhostDown
>11: Kill
>12: GhostUp
>13: GhostLeft
>14: GhostUp
>15: GhostLeft
>16: GhostRight
```

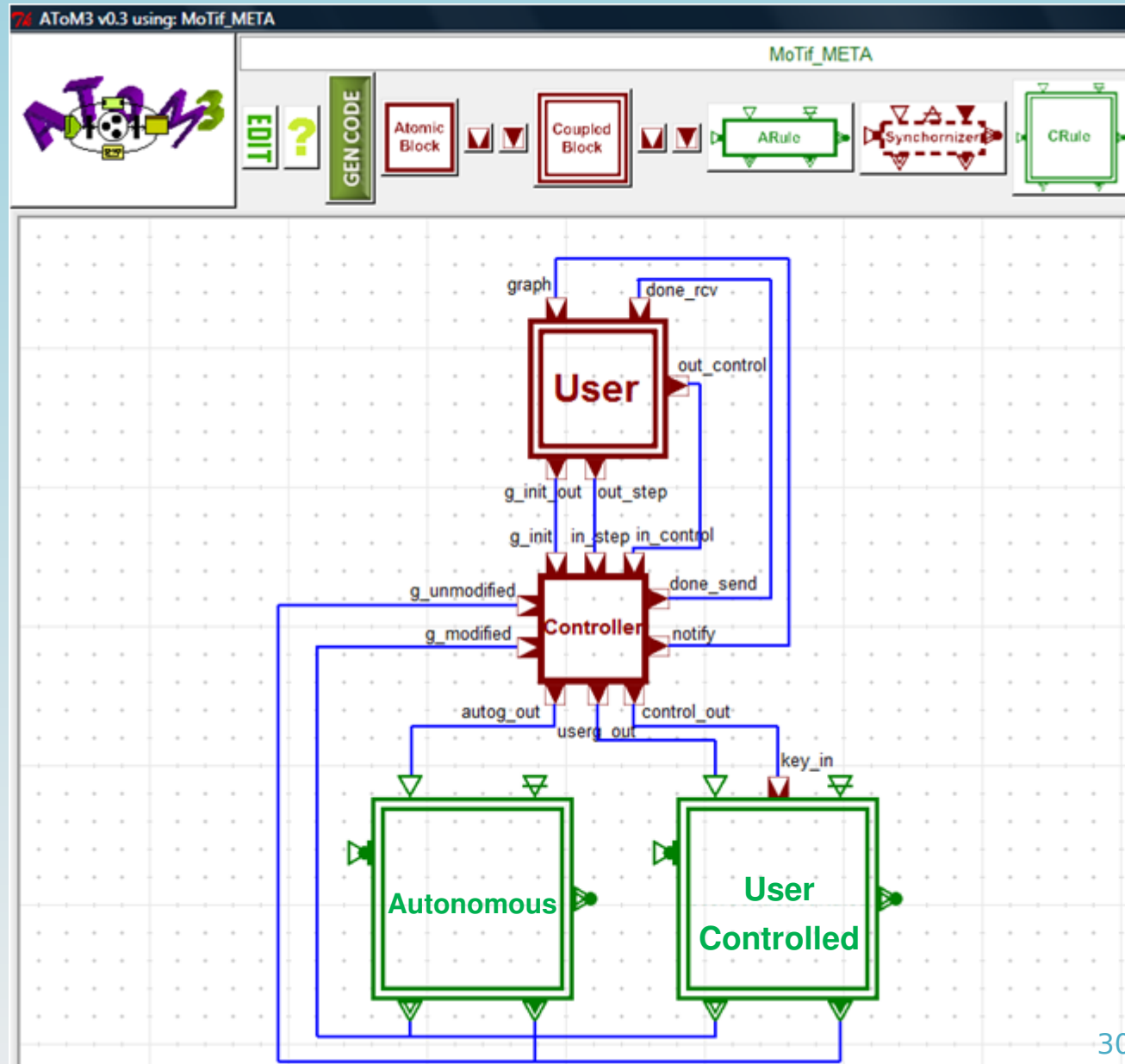


EXTENSION OF ATOM³'S GRAPH TRANSFORMATION ENGINE



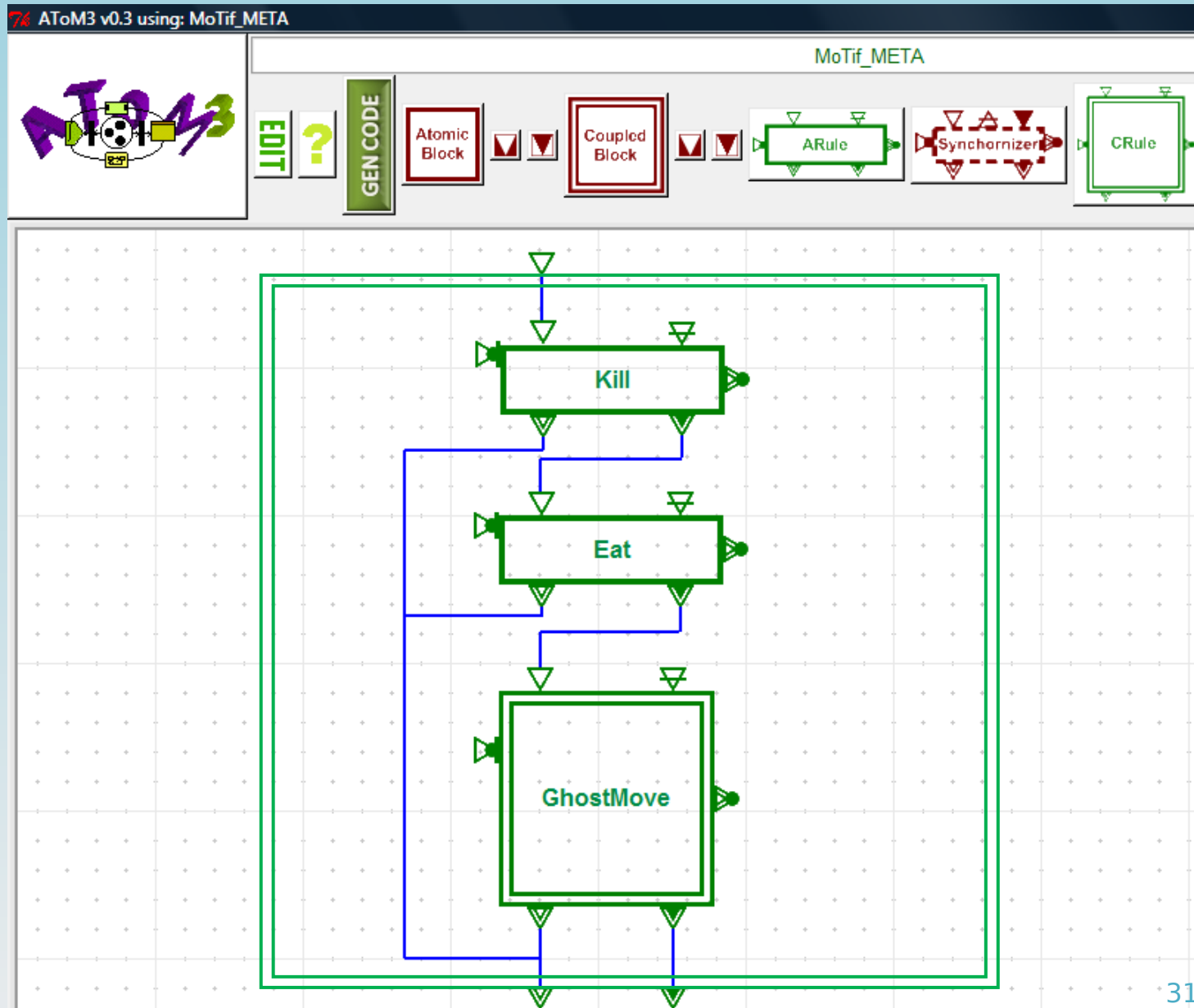
MODELLING OF THE TRANSFORMATION: SYSTEM

- **User – Controller – Autonomous loop**
- **Feed-back to User**
- **On User interrupt: User Controlled**
- **Feed-back to User**

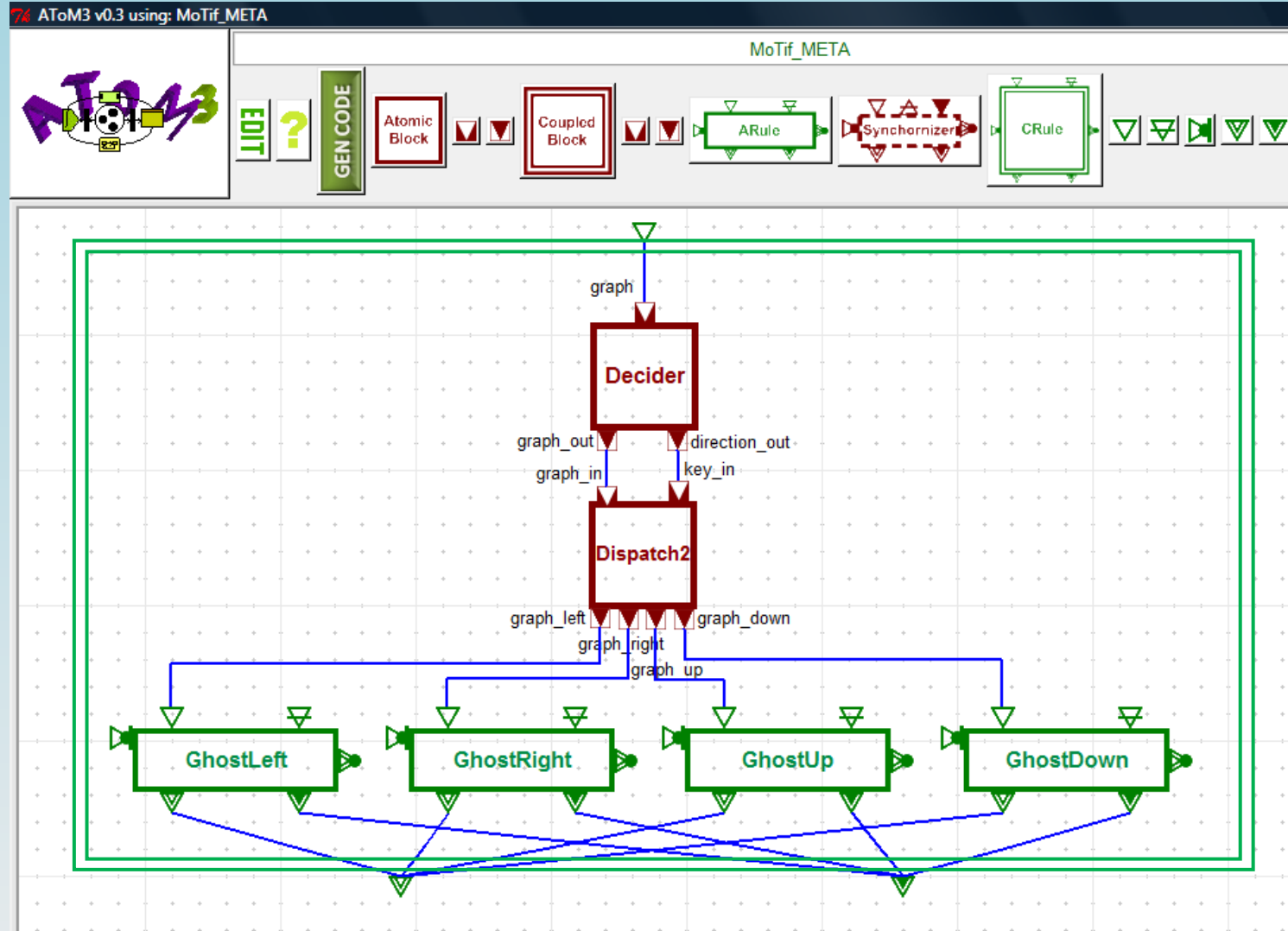


MODELLING OF THE TRANSFORMATION: AUTONOMOUS *CRule*

Priorities



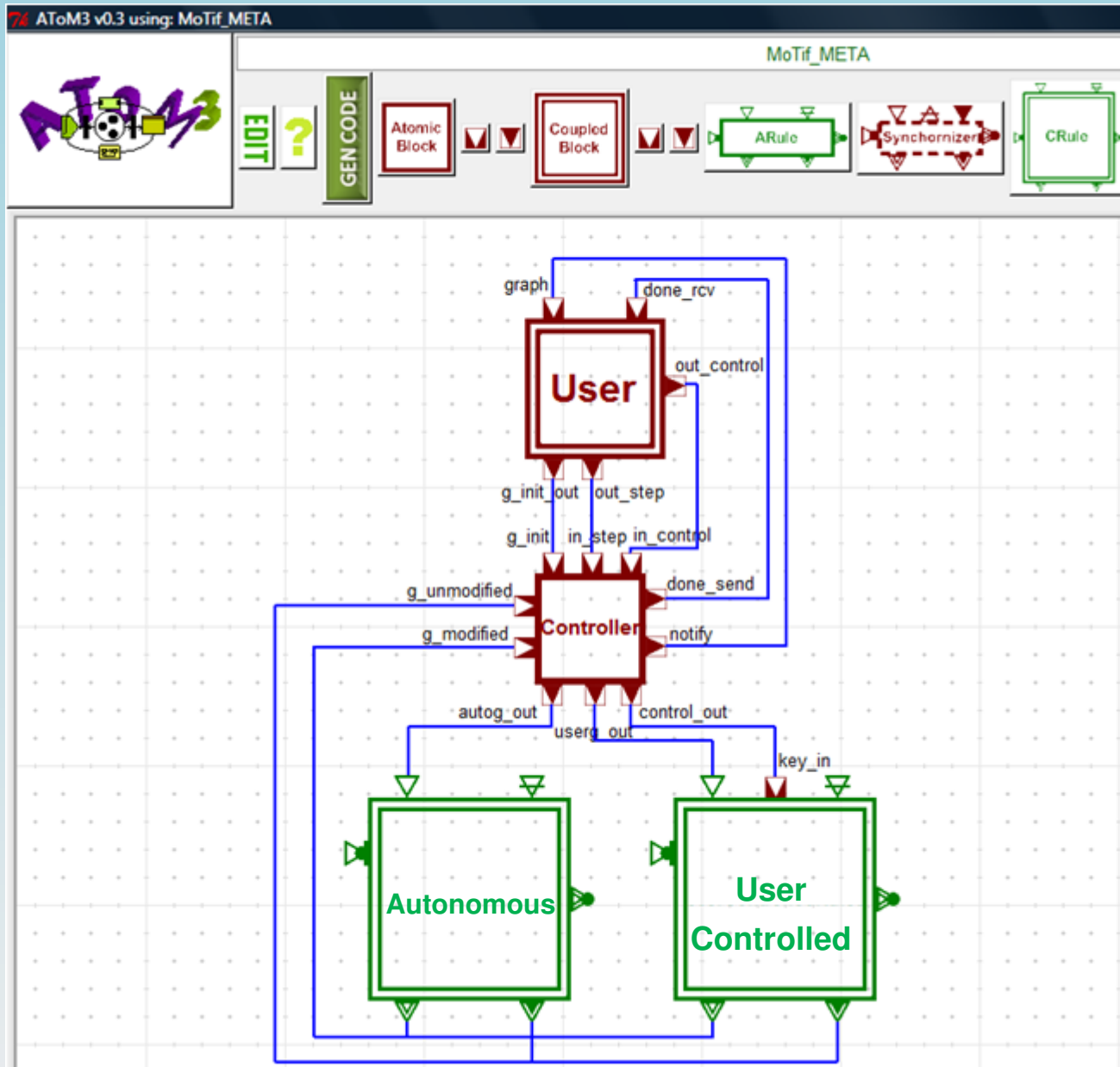
MODELLING OF THE TRANSFORMATION: GHOSTMOVE *CRule*



Decider
finds the
next move
for the
ghost

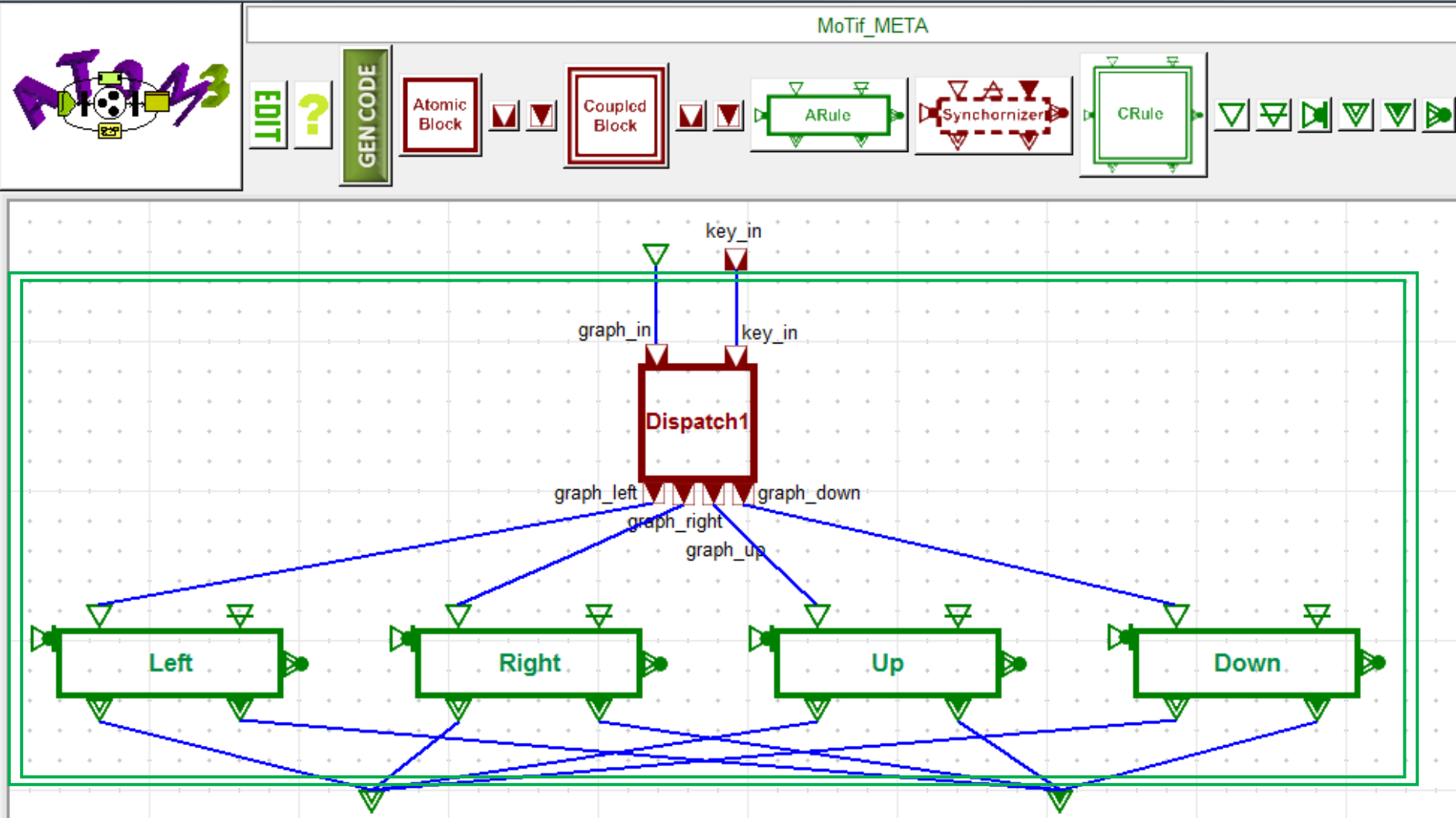
Decider
consumes
time

MODELLING OF TRANSFORMATION: SYSTEM



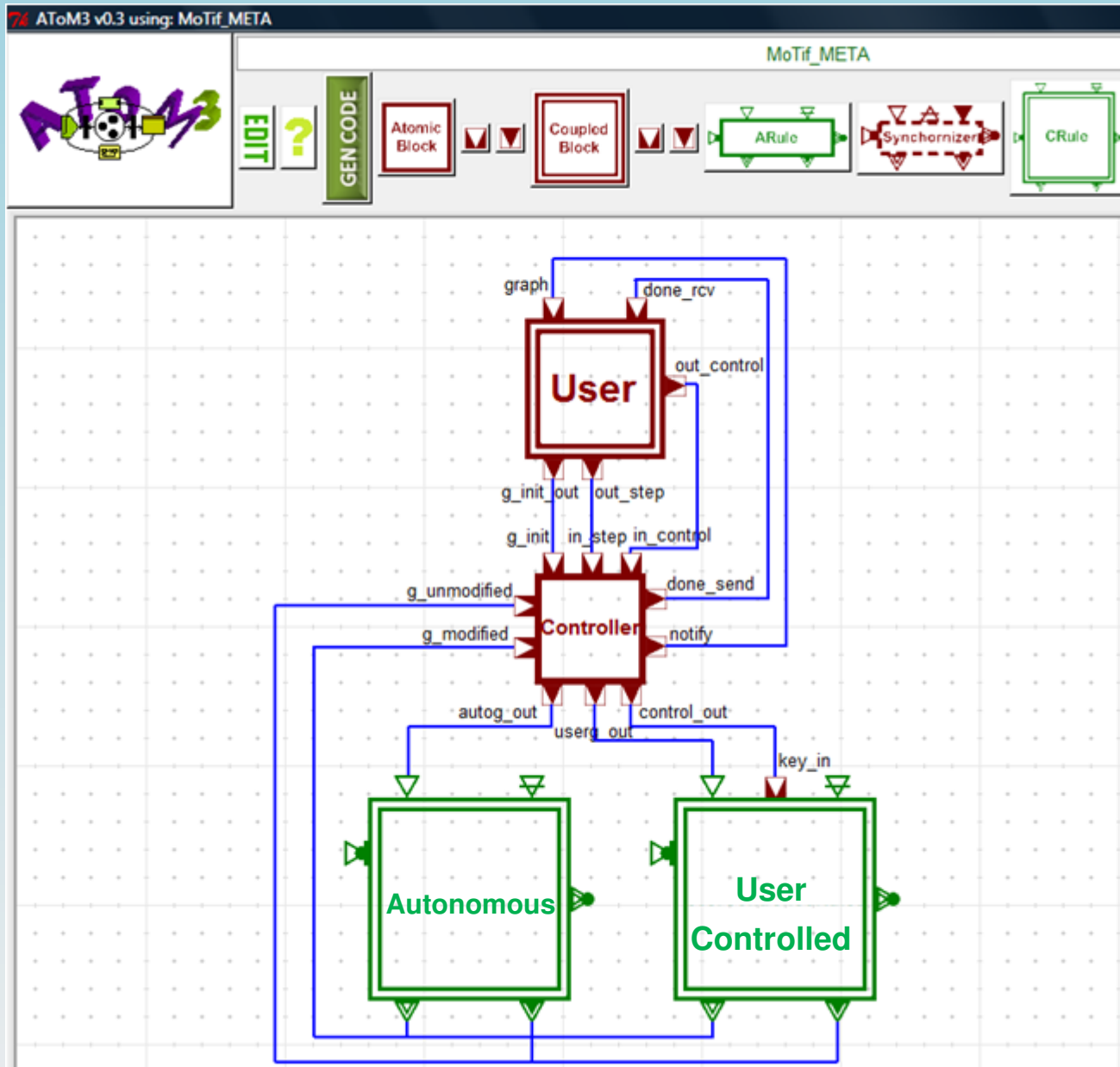
MODELLING OF THE TRANSFORMATION: USERCONTROLLED *CRule*

74 AToM3 v0.3 using: MoTif_META

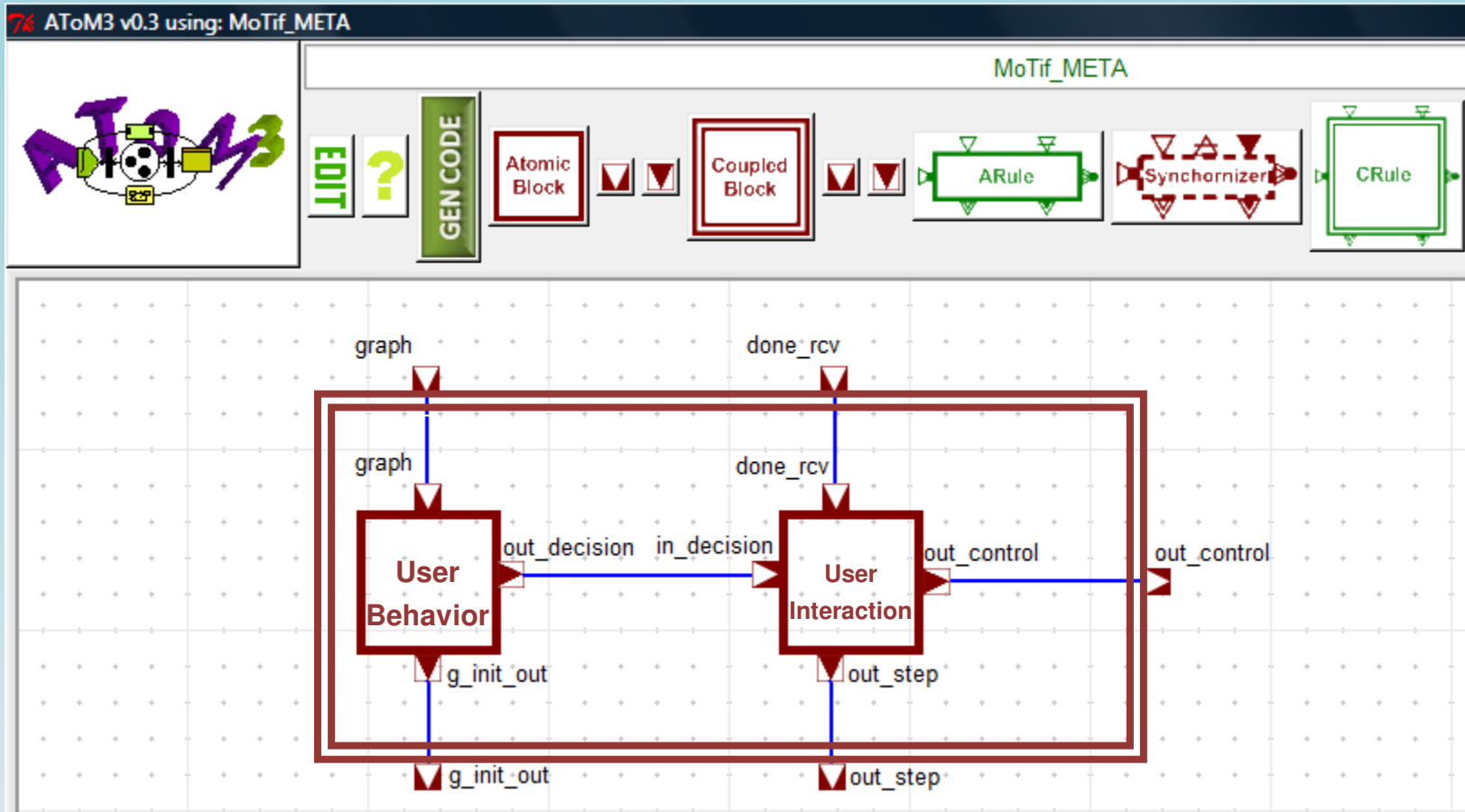


Conditional rule execution

MODELLING OF THE TRANSFORMATION: SYSTEM



MODELLING OF ENVIRONMENT: USER CoupledBlock

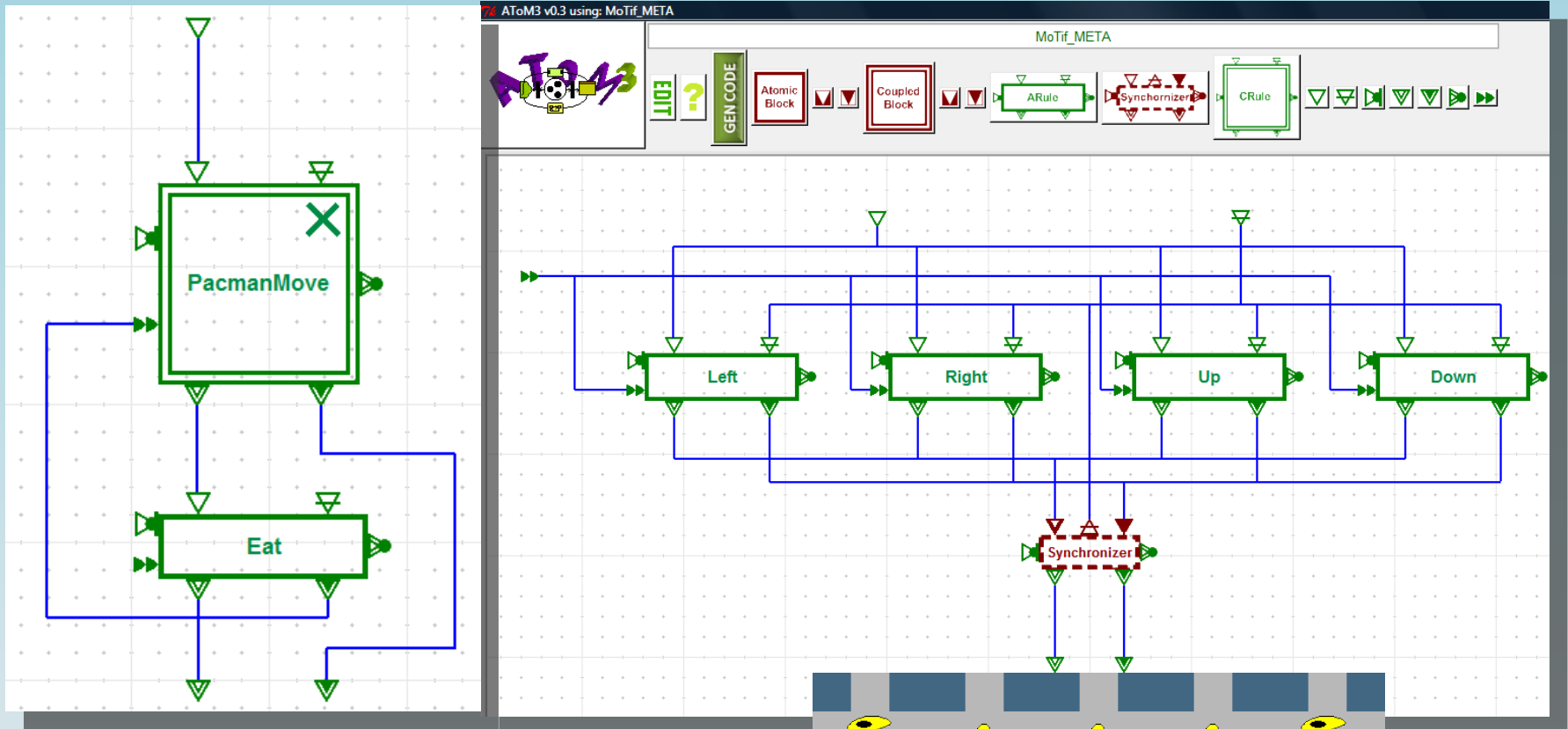


- Customization
- Modularity

BACKTRACKING

- **What?**
Algorithmically, used for exploring a search space
- **Why?**
In graph transformation, needed when a non-deterministic choice is made
 - Matching level
 - Rule level
- **How?**
 - Make copies of the graph
 - Use checkpoints and transactions
 - Have undo/inverse transformations

BACKTRACKING



- **Next Mode event:**
 - Cumulative
 - Roll-back

SUMMARY

Control flow structure properties satisfied

- ✓ **Sequence**
- ✓ **Branching**
- ✓ **Looping**
- ✓ **Hierarchy + Modularity**
- ✓ **(pseudo-)Parallelism**
- ✓ **Backtracking**
- ✓ **Time**

ONE STEP FURTHER

User - Events

- **Event-driven Graph Rewriting**
- **Modelling of the user**
- **Web-based pacman game**
 - **AJAX**
 - **SVG**
 - **Real-time**

ONE STEP FURTHER

Time

- **Metric, Statistics**
- **Timed graph transformation**
- **Real-Time DEVS**

FUTURE WORK

Some Extensions

- **Optimization (rule compilation)**
- **Replace transformation blocks by Statecharts, code, ...**
- **Integrate MoTif in AToM³: 2-way communication**
- **Scaling for larger models:**
 - **Database**
 - **Distributed**

FUTURE WORK

Parallelism

- **DEVS is a sequential formalism**
 - Parallel-DEVS
 - Kiltera (CSP-like languages)
- **Distributed rule application**

Variable Structure Formalisms