

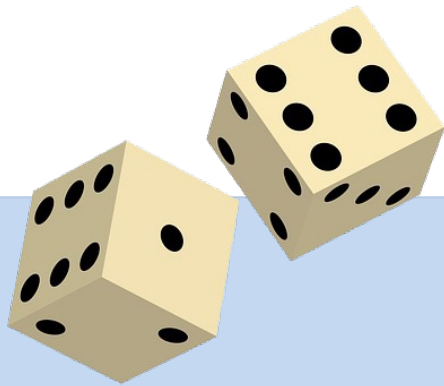


iCyPhy



Software Design for Cyber-Physical Systems

Edward A. Lee



Module 11: Models Revisited

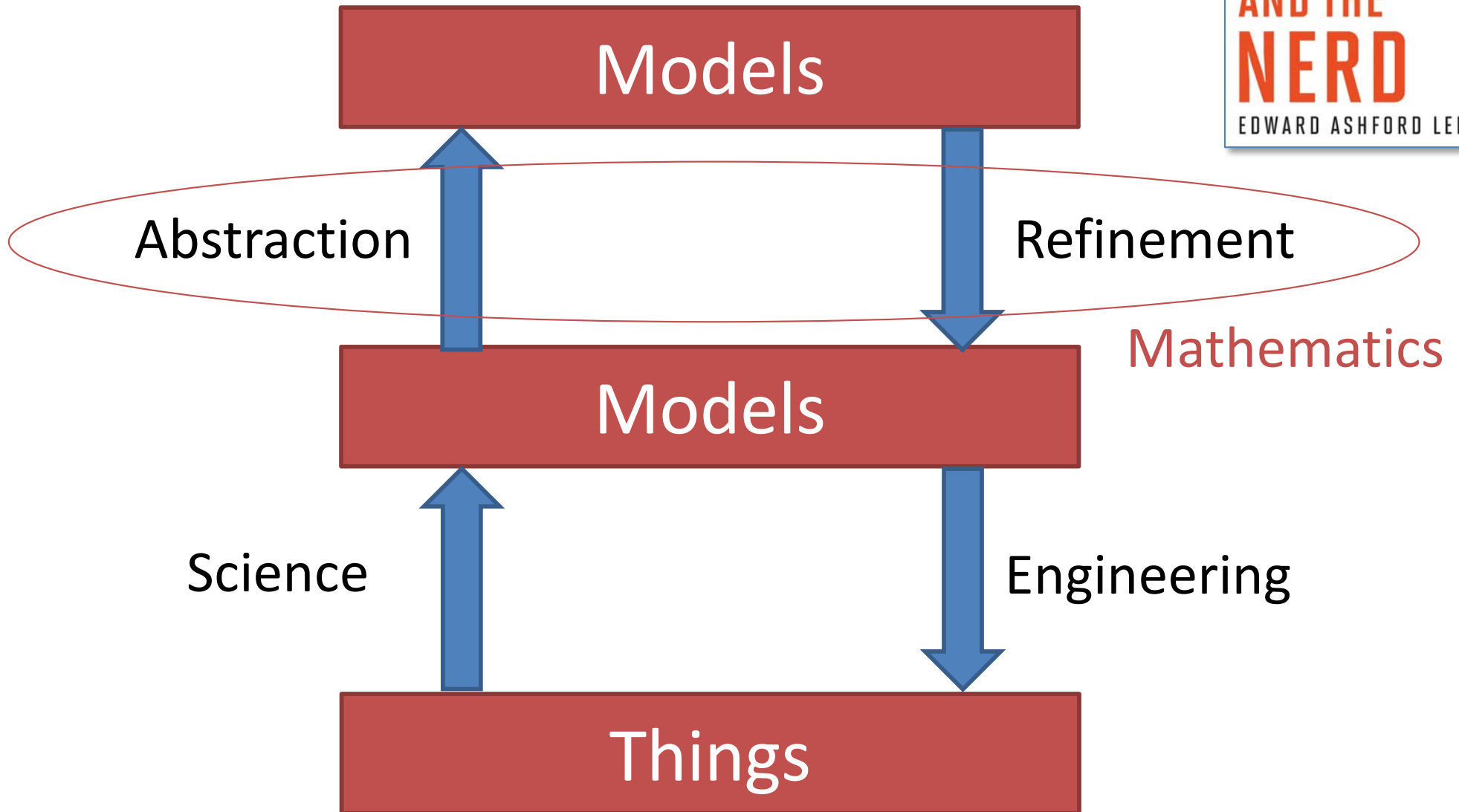
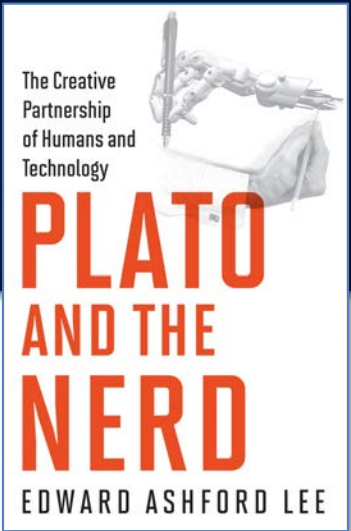
Technical University of Vienna
Vienna, Austria, May 2022



University of California, Berkeley

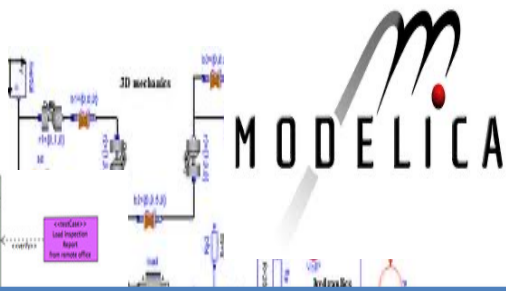


Science, Engineering, and Mathematics

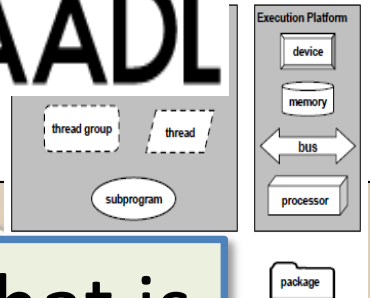




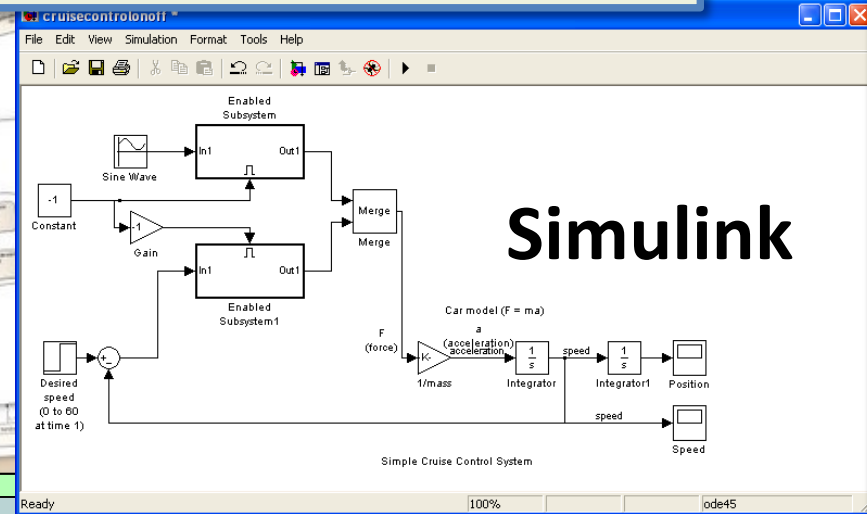
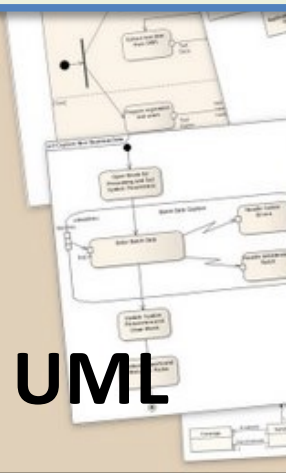
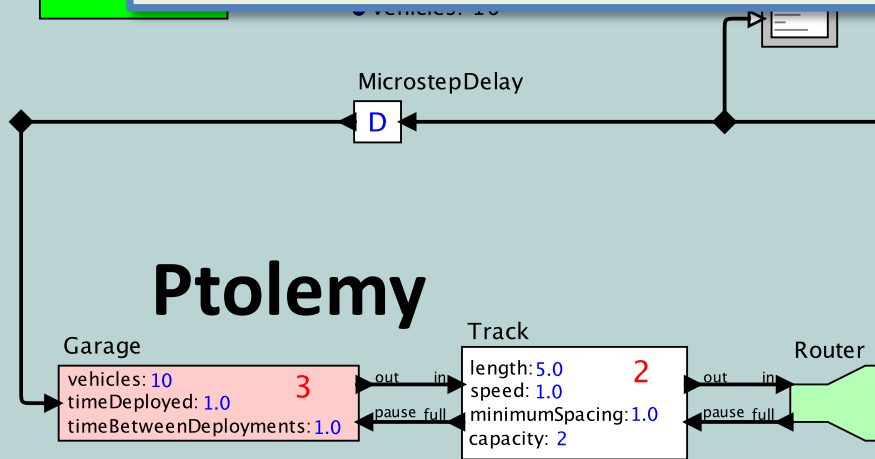
What is a model?



```
// Source code is a model:
for (int i=0; i<10; i++) {
  x[i] = a[i]*b[j-i];
  notify(x[i]);
}
```



A model is any description of a system that is not the thing-in-itself.
(das Ding an sich in Kantian philosophy).





Quiz: Is this a Model?

```
1 void foo(int32_t x) {  
2     if (x > 1000) {  
3         x = 1000;  
4     }  
5     if (x > 0) {  
6         x = x + 1000;  
7         if (x < 0) {  
8             panic();  
9         }  
10    }  
11 }
```



The physical system has many properties not represented in the model (e.g. timing, temperature, physical volume).





Purposes of Models

- Describe structure, weight, dimensions, ...
- Describe energy needs, temperatures, ...
- Describe dynamics
- Specify a design
- Simulate a behavior
- Verify that conformance with a requirement
- Specify a requirement
- ...



Properties of Models

Formal?

A formal model is a model given in a well-defined, machine-readable syntax and can be mechanistically manipulated using well-defined rules to derive properties of the model.

Executable?

An executable model is a formal model describing the dynamic behavior of a system where a machine can use the model to simulate that dynamic behavior.

Faithful?

A faithful model is a model that reasonably accurately conforms to properties of the thing being modeled.



Determinism as a Property of Models

A **model** is *deterministic* if, given the initial *state* and the *inputs*, the model defines exactly one *behavior*.



Determinism in Physics: Laplace's Demon

Pierre Simon Laplace

Pierre-Simon Laplace (1749–1827).

Portrait by Joan-Baptiste Paulin Guérin, 1838

Lee, Berkeley





Laplace's Demon cannot exist.

In 2008, David Wolpert proved that **Laplace's demon cannot exist.**

His proof relies on the observation that such a demon, were it to exist, would have to exist in the very physical world that it predicts.

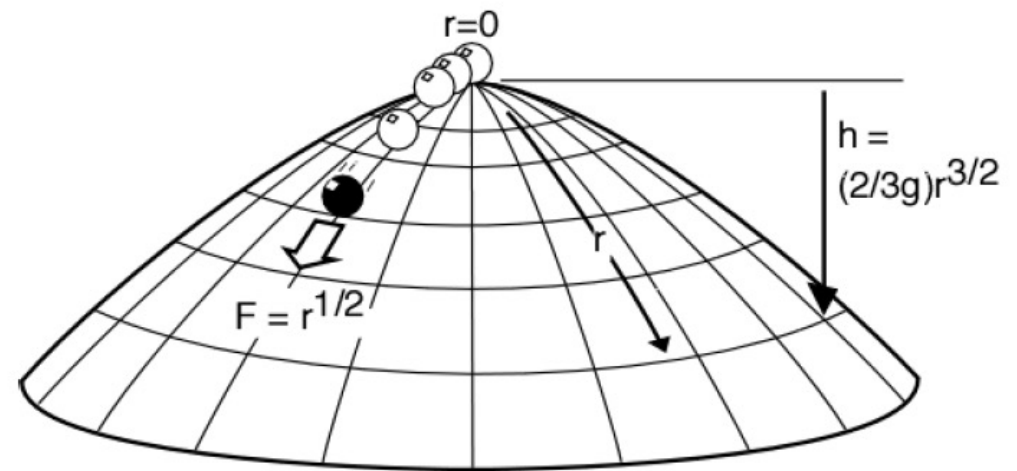


David Wolpert



Norton's Hill

Even without
quantum physics,
Newtonian physics is
not deterministic.



Metastable system that obeys all of
Newton's laws but is nondeterministic.

Norton, J. D. (2007). Causation as Folk Science. *In Causation, Physics, and the Constitution of Reality*, Oxford, Clarendon Press.



Did quantum physics dash this hope?

“At first, it seemed that these hopes for a complete determinism would be dashed by the discovery early in the 20th century that events like the decay of radioactive atoms seemed to take place at random. It was as if God was playing dice, in Einstein’s phrase. **But science snatched victory from the jaws of defeat** by moving the goal posts and redefining what is meant by a complete knowledge of the universe.”

(Stephen Hawking, 2002)

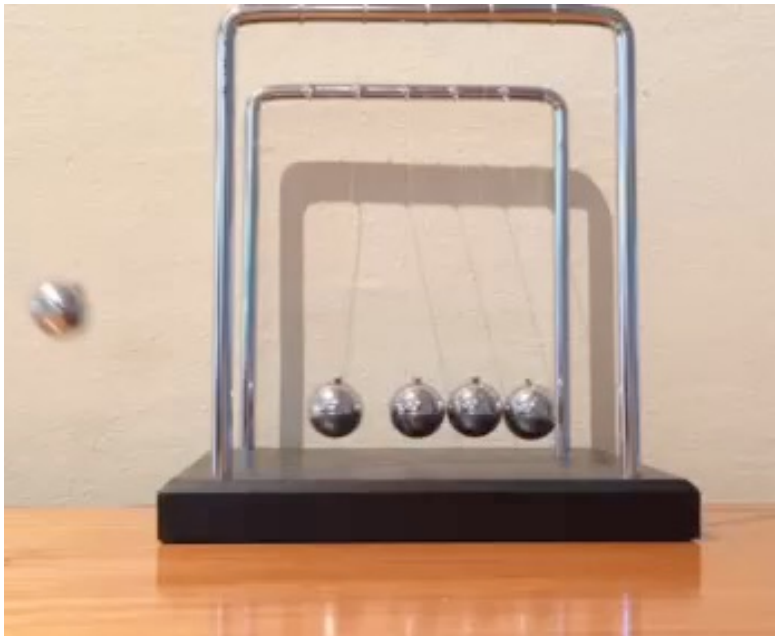




Determinism as a property of models, not things

$$x(t) = x(0) + \int_0^t v(\tau) d\tau$$
$$v(t) = v(0) + \frac{1}{m} \int_0^t F(\tau) d\tau.$$

Deterministic model



Deterministic system?



Determinism as a Property of Models

A **model** is *deterministic* if, given the initial *state* and the *inputs*, the model defines exactly one *behavior*.

Our most valuable models are *deterministic*.



Software as a Model

```
1 void foo(int32_t x) {  
2     if (x > 1000) {  
3         x = 1000;  
4     }  
5     if (x > 0) {  
6         x = x + 1000;  
7         if (x < 0) {  
8             panic();  
9         }  
10    }  
11 }
```

This program defines exactly one behavior, given the input x.

The modeling framework defines state, input, and behavior.

The physical system has many properties not represented in the model (e.g. timing, temperature, ...).





Architecture as a Model

Physical System

Model



Image: Wikimedia Commons

Integer Register-Register Operations

RISC-V defines several arithmetic R-type operations. All operations read the *rs1* and *rs2* registers as source operands and write the result into register *rd*. The *funct* field selects the type of operation.

31	27 26	22 21	17 16	7 6	0
rd	rs1	rs2	funct10	opcode	
5	5	5	10	7	
dest	src1	src2	ADD/SUB/SLT/SLTU	OP	
dest	src1	src2	AND/OR/XOR	OP	
dest	src1	src2	SLL/SRL/SRA	OP	
dest	src1	src2	ADDW/SUBW	OP-32	
dest	src1	src2	SLLW/SRLW/SRAW	OP-32	

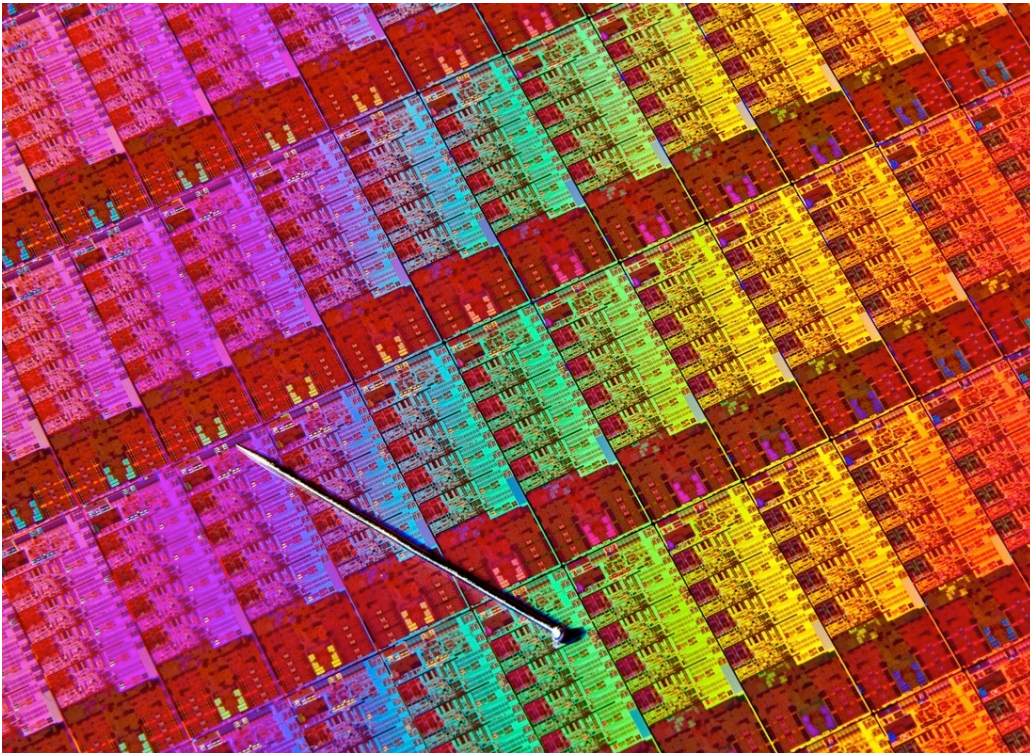
Waterman, et al., The RISC-V Instruction Set Manual, UCB/EECS-2011-62, 2011

*Instruction Set Architectures (ISAs)
are deterministic models*

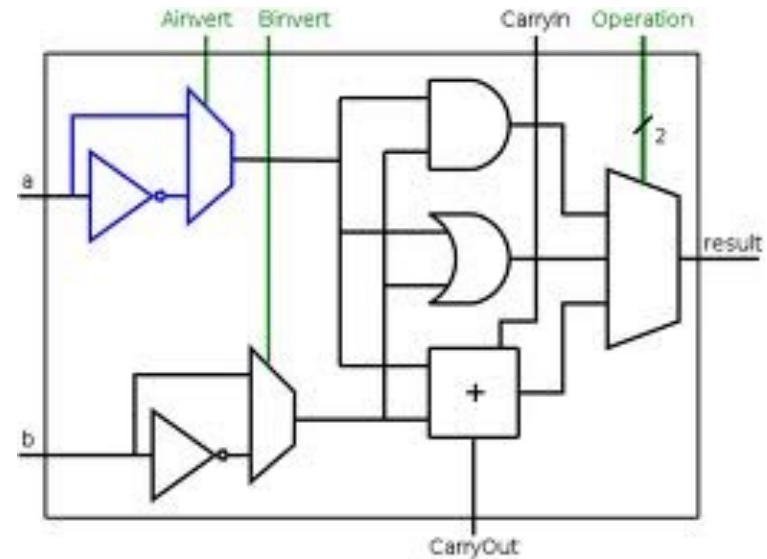


Digital Circuits as Models

Physical System



Model



Synchronous digital logic
is a deterministic model



Physical Dynamics as a Model

Physical System

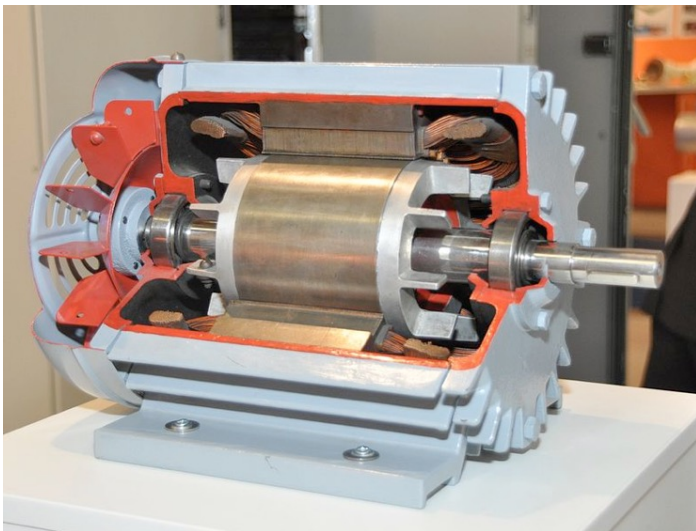


Image: Wikimedia Commons

Model



$$\dot{\mathbf{x}}(t) = \dot{\mathbf{x}}(0) + \frac{1}{M} \int_0^t \mathbf{F}(\tau) d\tau$$

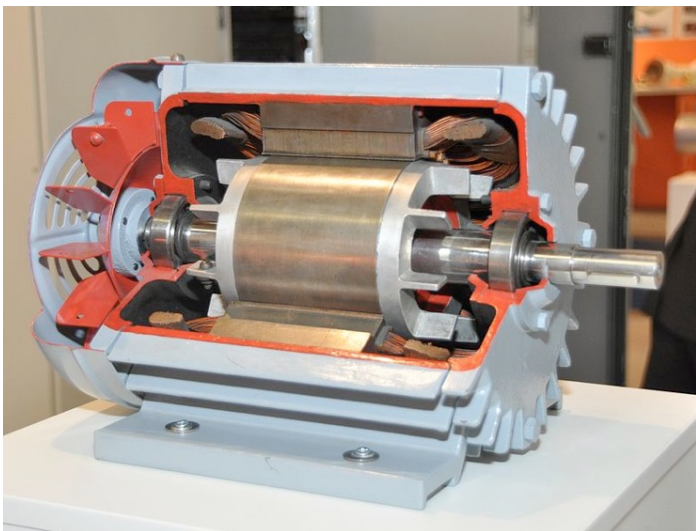
Differential Equations
are deterministic models



CPS combinations of deterministic models are nondeterministic



```
1 void initTimer(void) {
2     SysTickPeriodSet(SysCtlClockGet() / 1000);
3     SysTickEnable();
4     SysTickIntEnable();
5 }
6 volatile uint timer_count = 0;
7 void ISR(void) {
8     if(timer_count != 0) {
9         timer_count--;
10    }
11 }
12 int main(void) {
13     SysTickIntRegister(&ISR);
14     .. // other init
15     timer_count = 2000;
16     initTimer();
17     while(timer_count != 0) {
18         ... code to run for 2 seconds
19     }
20     ... // other code
21 }
```



$$\dot{\mathbf{x}}(t) = \dot{\mathbf{x}}(0) + \frac{1}{M} \int_0^t \mathbf{F}(\tau) d\tau$$



Models vs. Reality

$$x(t) = x(0) + \int_0^t v(\tau) d\tau$$

$$v(t) = v(0) + \frac{1}{m} \int_0^t F(\tau) d\tau.$$

The model



The target
(the thing
being
modeled).

In this example,
the *modeling*
framework is
calculus and
Newton's laws.

Fidelity is how
well the model
and its target
match



A Model

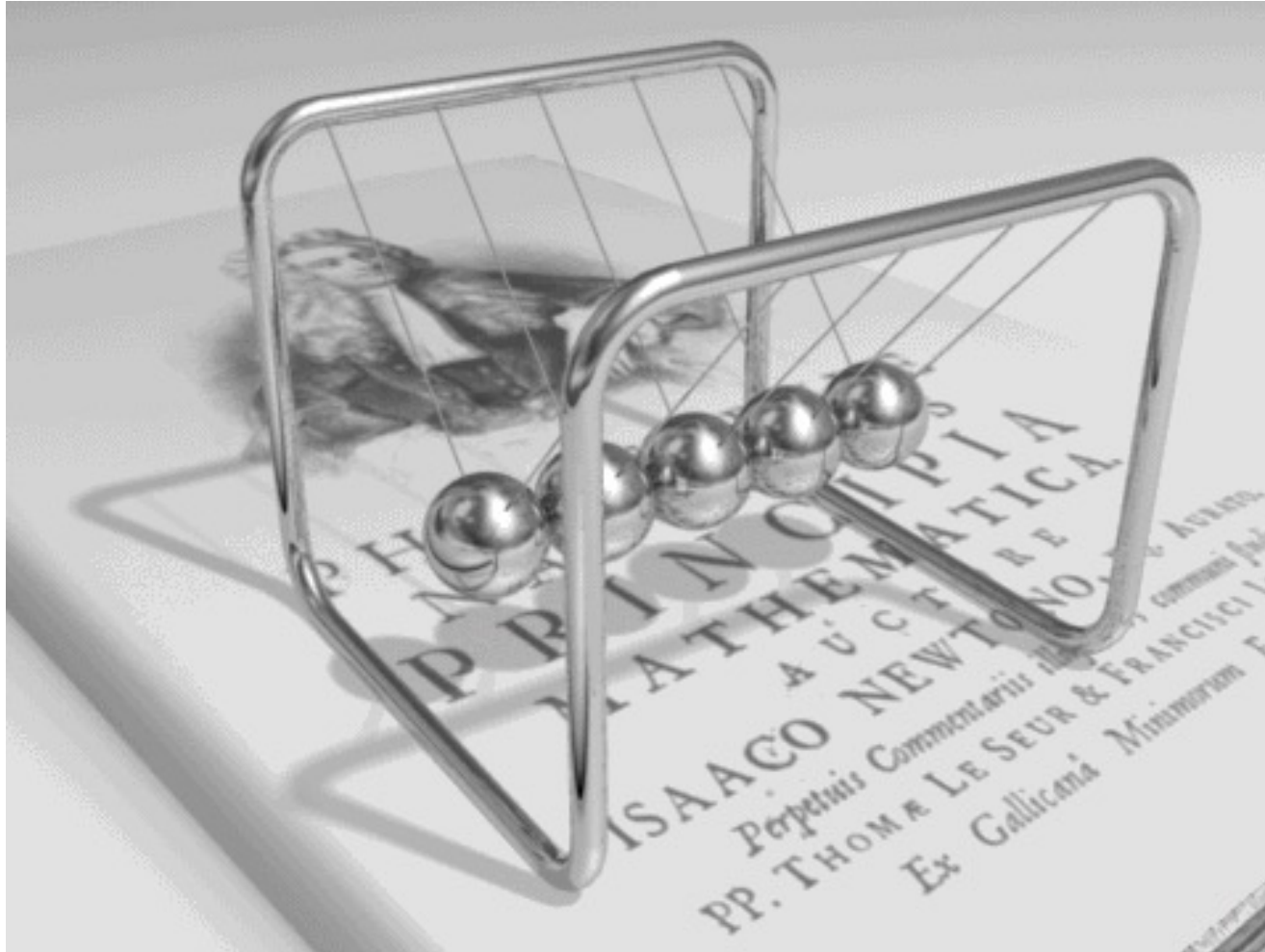
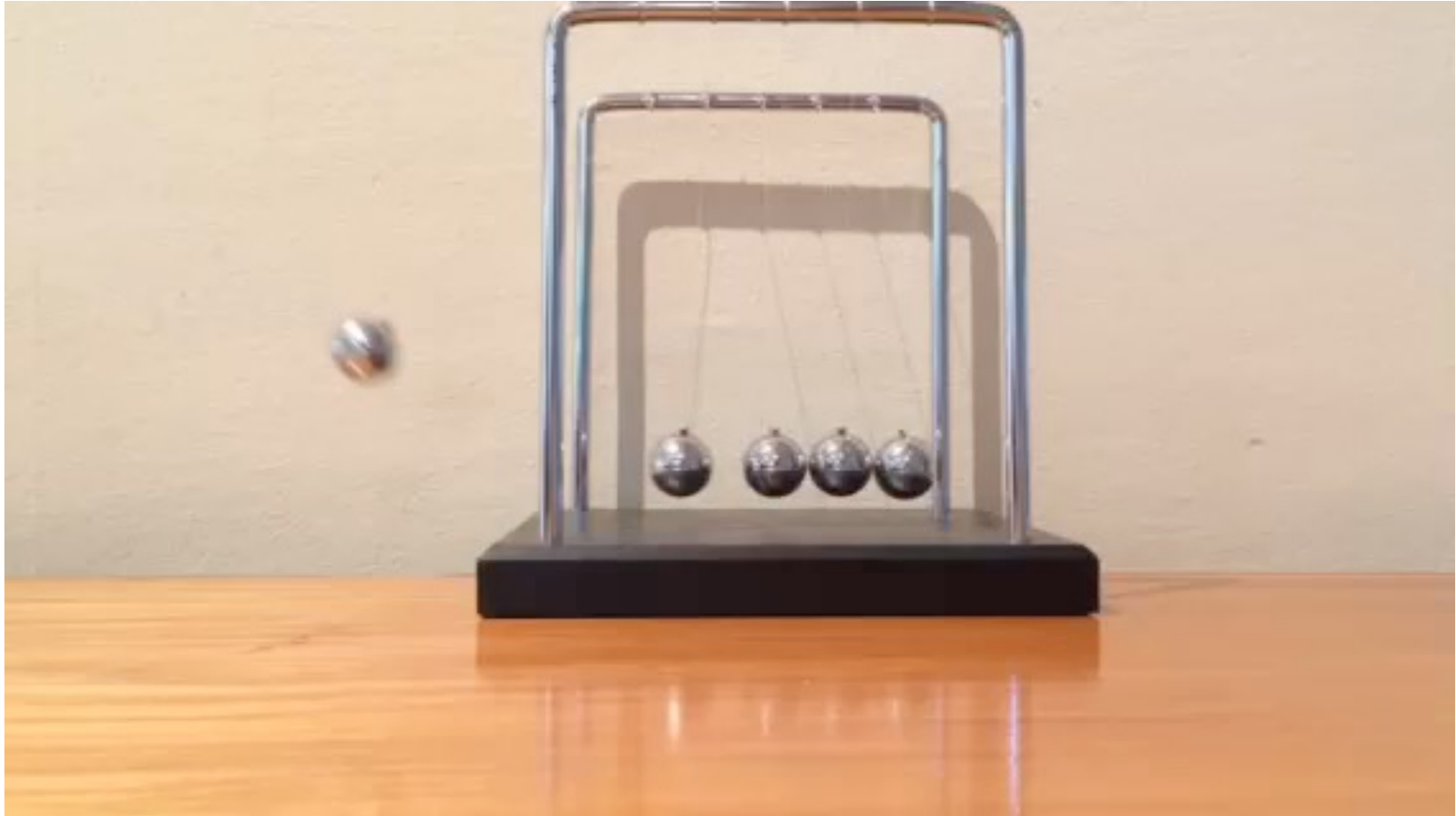


Image by Dominique Toussaint, GNU Free Documentation License, Version 1.2 or later.



A Physical Realization





The Value of Simulation

“Simulation is doomed to succeed.”

Could this statement be confusing engineering and scientific models?



Figure 1: Three scenes generated from a single ~20-line SCENIC scenario representing bumper-to-bumper traffic.

[Fremont, et al., Scenic: Language-Based Scene Generation, Arxiv.org, Sept. 2018]



Engineers often confuse the model with the thing being modeled

You will never strike oil by drilling through the map!

But this does not in any way diminish the value of a map!



Solomon Wolf Golomb

Lee, Berkeley





Recall Avionics

In “fly by wire” aircraft, computers control the plane, mediating pilot commands.



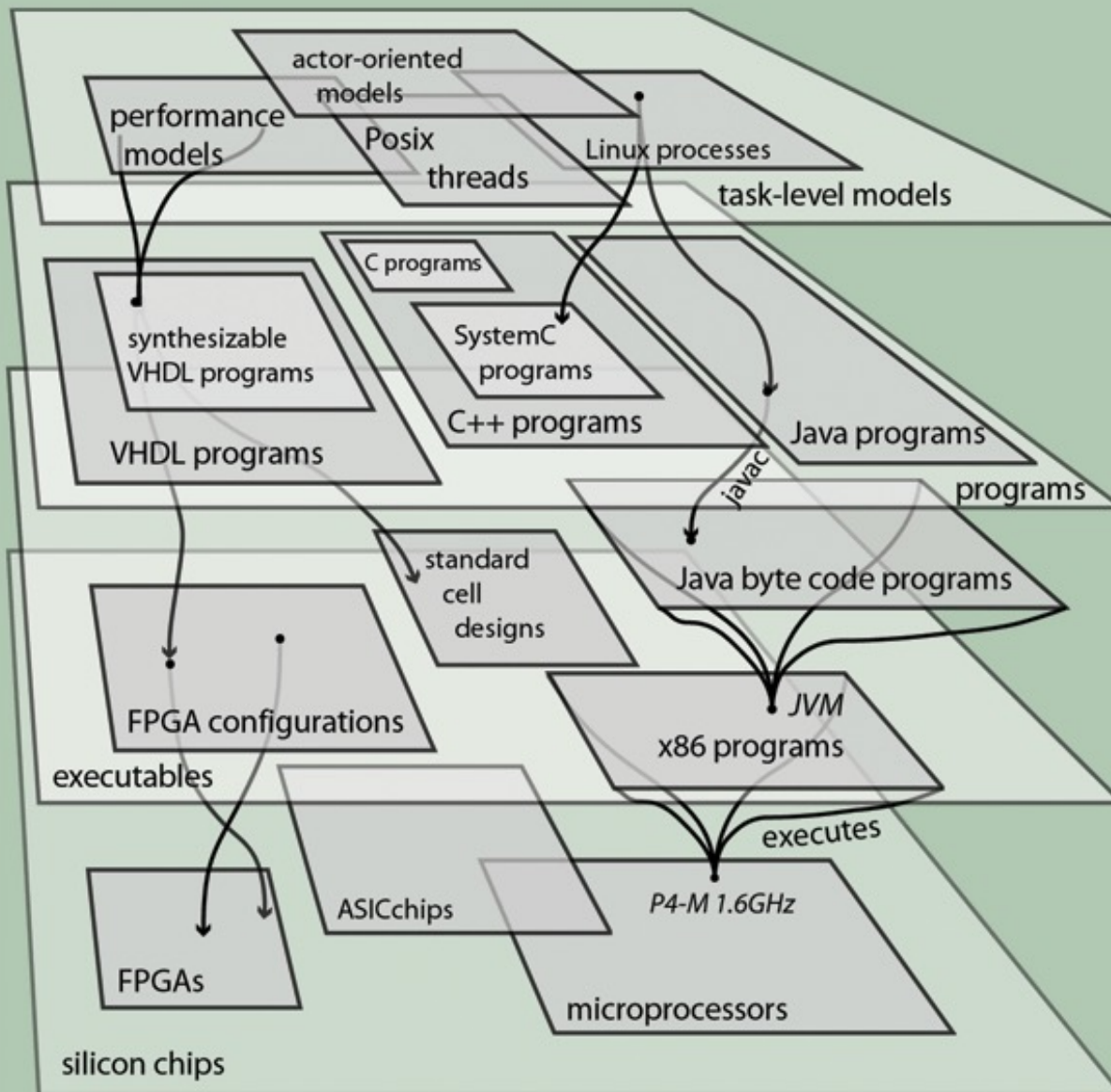
CCA 2.0

Boeing Dreamscape



Abstraction Layers

All of which are models except the bottom

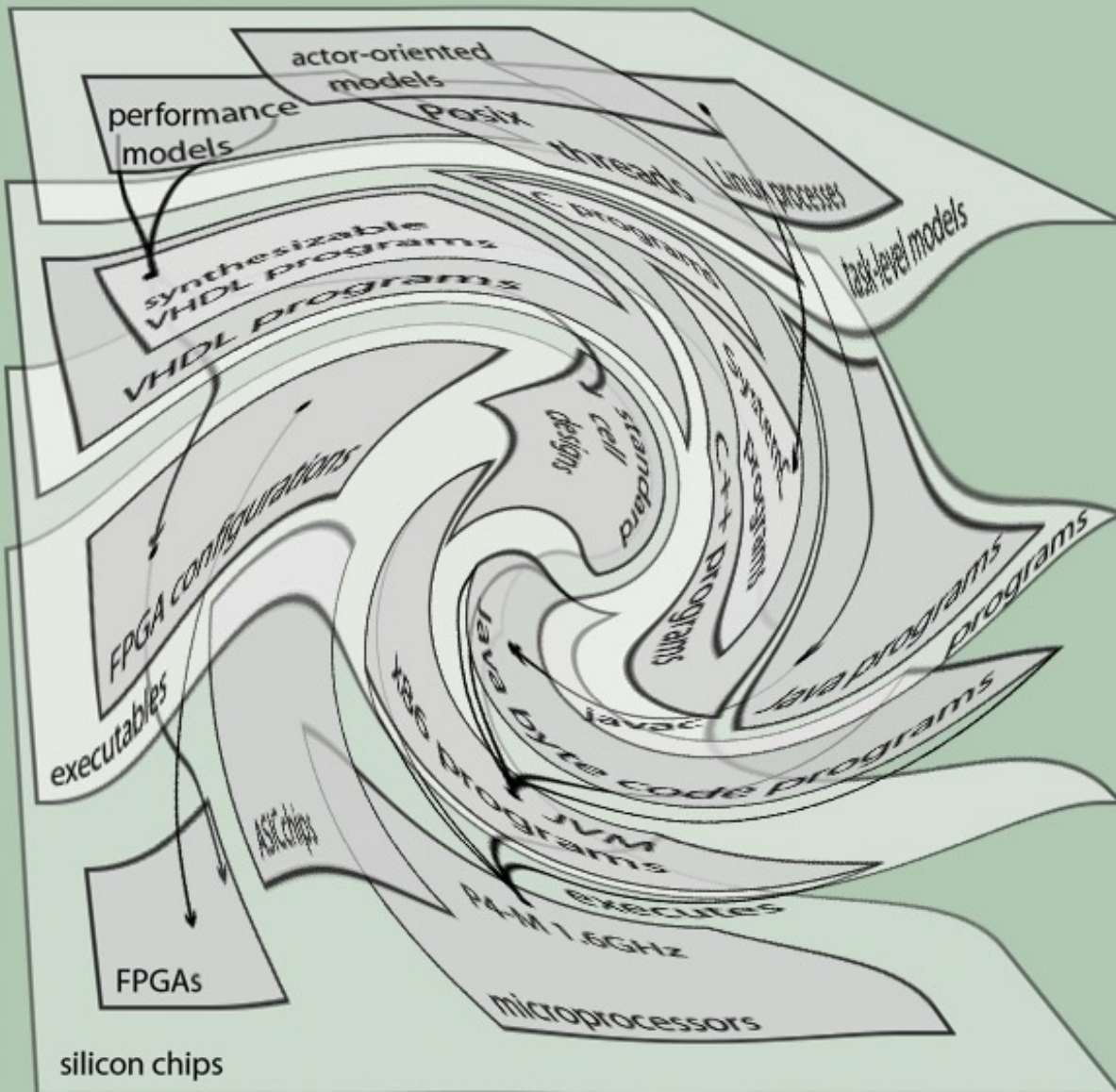


The purpose of an abstraction is to hide details of the implementation below and provide a platform for design from above.



Abstraction Layers

All of which are models except the bottom



Every abstraction layer has failed for the aircraft designer.

The design is the implementation.



Frozen Designs

Everything about the design, down to wire lengths and microprocessor chips, must be frozen at the time of design.



CCA 2.0

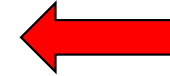
Boeing Dreamscape



Contrast with correctness criteria in software

We can safely assert that line 8 does not execute, regardless of the choice of microprocessor!

```
1 void foo(int32_t x) {
2     if (x > 1000) {
3         x = 1000;
4     }
5     if (x > 0) {
6         x = x + 1000;
7         if (x < 0) {
8             panic();
9         }
10    }
11 }
```



We can develop **absolute confidence** in the software, in that only a **hardware failure** is an excuse.

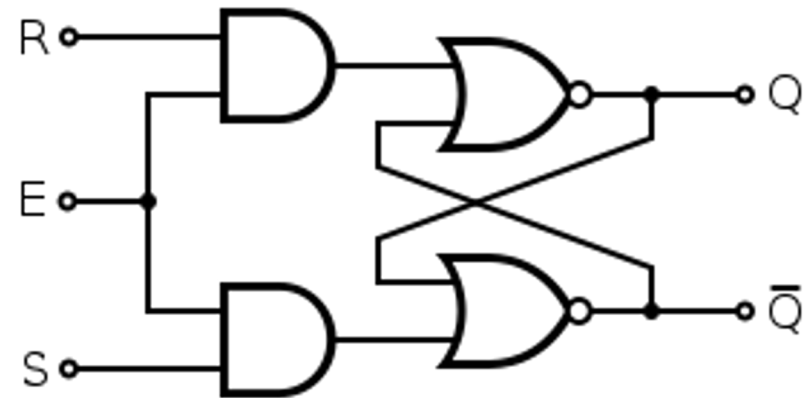
But not with regards to timing!!



Hardware is Good at Timing

Synchronous digital logic delivers precise, repeatable timing.

... but the overlaying software abstractions discard timing.



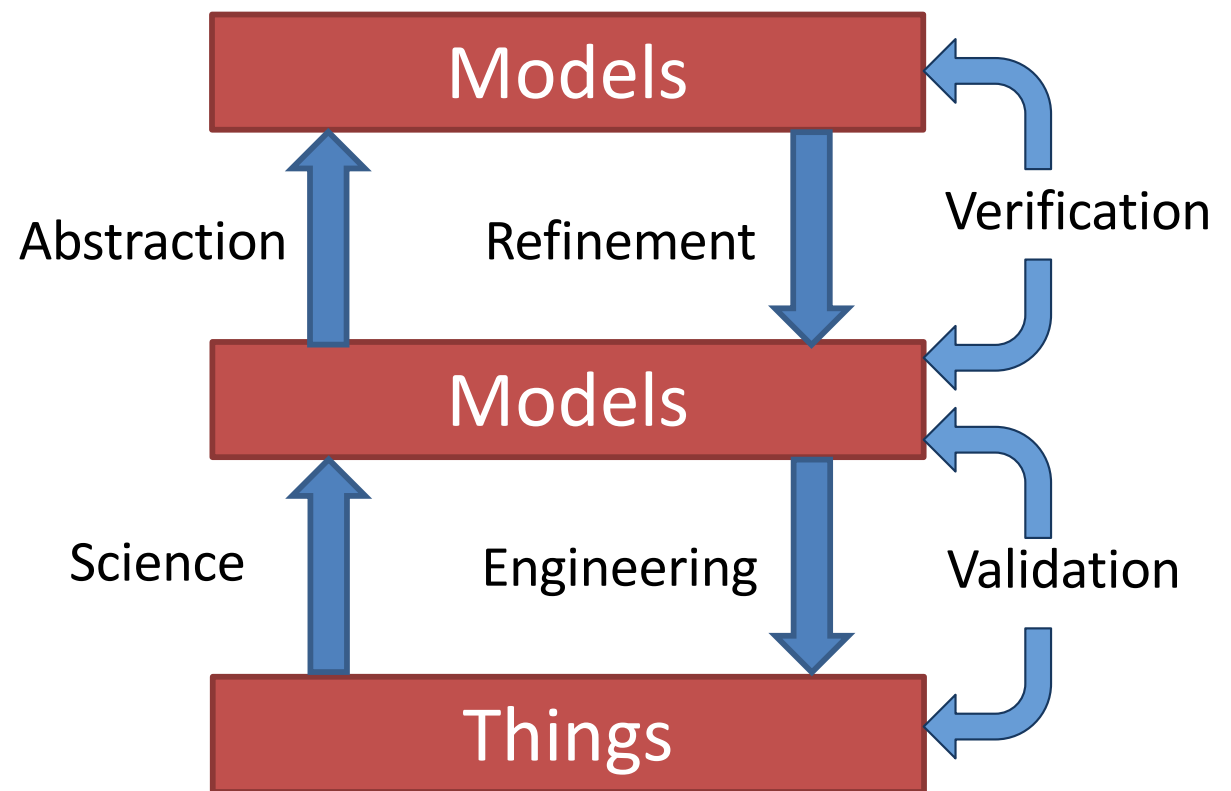
```
// Perform the convolution.
for (int i=0; i<10; i++) {
    x[i] = a[i]*b[j-i];
    // Notify listeners.
    notify(x[i]);
}
```



Verification and Validation

Per Boehm:

- Am I building the right product? (validation)
- Am I building the product right? (verification)



Formal methods can only address the Verification question.



References



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08 Apr 2021



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ACM Transactions on Embedded Computing Systems, Volume 20, Issue 5 • July 2021 • Article No.: 38, pp 1–34 • <https://doi.org/10.1145/3453652>

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