



# Ptera: An Event-Oriented Model of Computation for Heterogeneous Systems

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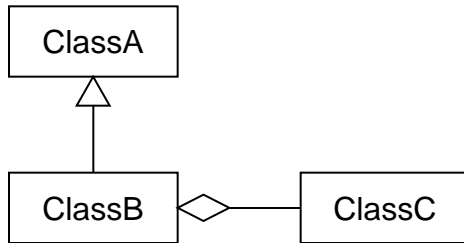
EECS, UC Berkeley

**Lee W. Schruben**

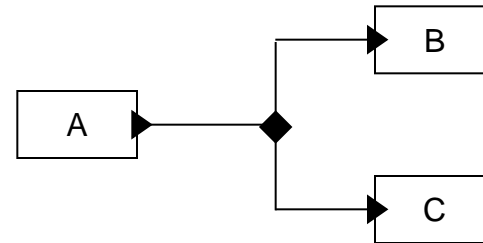
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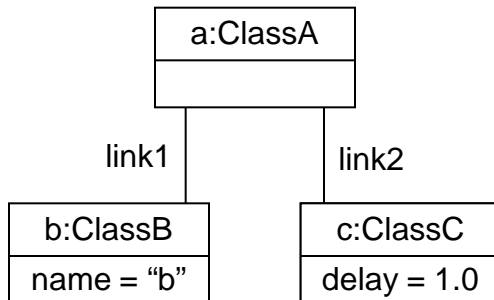
# Models of Systems



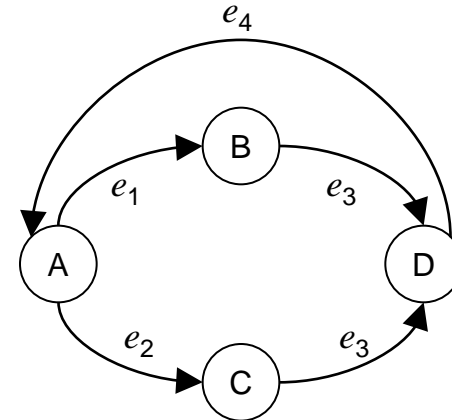
**Class Diagram**



**Actor Diagram**

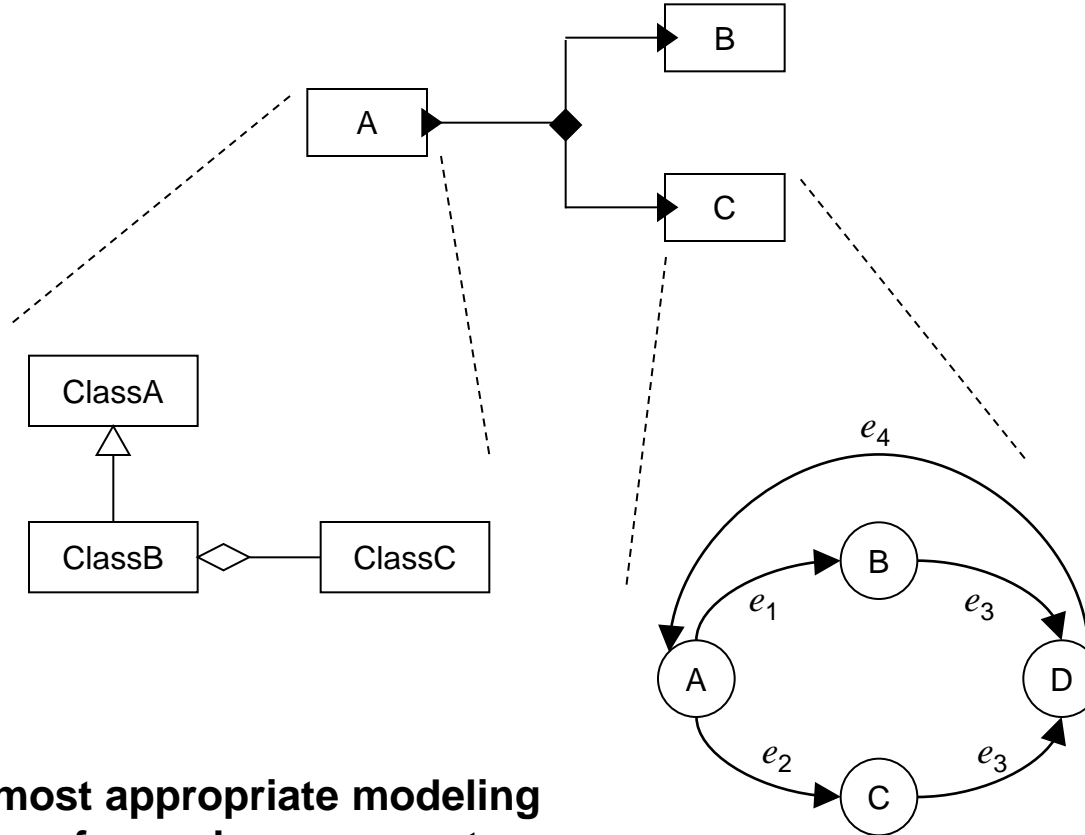


**Object Diagram**



**State Diagram**

# Hierarchical Heterogeneous Modeling



**Use the most appropriate modeling language for each component.**

**Compose those components to form more complex systems.**

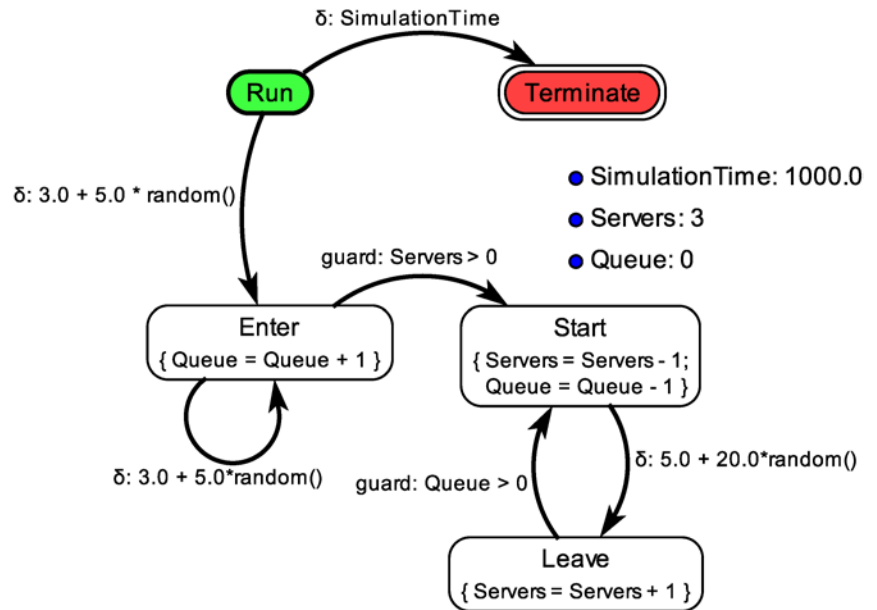
# The Event-Oriented View

- Ptera (Ptolemy Event-Relationship Actor)  
Based on event graphs [Schruben 1983]
- Visual representation
  - Nodes are **events**
  - Edges are **scheduling relations**

- Compare
  - State diagram
  - UML activity diagram
  - Business process modeling

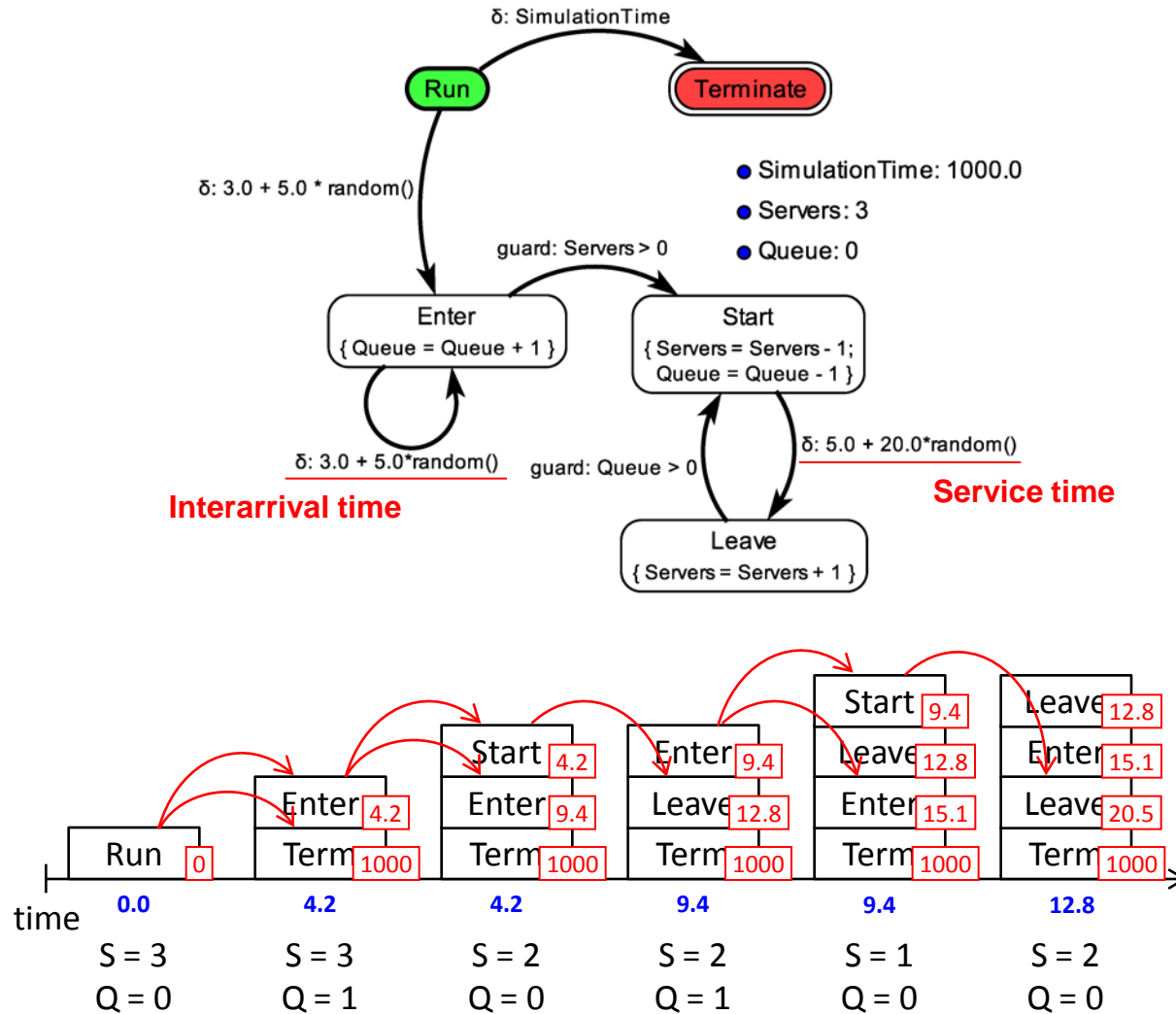


CarWash: single queue multiple servers

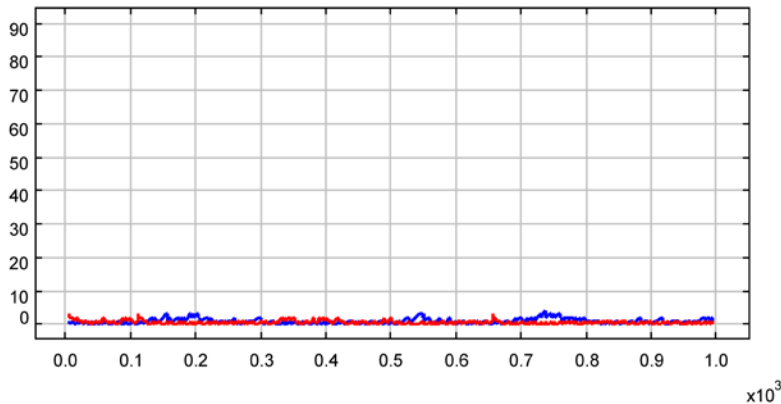
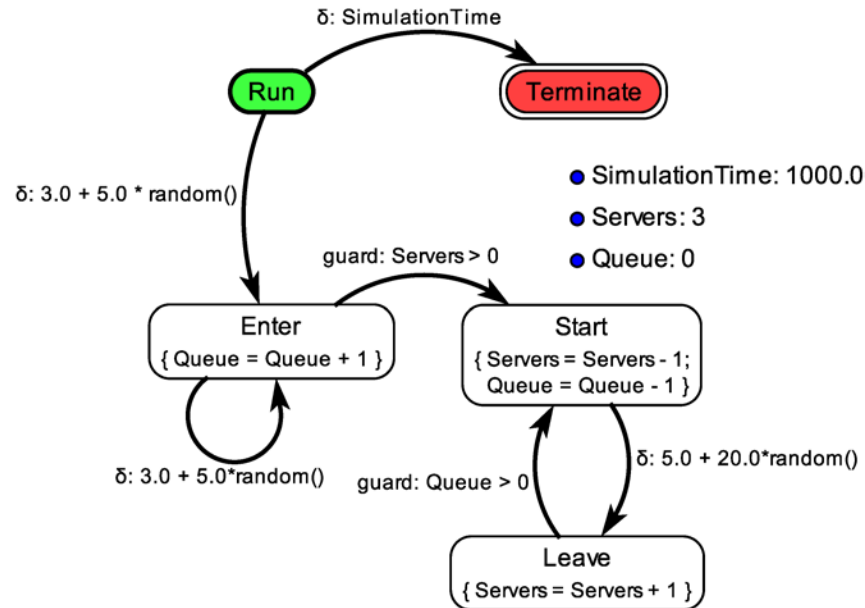


The CarWash model

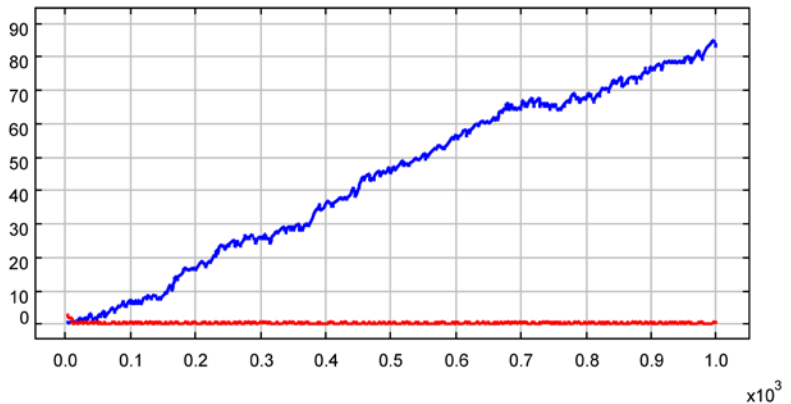
# Execution with an Event Queue



# Simulation



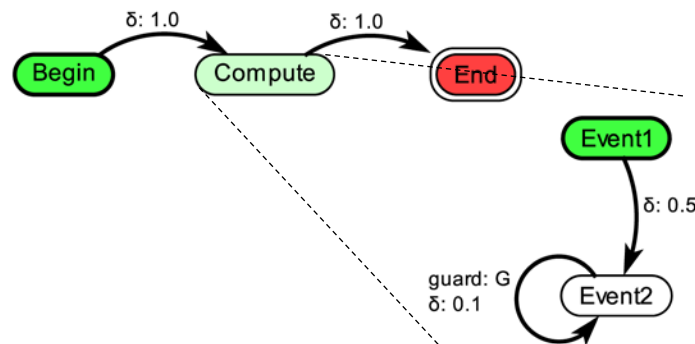
$IAT = 3.0 + 5.0 * \text{random}()$



$IAT = 1.0 + 5.0 * \text{random}()$

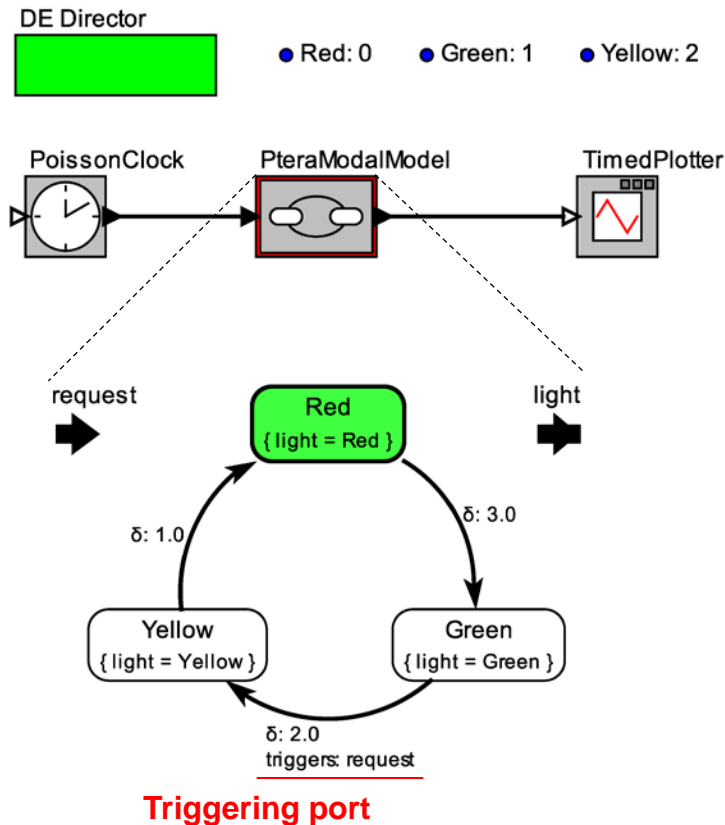
# Model Hierarchy: The Ptera Approach

- A submodel is itself a model
  - No difference in syntax
  - Conceptually equipped with an isolated event queue
  - A global notion of model time



- Implication: **events (or tasks) are no longer instantaneous**
  - **Start** of an event causes **start** of its submodel
  - **End** of the submodel causes **end** of the event

# Communication via Ports

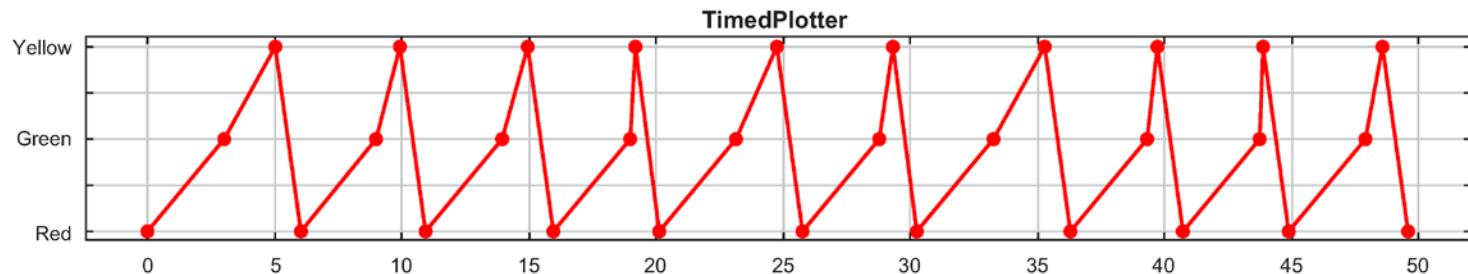


## Event processing conditions

1. Scheduled time is reached, or
2. Tokens received at one or more triggering ports

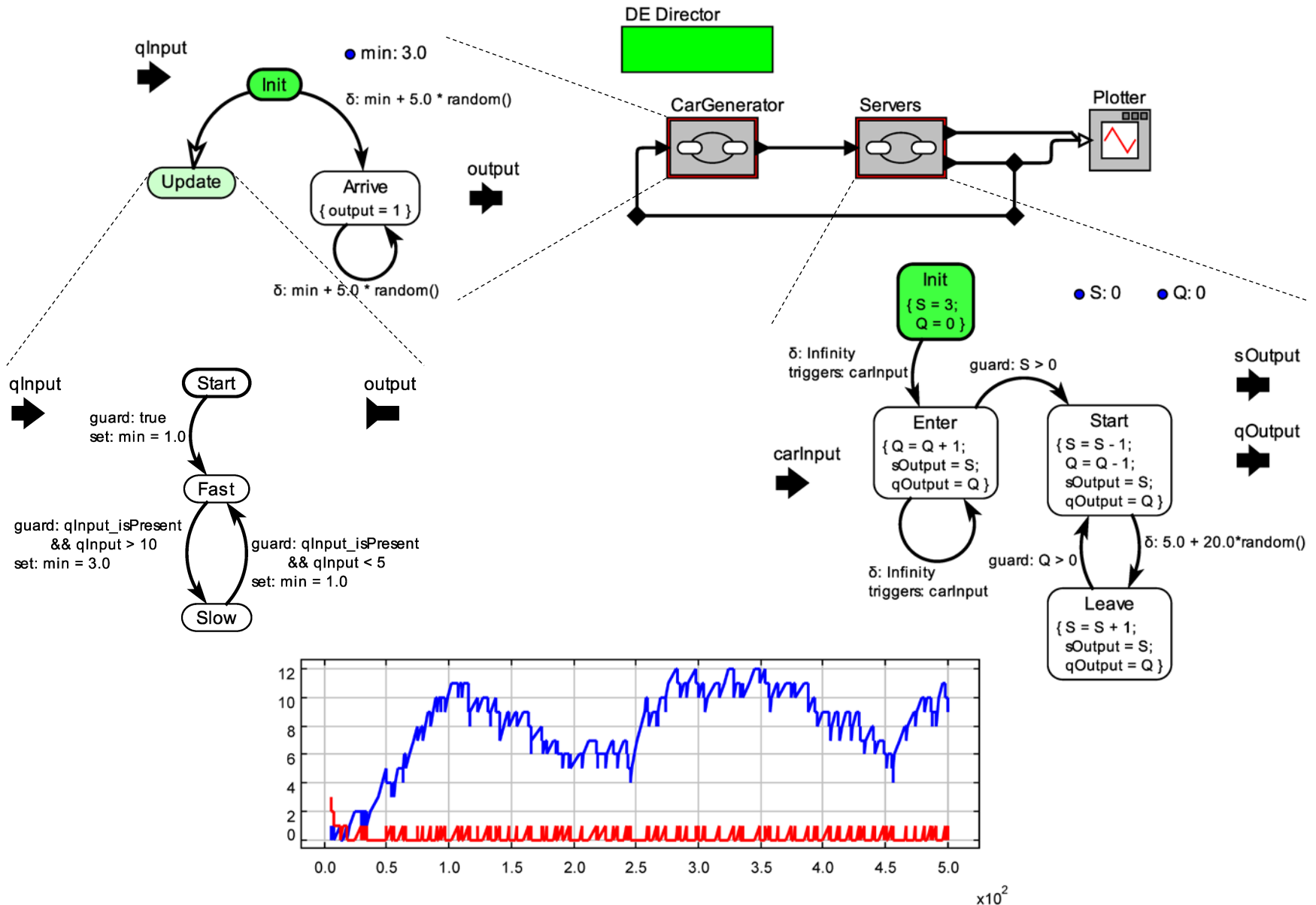
Inputs not triggering any event are ignored.

Outputs can be sent in actions.

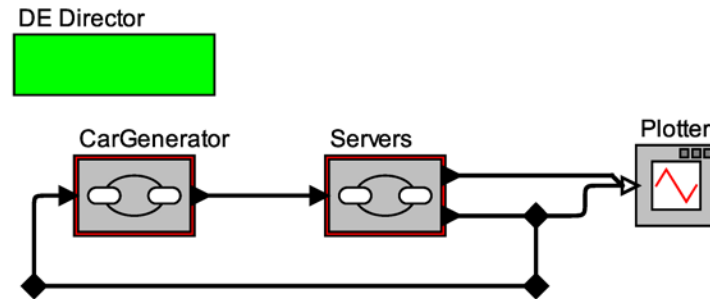




# Hierarchical Multimodeling



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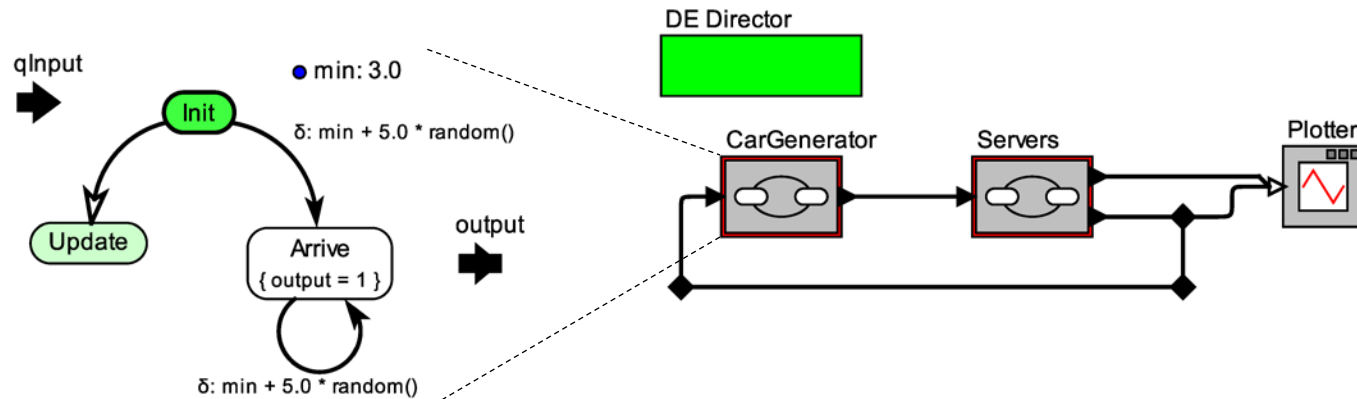


Goal: reusable, robust and flexible design

Choose DE at top level for

- Concurrency
- Concern separation
- Encapsulation
- Fixpoint semantics
- Out-of-order execution
- Distributed execution

# Hierarchical Multimodeling



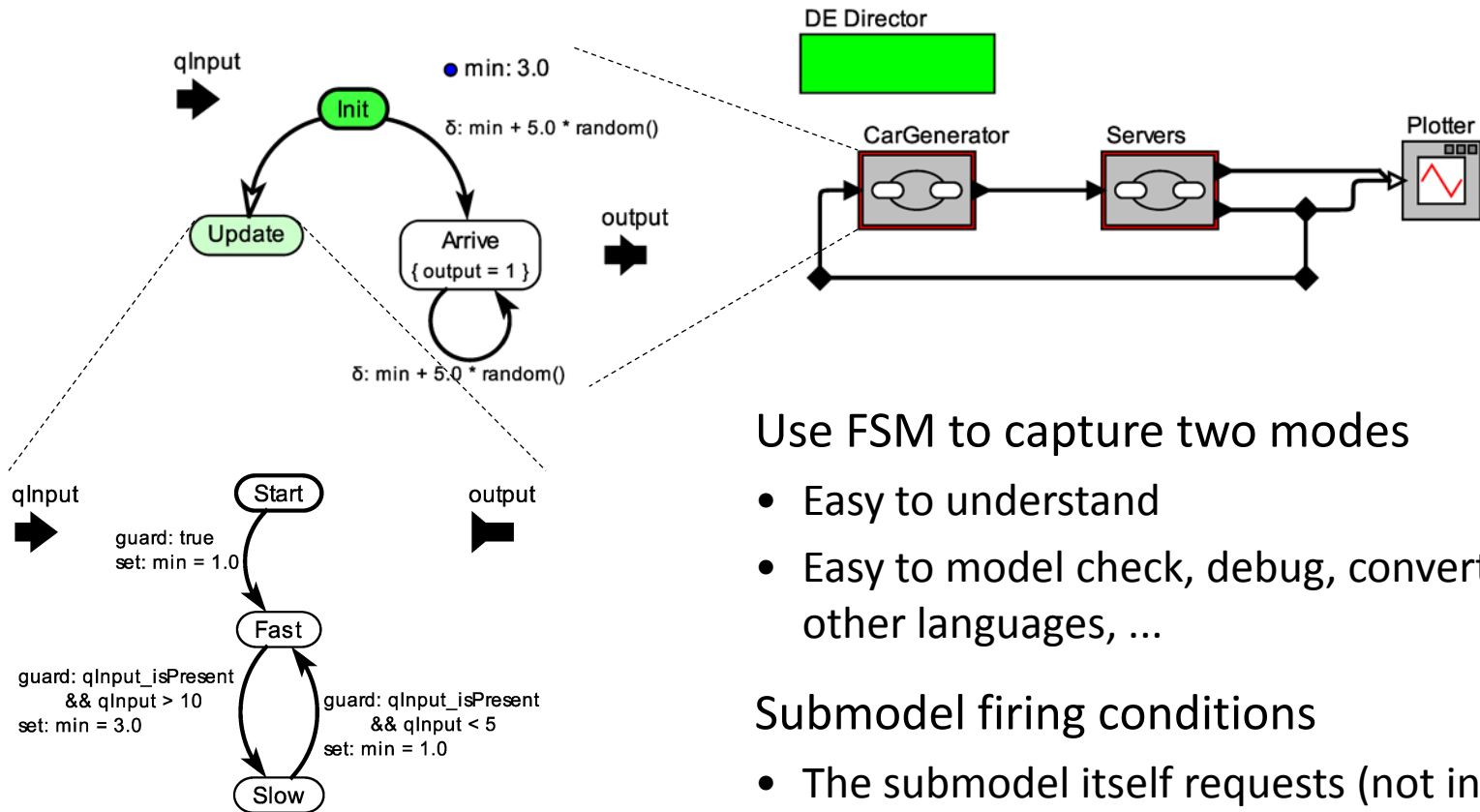
Choose Ptera to model a random process

- No need to depend on predefined actors
- Easy to control the exact behavior
- Totally sequential (but concurrency may be possible)

Some predefined actors can be designed in this way

- Source actors
- Math actors
- Time delay actors
- Flow control actors

# Hierarchical Multimodeling



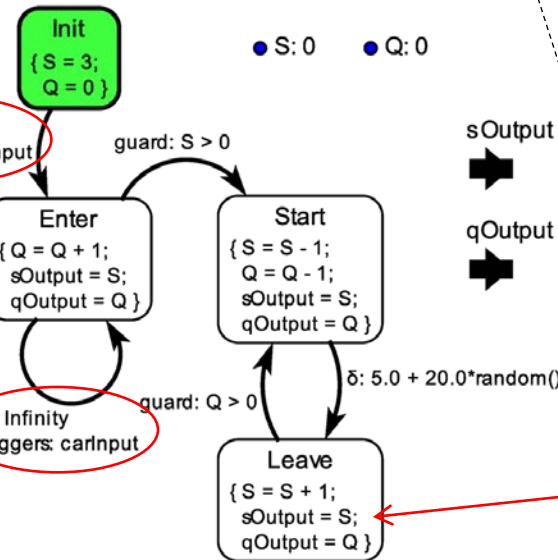
Use FSM to capture two modes

- Easy to understand
- Easy to model check, debug, convert into other languages, ...

Submodel firing conditions

- The submodel itself requests (not in this case), or
- Input is received at a port, or
- The event containing the submodel is processed

Indefinitely wait for change of car number.



- Output both S and Q when either of them is changed

# Opportunities

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- Composition with other MoCs  
(Especially, Ptides and continuous time)
- Formal analysis  
(Bound of event queue, simultaneous events, termination condition, model categorization, ...)
- Behavior-preserving concurrent and distributed execution
- Other application domains  
(Currently studied: statistical analysis, model transformation)
- Tool support  
(Debugging and testing, code generation)
- Design patterns  
(Currently studied: Input, Output, LoopForCount, ParallelTasks, SingleQueueMultipleServers)